

LIMITED FARSIGHTEDNESS IN R&D NETWORK FORMATION

Ana Mauleon, Jose J. Sempere-Monerris,
Vincent Vannetelbosch

REPRINT | 3214

CORE

Voie du Roman Pays 34, L1.03.01

B-1348 Louvain-la-Neuve

Tel (32 10) 47 43 04

Email: lidam-library@uclouvain.be

<https://uclouvain.be/en/research-institutes/lidam/core/core-reprints.html>



Limited Farsightedness in R&D Network Formation

Ana Mauleon^{1,2} · Jose J. Sempere-Monerris^{2,3} · Vincent Vannetelbosch²

Accepted: 12 July 2022

© The Author(s), under exclusive licence to Springer Science+Business Media, LLC, part of Springer Nature 2022

Abstract

We adopt the horizon- K farsighted set of Herings, Mauleon and Vannetelbosch (2019) to study the R&D networks that will emerge in the long run when firms are neither myopic nor fully farsighted but have some limited degree of farsightedness. We find that a singleton set consisting of a pairwise stable network is a horizon- K farsighted set for any degree of farsightedness $K \geq 2$. That is, each R&D network consisting of two components of nearly equal size satisfies both horizon- K deterrence of external deviations and horizon- K external stability for $K \geq 2$. On the contrary, each R&D network consisting of two components with the largest one comprising three-quarters of firms, predicted when all firms are fully farsighted, violates horizon- K deterrence of external deviations. Thus, when firms are homogeneous in their degree of farsightedness, pairwise stable R&D networks consisting of two components of nearly equal size are robust to limited farsightedness.

Keywords Limited farsightedness · Stability · R&D Networks

JEL Classification C70 · L13 · L20

1 Introduction

R&D bilateral collaborations are agreements that allow firms to access to new knowledge providing them a competitive advantage. Hence, such collaborative agreements could induce

This article is part of the topical collection 'Group Formation and Farsightedness' edited by Francis Bloch, Ana Mauleon and Vincent Vannetelbosch.

✉ Vincent Vannetelbosch
vincent.vannetelbosch@uclouvain.be

Ana Mauleon
ana.mauleon@usaintlouis.be

Jose J. Sempere-Monerris
Jose.J.Sempere@uv.es

¹ CEREC, UCLouvain Saint-Louis, Brussels, Belgium

² CORE/LIDAM, UCLouvain, Louvain-la-Neuve, Belgium

³ Department of Economic Analysis and ERI-CES, University of Valencia, Valencia, Spain

competitors to look for their own R&D alliances. Since innovation enhances both growth and welfare, it is important to analyse the formation of bilateral R&D agreements between firms.

Different ways of characterizing which network structures are stable have been proposed in the literature depending on whether (and how far) agents anticipate that their action may also induce others to change the network relations they maintain.¹ On the one hand, pairwise stability (Jackson and Wolinsky [15]) involves fully myopic agents in the sense that they do not anticipate that others might react to their actions: agents are able to modify the network one link at a time, and choose to change the network if the resulting network implies higher payoffs for the deviating agents. On the other hand, a number of solution concepts involve perfectly farsighted agents: agents fully anticipate the complete sequence of reactions that results from their own actions in the network.² However, Kirchsteiger et al. [18] provide experimental evidence suggesting that subjects are consistent with an intermediate degree of farsightedness: agents only anticipate a limited number of reactions by the other agents to the actions they take themselves.

Similarly to Goyal and Moraga-Gonzalez [9], Goyal and Joshi [8], and Mauleon et al. [21], we consider a n -firm industry, where initially firms produce an homogeneous good at a given equal and constant marginal cost. Each firm is able to reduce its marginal cost by forming a R&D collaborative link with another competitor. The marginal cost of production reduction for one firm is proportional to the number of firms it is connected to. When a link is formed between two firms that are not connected, all firms connected to those two firms benefit from that link, while others become less competitive. The collection of R&D collaborative links define the R&D network which in turn determines the marginal cost profile for the n firms. Once the R&D network is formed, firms compete in quantities.

When all firms are myopic, Mauleon et al. [21] show that a R&D network is pairwise stable if and only if it consists of two "symmetric" components of nearly equal size (close to $n/2 + 1$ and $n/2 - 1$). In contrast to myopia, once all firms are fully farsighted, farsighted stability leads to R&D networks consisting of two "asymmetric" components of different sizes (close to $3n/4$ and $n/4$). Recently, Mauleon et al. [23] allows for a mixed population of firms: myopic firms interacting together with farsighted firms.³ When the majority of firms are myopic, the myopic-farsighted stable set consists of R&D networks having either two "asymmetric" components of different sizes (close to $3n/4$ and $n/4$) with farsighted firms mostly occupying key positions in the largest component, or two "symmetric" components of nearly equal size (close to $n/2 + 1$ and $n/2 - 1$) with the largest component having only myopic firms. However, when the majority of firms becomes farsighted, networks having two components of nearly equal size are now unstable. The myopic-farsighted stable set consists only of the networks having two components of different sizes.⁴

¹ Mauleon and Vannetelbosch [25] provide a comprehensive overview of the solution concepts for solving network formation games.

² Various approaches to farsightedness can be found in Chwe [6], Xue [32], Herings et al. [10, 11], Dutta et al. [7], Page et al. [27], Page and Wooders [28], Mauleon et al. [26], and Ray and Vohra [30].

³ Herings, Mauleon and Vannetelbosch (2020) define the myopic-farsighted stable set for two-sided matching problems, while Luo et al. [19] investigate the myopic-farsighted stable set in general network formation problems.

⁴ Petrakis and Tskas [29] investigate the effect of potential entry on the formation and stability of R&D networks when firms are farsighted, while Roketskiy [31] studies collaboration between farsighted firms competing in a tournament and finds that stable networks consist of two asymmetric mutually disconnected complete components.

Which are the R&D networks that will emerge in the long run when firms have a limited degree of farsightedness? We adopt the horizon- K farsighted set of Herings et al. [12] to answer this question. The concept encompasses both the pairwise farsightedly stable set and the pairwise myopically stable set introduced by Herings et al. [11]. A set of networks G_K is a horizon- K farsighted set if three conditions are satisfied. First, deviations outside the set should be horizon- K deterred. Second, horizon- K external stability is required. That is, from any network outside of G_K there is a sequence of farsighted improving paths of length smaller than or equal to K leading to some network in G_K . Third, a minimality condition is required. That is, there is no proper subset of G_K satisfying the first two conditions.

In this paper, we show that a singleton set consisting of a pairwise stable network is a horizon- K farsighted set for any degree of farsightedness greater than or equal to 2. That is, each R&D network having two components of nearly equal size satisfies both horizon- K deterrence of external deviations and horizon- K external stability for $K \geq 2$. On the contrary, we find that each R&D network having two "asymmetric" components with the largest one comprising three-quarters of firms violates horizon- K deterrence of external deviations. Hence, R&D networks having two components of nearly equal size are not only stable when the majority of firms are myopic but also when all firms are limitedly farsighted. To sum up, when firms are homogeneous in their degree of farsightedness, pairwise stable R&D networks consisting of two "symmetric" components of nearly equal size are robust to limited farsightedness.

The formation of research collaborations is also studied using the group formation approach where collaborations are modelled in terms of a coalition structure which is a partition of the set of firms (i.e. each firm can only belong to one coalition). Bloch [2] proposes a sequential game for forming associations of firms. In equilibrium, firms form two asymmetric associations, with the largest one comprising roughly three-quarters of industry members. So, the sizes of the two associations coincide with those Mauleon et al. [21] obtain when firms are farsighted. In fact, by assuming that all connected firms in a network fully benefit from a new link, Mauleon et al. [21] recover the assumption in Bloch [2] where the benefits from cooperation increase linearly in the size of the association. The network approach differs from the group formation approach by focusing on bilateral relationships and allowing for a richer class of collaborations. It also differs in the decision-making for establishing R&D collaborations. Mutual consent is needed for forming a new link between two firms,⁵ whereas the consent of all members of the association is required when a firm joins the association.⁶ Both approaches lead to similar conclusions only if firms are farsighted and anticipate the reactions of other firms to the decisions they take.⁷

The paper is organized as follows: In Sect. 2, we introduce some notation and basic properties of R&D networks. In Sect. 3, we define the notion of a horizon- K farsighted set. In Sect. 4, we identify the horizon- K farsighted set of R&D networks. Finally, in Sect. 5 we conclude.

⁵ Caulier et al. [4, 5] propose the concept of contractual stability to predict the stable networks when the consent of coalition partners is needed for adding or deleting links.

⁶ An exception is the open membership game. Yi [33] finds that only the grand coalition is stable, but this result is not always robust when firms are not identical (see Yi and Shin [34]). See Bloch (2005) for a survey on group and network formation in industrial organization.

⁷ Mauleon et al. [22] show that if firms are myopic (Δ -stability) there is no stable association structure for $n \geq 8$.

2 R&D Networks

We consider a two-stage game in a setting with n competing identical firms that produce some homogenous good. In the first stage, firms decide the bilateral R&D collaborations they establish to maximize their respective profits. Let $N = \{1, 2, \dots, n\}$ be the set of firms.⁸ A network g of R&D collaborations is a list of which pairs of firms are linked to each other and $ij \in g$ indicates that i and j are linked under g . The complete network on the set of firms $S \subseteq N$ is denoted by g^S and is equal to the set of all subsets of S of size 2. The empty network is denoted by g^\emptyset . The set of all possible networks on N is denoted by \mathcal{G} and consists of all subsets of g^N . The cardinality of \mathcal{G} is denoted by $n' = 2^{n(n-1)/2}$.

The network obtained by adding link ij to an existing network g is denoted $g + ij$ and the network that results from deleting link ij from an existing network g is denoted $g - ij$. Let $N(g) = \{i \mid \text{there is } j \text{ such that } ij \in g\}$ be the set of firms who have at least one link in the network g . A path in a network g between i and j is a sequence of firms i_1, \dots, i_K such that $i_k i_{k+1} \in g$ for each $k \in \{1, \dots, K-1\}$ with $i_1 = i$ and $i_K = j$. A network g is connected if for all $i \in N$ and $j \in N \setminus \{i\}$, there exists a path in g connecting i and j . A non-empty network $h \subseteq g$ is a component of g , if for all $i \in N(h)$ and $j \in N(h) \setminus \{i\}$, there exists a path in h connecting i and j , and for any $i \in N(h)$ and $j \in N(g) \setminus N(h)$, $ij \notin g$. The set of components of g is denoted by $C(g)$. A component h of g is minimally connected if h has $\#N(h) - 1$ links.⁹ Knowing the components of a network, we can partition the firms into coalitions within which firms are connected. Let $\mathcal{P}(g)$ denote the partition of N into components and singletons induced by the network g . That is, $S \in \mathcal{P}(g)$ if and only if either there exists $h \in C(g)$ such that $S = N(h)$ or there exists $i \notin N(g)$ such that $S = \{i\}$. We denote by $S(i)$ the coalition $S \in \mathcal{P}(g)$ such that $i \in S$. We denote by $\bar{S}(g)$ the largest coalition of g . That is, $\bar{S}(g) \in \mathcal{P}(g)$ is such that $\#\bar{S}(g) \geq \#S(g)$ for all $S(g) \in \mathcal{P}(g)$.

R&D collaborations reduce marginal costs of production as in Mauleon et al. [21].¹⁰ Each firm benefits fully from its own R&D and from the R&D done by the firms it is connected to.¹¹ Given a network g , the marginal cost for firm i is given by

$$c_i(g) = c_0 - \#S(i)$$

where c_0 is a firm's initial marginal cost and $\#S(i)$ is the number of firms in the component of firm i . Since knowledge flows perfectly throughout the component, firms bear an infinitesimally small cost for maintaining redundant (or superfluous) links.¹²

In the second stage, firms compete in quantities in the oligopolistic market, taking as given the costs of production. Let $p(Q) = a - Q$ be the linear inverse demand function with $a > 0$ and $Q = \sum_{i \in N} q_i$. For any given R&D network g , one can easily show that

⁸ Throughout the paper, we use the notation \subseteq for weak inclusion and \subset for strict inclusion. Finally, $\#$ will refer to the notion of cardinality.

⁹ In a minimally connected component, every pair of firms belonging to the component is connected by exactly one path.

¹⁰ Firms collaborate in R&D but do not cooperate on R&D effort choices. For a general background on R&D cooperation in oligopoly the reader is directed to Amir [1], Kamien et al. [16] and Katz [17], among others.

¹¹ In Mauleon et al. [20], the reduction in marginal costs depends on the total number of connected firms, but decreases with the distance. In Goyal and Joshi [8], the reduction in marginal costs only depends on the number of direct links. In Goyal and Moraga-Gonzalez [9], firms also benefit imperfectly from public spillovers, i.e. the research done by firms to whom they are not connected.

¹² In a network g , a component $h \in C(g)$ has no redundant links if and only if h is minimally connected. It reflects the idea that firms avoid wasting resources. When a firm deletes a redundant or superfluous link, it remains connected to the same set of firms and so still benefits from the same reduction in marginal costs.

there exists a unique Cournot equilibrium on the market, and that each firm's profit $\pi_i(g)$ is a monotonically increasing function of the following valuation or payoff function,¹³

$$\Pi_i(g) = a - c_0 + (n + 1)\#S(i) - \sum_{S \in \mathcal{P}(g)} (\#S)^2. \quad (1)$$

In fact, $\Pi_i(g) = (n + 1)\sqrt{\pi_i(g)} = (n + 1)q_i(g)$ where $q_i(g)$ is the equilibrium output. We focus our analysis on the case where there are at least eight firms.¹⁴ Notice that R&D networks connecting all firms are the ones that maximize social welfare, i.e. the sum of the profits and the consumer surplus. As in Bloch [2], for $n \geq 8$, this payoff function in (1) satisfies some general properties (**P1-P6**) that are useful for characterizing the networks that will emerge in the long run. **P1** states that in any R&D network, linking two components decreases the payoffs of the firms that do not belong to those components. **P2** states that in any R&D network, firms belonging to bigger components obtain greater payoffs. **P3** states that in any R&D network, firms belonging to the two smallest components obtain greater payoffs by bridging the two components. **P4** states that firms prefer to belong to the largest component of a R&D network with one component encompassing all firms except one rather than to belong to the largest component of a R&D network with two nearly symmetric coalitions. **P5** states that firms prefer to belong to the single component of a R&D network that includes less firms rather than to belong to the single component of a R&D network that includes more firms, provided that more than half of the firms belong to the single component. **P6** states that isolating a single firm from the largest component in a R&D network with two components is profitable for the rest of the firms belonging to that component. Formally, the payoff function satisfies the following six properties.¹⁵

- P1** In any R&D network g , we have that $\Pi_i(g + jk) < \Pi_i(g)$ if $S(i) \neq S(j) \neq S(k)$ and $S(i), S(j), S(k) \in \mathcal{P}(g)$.
- P2** In any R&D network g , we have that $\Pi_i(g) > \Pi_j(g)$ if and only if $\#S(i) > \#S(j)$.
- P3** In any R&D network g with $\#\mathcal{P}(g) \geq 3$, we have that $\Pi_i(g + ij) > \Pi_i(g)$ and $\Pi_j(g + ij) > \Pi_j(g)$ if $S(i) \neq S(j)$, $S(i), S(j) \in \mathcal{P}(g)$, and $\#S \geq \max\{\#S(i), \#S(j)\}$ for all $S \in \mathcal{P}(g)$, $S \neq S(i), S(j)$.
- P4** In any R&D networks g, g' such that $\#\mathcal{P}(g) = \#\mathcal{P}(g') = 2$ with $\#\bar{S}(g) = n - 1$ and $\bar{S}(g') = \lceil (n + 1)/2 \rceil$, we have that $\Pi_i(g) > \Pi_i(g')$ if $i \in \bar{S}(g)$ and $i \in \bar{S}(g')$.¹⁶
- P5** In any R&D networks g, g' such that $\#C(g) = \#C(g') = 1$ and $\#\bar{S}(g') > \#\bar{S}(g) > \lceil n/2 \rceil$, we have $\Pi_i(g) > \Pi_i(g')$ if $i \in \bar{S}(g)$ and $i \in \bar{S}(g')$.
- P6** In any R&D network g such that $\#\mathcal{P}(g) = 2$ and $\#\bar{S}(g) > \lceil (n + 1)/2 \rceil$, we have $\Pi_i(g - jk) > \Pi_i(g)$ if $\#\mathcal{P}(g - jk) = 3$, $i \in \bar{S}(g - jk)$ and $j, k \in \bar{S}(g)$.

Throughout the paper we illustrate our main results by means of an example with eight firms. In Table 1, we give the firms' equilibrium payoffs in several networks for $a - c_0 = 42$.

¹³ Excluding infinitesimally small costs for maintaining redundant links.

¹⁴ Petrakis and Tsakas [29] consider a set-up where R&D effort is costly and endogenous but in an environment with only three farsighted firms that could differ in the initial marginal cost and the levels of substitutability between products.

¹⁵ **P1-P6** can also be satisfied by the equilibrium payoff functions in the case of nonlinear inverse demand functions. For instance, a constant-elasticity inverse demand function, $p(Q) = aQ^{-t}$ with $0 < t < 1$, and an iso-elastic inverse demand function, $p(Q) = a - Q^\alpha$ with $0 < \alpha$, do satisfy the properties **P1-P6** under some conditions. However, it could happen that the pairwise stable networks under the linear demand function are now defeated by some adjacent network.

¹⁶ $\lceil x \rceil$ is the function that takes as input a real number x and gives as output the lowest integer greater than or equal to x .

Table 1 Payoffs for the 8-firm case with $a - c_0 = 42$

| | | | | | |
|-----------|----------|--------------|--------------|------------------|------------------|
| Networks: | {8} | {5, 3} | {5, 2, 1} | {3, 3, 2} | {3, 3, 1, 1} |
| Payoffs: | (50) | (53, 35) | (57, 30, 21) | (47, 47, 38) | (49, 49, 31, 31) |
| Networks: | {7, 1} | {4, 4} | {4, 3, 1} | {5, 1, 1, 1} | {3, 2, 2, 1} |
| Payoffs: | (55, 1) | (46, 46) | (52, 43, 25) | (59, 23, 23, 23) | (51, 42, 42, 33) |
| Networks: | {6, 2} | {6, 1, 1} | {4, 2, 2} | {4, 2, 1, 1} | {2, 2, 2, 2} |
| Payoffs: | (56, 20) | (58, 13, 13) | (54, 36, 36) | (56, 38, 29, 29) | (44, 44, 44, 44) |

We make a slight abuse of notation. For instance, {5, 2, 1} should be interpreted as a network, composed of three "components" of size 5, 2 and 1, that can be formed by eight firms. Firms in the component of size 5 obtain a payoff of 57, firms in the component of size 2 obtain a payoff of 30, and the (isolated) firm in the "component" of size 1 obtains a payoff of 21.

3 Horizon- K Farsighted Set

We propose the notion of horizon- K farsighted set introduced by Heringset al. [12] to determine the R&D networks that emerge in the long run when firms are neither fully myopic nor completely farsighted but have some limited degree of farsightedness.

A farsighted improving path of length $K \geq 1$ from a network g to a network g' is a finite sequence of networks g_0, \dots, g_K with $g_0 = g$ and $g_K = g'$ such that for any $k \in \{1, \dots, K - 1\}$ either (i) $g_{k+1} = g_k - ij$ for some ij such that $\Pi_i(g_K) > \Pi_i(g_k)$ or $\Pi_j(g_K) > \Pi_j(g_k)$, or (ii) $g_{k+1} = g_k + ij$ for some ij such that $\Pi_i(g_K) > \Pi_i(g_k)$ and $\Pi_j(g_K) > \Pi_j(g_k)$. If there exists a farsighted improving path of length K from g to g' , then we write $g \rightarrow_K g'$. For a given network g and some $K' \geq 1$, let $\phi_{K'}(g)$ be the set of networks that can be reached from g by a farsighted improving path of length $K \leq K'$. That is, $\phi_{K'}(g) = \{g' \in \mathcal{G} \mid \exists K \leq K' \text{ such that } g \rightarrow_K g'\}$. Let $\phi_\infty(g) = \{g' \in \mathcal{G} \mid \exists K \in \mathbb{N} \text{ such that } g \rightarrow_K g'\}$ denote the set of networks that can be reached from g by some farsighted improving path. Lemma 1 in Herings et. al [12] shows that for every $K \geq 1$, for every $g \in \mathcal{G}$, it holds that $\phi_K(g) \subseteq \phi_{K+1}(g)$, and that for $K \geq n' - 1$, for every $g \in \mathcal{G}$, it holds that $\phi_K(g) = \phi_{K+1}(g) = \phi_\infty(g)$.

A network g' is *adjacent* to g if either $g' = g + ij$ or $g' = g - ij$ for some ij . A network g' *defeats* g either if $g' = g - ij$ and $\Pi_i(g') > \Pi_i(g)$ or $\Pi_j(g') > \Pi_j(g)$, or if $g' = g + ij$ with $\Pi_i(g') > \Pi_i(g)$ and $\Pi_j(g') > \Pi_j(g)$. A network is *pairwise stable* (Jackson and Wolinsky [15]) if and only if it is not defeated by another network. Notice that $g' \in \phi_1(g)$ if and only if g' defeats g . We can therefore define the pairwise stable networks P_1 as those $g \in \mathcal{G}$ for which $\phi_1(g) = \emptyset$. For $K \geq 1$, let $P_K = \{g \in \mathcal{G} \mid \phi_K(g) = \emptyset\}$ denote the set of horizon- K pairwise stable networks.

A refinement of pairwise stability is obtained when we require the network g to defeat every other adjacent network, so $g \in \phi_1(g')$ for every network g' adjacent to g . We call such a network g *pairwise dominant*. For $K \geq 1$, a network $g \in \mathcal{G}$ is horizon- K pairwise dominant if for every g' adjacent to g it holds that $g \in \phi_K(g')$. The set of horizon- K pairwise dominant networks is denoted by D_K .

The set $\phi_K^2(g) = \phi_K(\phi_K(g)) = \{g'' \in \mathcal{G} \mid \exists g' \in \phi_K(g) \text{ such that } g'' \in \phi_K(g')\}$ consists of those networks that can be reached by a composition of two farsighted improving paths of length at most K from g . For $m \in \mathbb{N}$, let $\phi_K^m(g)$ be the networks that can be reached from g by means of m compositions of farsighted improving paths of length at most K . Let ϕ_K^∞ denote

the set of networks that can be reached from g by means of any number of compositions of farsighted improving paths of length at most K . Lemma 2 in Herings et al. [12] shows that for every $K \geq 1$, for every $g \in \mathcal{G}$, it holds that $\phi_K^\infty(g) \subseteq \phi_{K+1}^\infty(g)$, and that for $K \geq n' - 1$, for every $g \in \mathcal{G}$, it holds that $\phi_K^\infty(g) = \phi_{K+1}^\infty(g) = \phi_\infty^\infty(g)$.

The notion of a horizon- K farsighted set is based on two main requirements: horizon- K deterrence of external deviations and horizon- K external stability. A set of networks G satisfies *horizon- K deterrence of external deviations* if all possible deviations from any network $g \in G$ to a network outside G are deterred by a threat of ending worse off or equally well off.¹⁷

Definition 1 (Herings et al. [12]) *For $K \geq 1$, a set of networks $G \subseteq \mathcal{G}$ satisfies horizon- K deterrence of external deviations if for every $g \in G$,*

- (a) $\forall ij \notin g$ such that $g+ij \notin G, \exists g' \in [\phi_{K-2}(g+ij) \cap G] \cup [\phi_{K-1}(g+ij) \setminus \phi_{K-2}(g+ij)]$ such that $\Pi_i(g') \leq \Pi_i(g)$ or $\Pi_j(g') \leq \Pi_j(g)$,
- (b) $\forall ij \in g$ such that $g-ij \notin G, \exists g', g'' \in [\phi_{K-2}(g-ij) \cap G] \cup [\phi_{K-1}(g-ij) \setminus \phi_{K-2}(g-ij)]$ such that $\Pi_i(g') \leq \Pi_i(g)$ and $\Pi_j(g'') \leq \Pi_j(g)$.

Condition (a) in Definition 1 captures that adding a link ij to a network $g \in G$ that leads to a network $g+ij$ outside of G , is deterred by the threat of ending in g' . Here g' is such that either there is a farsighted improving path of length smaller than or equal to $K-2$ from $g+ij$ to g' and g' belongs to G or there is a farsighted improving path of length equal to $K-1$ from $g+ij$ to g' and there is no farsighted improving path from $g+ij$ to g' of smaller length. Condition (b) is a similar requirement, but then for the case where a link is severed.¹⁸

A set of networks G satisfies *horizon- K external stability* if from any network outside of G there is a sequence of farsighted improving paths of length smaller than or equal to K leading to some network in G .

Definition 2 (Herings et al. [12]) *For $K \geq 1$, a set of networks $G \subseteq \mathcal{G}$ satisfies horizon- K external stability if for every $g' \in \mathcal{G} \setminus G, \phi_K^\infty(g') \cap G \neq \emptyset$.*

This requirement implies that if we allow players with a degree of farsightedness equal to K to successively create or delete links, they will ultimately reach the set G irrespective of the initial network.

Definition 3 (Herings et al. [12]) *For $K \geq 1$, a set of networks $G_K \subseteq \mathcal{G}$ is a horizon- K farsighted set if it is a minimal set satisfying horizon- K deterrence of external deviations and horizon- K external stability.*

Herings et al. [12] prove that a horizon- K farsighted set of networks exists. For $K = 1$, Theorem 3 in Herings et al. [12] show that there is a unique horizon-1 farsighted set consisting of all networks that belong to a closed cycle.¹⁹ This result does not carry over to higher levels of K .

¹⁷ We use the notational convention that $\phi_{-1}(g) = \emptyset$ for every $g \in \mathcal{G}$.

¹⁸ Since the degree of farsightedness of players is equal to K , Herings et al. [12] distinguish farsighted improving paths of length less than or equal to $K-2$ after a deviation from g to $g+ij$ and farsighted improving paths of length equal to $K-1$. In the former case, the reasoning capacity of the players is not yet reached, and the threat of ending in g' is only credible if it belongs to the set G . In the latter case, the only way to reach g' from g requires K steps of reasoning or even more; one step in the deviation to $g+ij$ and at least $K-1$ additional steps in any farsighted improving path from $g+ij$ to g' . Since this exhausts the reasoning capacity of the players, the threat of ending in g' is credible, irrespective of whether it belongs to G or not.

¹⁹ Similarly to Jackson and Watts [15], a set of networks C is a cycle if for any $g' \in C$ and $g \in C \setminus \{g'\}$, $g' \in \phi_1^\infty(g)$. A cycle C is a closed cycle if $\phi_1^\infty(C) = C$. For every pairwise stable network $g \in P_1$, the set $\{g\}$ is a closed cycle.

As shown by Herings et al. [12], the collection of horizon- K farsighted sets is independent of K when $K \geq n' + 1$. Moreover, for every pairwise farsightedly stable set G_∞ defined by Herings et al. [12], there is a set $G' \subseteq G_\infty$ such that G' is a horizon- $(n' + 1)$ farsighted set.²⁰

4 Horizon- K Farsighted Set of R&D Networks

Mauleon et al. [21] show that the set $G^{1/2} = \{g \in \mathcal{G} \mid C(g) = (h_1, h_2), h_1 \text{ and } h_2 \text{ are minimally connected, } N(h_1) \cup N(h_2) = N, \#N(h_1) = \lceil (n + 1)/2 \rceil\}$ is the set of pairwise stable networks. That is, a network $g \in \mathcal{G}$ is pairwise stable if and only if g consists of two minimally connected components with the cardinality of the largest component equal to $\lceil (n + 1)/2 \rceil$. Thus, in the case all firms are myopic, stability leads to R&D networks consisting of nearly symmetric components. However, in the case all firms are farsighted, Mauleon et al. [21] show that the set $G^{3/4}$ is a pairwise farsightedly stable set, where $G^{3/4} = \{g \in \mathcal{G} \mid C(g) = (h_1, h_2), h_1 \text{ and } h_2 \text{ are minimally connected, } N(h_1) \cup N(h_2) = N, \text{ and } \#N(h_1) = \lfloor (3n + 1)/4 \rfloor\}$ is the set of all R&D networks that consist of two minimally connected components of different size close to $3n/4$ and $n/4$, respectively.²¹

Which R&D networks are stable when firms are neither myopic nor fully farsighted but rather have a limited degree of farsightedness?

We say that firm i is a *leaf node* in network g if it only has a single link, i.e. $\#N_i(g) = 1$. If a firm that is a leaf node deletes its single link, it becomes an isolated firm with no R&D collaboration.

We now provide results that turn to be useful for characterizing the set of horizon-1 pairwise dominant networks, the horizon-1 farsighted set and the horizon- K farsighted sets for $K \geq 2$. Lemma 1 tells us that, from any network where some component is not minimally connected there is a sequence of farsighted improving paths of length 1 leading to some network where this component is now minimally connected and all firms belong to the same component or are isolated as in the initial network. Lemma 1 follows from the incentives for deleting superfluous links in components that are not minimally connected.

Lemma 1 *Take any network $g \in \mathcal{G}$ such that some component $h \in C(g)$ is not minimally connected. It holds that there exists some network $g' \in \phi_1^\infty(g)$ such that every component $h \in C(g')$ is minimally connected and $\mathcal{P}(g) = \mathcal{P}(g')$.*

Lemma 2 tells us that, from any network with at least three components and/or isolated firms, there is a sequence of farsighted improving paths of length 1 leading to some network with two components. Lemma 2 follows from P3 and the incentives for adding a link between two firms that belong to the two smallest coalitions.

Lemma 2 *Take any network $g \in \mathcal{G}$ such that every component $h \in C(g)$ is minimally connected and $\#\mathcal{P}(g) \geq 3$. It holds that there exists some network $g' \in \phi_1^\infty(g)$ such that every component $h \in C(g')$ is minimally connected and $\#\mathcal{P}(g') = \#C(g') = 2$.*

Lemma 3 tells us that, from any minimally connected network with a single component connecting all firms, there is a sequence of farsighted improving paths of length 1

²⁰ Herings et al. [11] define a pairwise farsightedly stable set as a set G_∞ of networks satisfying horizon- ∞ deterrence of external deviations and minimality, but with horizon- ∞ external stability replaced by the requirement that for every $g' \in \mathcal{G} \setminus G_\infty, \phi_\infty(g') \cap G_\infty \neq \emptyset$.

²¹ $\lfloor x \rfloor$ is the function that takes as input a real number x and gives as output the greatest integer less than or equal to x .

towards some network belonging to the set of pairwise stable networks, $G^{1/2}$. Starting from a minimally connected network g such that $\mathcal{P}(g) = \{N\}$ we build a sequence of farsighted improving paths of length 1 towards some network $g' \in G^{1/2}$ as follows. First, at each step a firm that is a leaf is isolated until we reach a network $g_1 \subset g$ with $\#\bar{S}(g_1) = \lceil (n+1)/2 \rceil$ and $n - \lceil (n+1)/2 \rceil$ isolated firms. Given **P5**, firms belonging to the largest component have incentives to isolate a firm that is a leaf. Next, at each step isolated firms have incentives to add links one by one between them to form a minimally connected component leading to some g' such that $\mathcal{P}(g') = \{S_1, S_2\}$ with $\#S_1 = \lceil (n+1)/2 \rceil$ and $\#S_2 = n - \lceil (n+1)/2 \rceil$.

Lemma 3 *Take any minimally connected network $g \in \mathcal{G}$ such that $\#\mathcal{P}(g) = 1$. It holds that $\phi_1^\infty(g) \cap G^{1/2} \neq \emptyset$.*

Lemma 4 tells us that, from any non-pairwise stable network with two minimally connected components or one minimally connected component and one isolated firm, there is a sequence of farsighted improving paths of length 1 leading to some pairwise stable network.

Lemma 4 *Take any network $g \in \mathcal{G} \setminus G^{1/2}$ such that every component $h \in C(g)$ is minimally connected and $\#\mathcal{P}(g) = 2$. It holds that $\phi_1^\infty(g) \cap G^{1/2} \neq \emptyset$.*

Proof Starting from a network $g \notin G^{1/2}$ such that each component is minimally connected and $\#\mathcal{P}(g) = 2$ we build a sequence of farsighted improving paths of length 1 towards some network $g' \in G^{1/2}$ as follows. At each step some firm that is a leaf in the largest component is first isolated. Given **P6**, firms belonging to the largest component have incentives to isolate a firm that is a leaf. Next, given **P3**, this isolated firm and any firm that does not belong to the largest component have incentives to add a link between them. We proceed so up to the largest component reaches the size $\lceil (n+1)/2 \rceil$. Formally, let $g_0 = g$ and $g_{\bar{k}} = g'$. For $k = 1, \dots, \bar{k} = 2(\#\bar{S}(g) - \lceil (n+1)/2 \rceil)$, either $g_k = g_{k-1} - ij$ for k odd with $\#N_j(g_{k-1}) = 1$ and $j \in \bar{S}(g_{k-1})$, or $g_k = g_{k-1} + jl$ for k even with $N_j(g_{k-1}) = \emptyset$ and $l \notin \bar{S}(g_{k-1})$. When k is odd, we have that $\Pi_i(g_k) > \Pi_i(g_{k-1})$ for $i \in \bar{S}(g_{k-1}) \setminus \{j\}$ with $\mathcal{P}(g_k) = \{\bar{S}(g_{k-1}) \setminus \{j\}, \{j\}, N \setminus \bar{S}(g_{k-1})\}$. When k is even, we have that $\Pi_j(g_k) > \Pi_j(g_{k-1})$ and $\Pi_l(g_k) > \Pi_l(g_{k-1})$ for j such that $N_j(g_{k-1}) = \emptyset$ and $l \in N \setminus \bar{S}(g_{k-1})$, with $\mathcal{P}(g_k) = \{\bar{S}(g_{k-1}) \setminus \{j\}, N \setminus \bar{S}(g_{k-1}) \cup \{j\}\}$. Thus, $\phi_1^\infty(g) \cap G^{1/2} \neq \emptyset$ \square

We first show that the set of pairwise stable networks, $G^{1/2}$, is the set of pairwise dominant networks.

Proposition 1 *The set $G^{1/2}$ is the set of horizon-1 pairwise dominant networks, $D_1 = G^{1/2}$.*

Proof (i) We first show that $G^{1/2} \subseteq D_1$. Each $g \in G^{1/2}$ defeats every adjacent network g' to g , so $g \in \phi_1(g')$. Indeed, for every $g \in G^{1/2}$ we have $\Pi_i(g) > \Pi_i(g - ij)$ for all $ij \in g$. Deleting some $ij \in g$ would split one of the two components in $C(g)$ either in two new components or in one new component with an isolated firm. In both cases, all firms belonging to the component that is split become strictly worse off. Adding a link between two firms belonging to the two different components in g would strictly decrease the profit of the firm belonging to the largest component in g . That is, $\Pi_i(g) > \Pi_i(g + ij)$ for $g \in G^{1/2}$, $i \in h_1$, $j \in h_2$, $C(g) = (h_1, h_2)$, $\#N(h_1) > \#N(h_2)$; so $g \in \phi_1(g + ij)$. Adding a link $ij \notin g$ between two firms i and j belonging to the same component in $g \in G^{1/2}$ would strictly decrease the profit of both firms i and j since this link ij does not increase the profit and is infinitesimally costly; so again $g \in \phi_1(g + ij)$. Thus, $G^{1/2} \subseteq D_1$.

(ii) We now show that for any $g \notin G^{1/2}$, $\phi_1(g) \neq \emptyset$, and so $g \notin D_1$. From Lemma 1, Lemma 2, Lemma 3 and Lemma 4 it directly follows that for any $g \in \mathcal{G} \setminus G^{1/2}$ it holds that $\phi_1(g) \neq \emptyset$. Thus, from (i) and (ii) it follows that $D_1 = G^{1/2}$. \square

We next show that the set of pairwise stable networks, $G^{1/2}$, is the unique horizon-1 farsighted set.

Proposition 2 *The set $G^{1/2}$ is the unique horizon-1 farsighted set.*

Proof (i) Notice that if $g \in \phi_1^\infty(g')$ and $g' \in \phi_1^\infty(g'')$ then $g \in \phi_1^\infty(g'')$. From Lemma 1, Lemma 2, Lemma 3 and Lemma 4 it directly follows that for any $g \in \mathcal{G} \setminus G^{1/2}$ it holds that $\phi_1^\infty(g) \cap G^{1/2} \neq \emptyset$. Hence, $G^{1/2}$ satisfies horizon-1 external stability. (ii) From Proposition 1, we have that $D_1 = G^{1/2}$ and each $g \in G^{1/2}$ defeats every adjacent network g' to g , so $g \in \phi_1(g')$. Hence, $G^{1/2}$ satisfies horizon-1 deterrence of external deviations. (iii) Since $G^{1/2}$ is the set of pairwise stable networks, it holds that $\phi_1(g) = \phi_1^\infty(g) = \emptyset$ for every $g \in G^{1/2}$. Hence, $G^{1/2}$ satisfies the minimality requirement. (iv) Suppose that $G' \neq G^{1/2}$ is a horizon-1 farsighted set. Since for every $g \in G^{1/2}$, it holds that $\phi_1^\infty(g) = \emptyset$, then $G^{1/2} \subseteq G'$. Otherwise, G' violates horizon-1 external stability. But, if $G^{1/2} \subsetneq G'$ then G' violates the minimality requirement. Hence, G is the unique horizon-1 farsighted set. \square

What happens for higher degrees of farsightedness (i.e. for $K \geq 2$)? We show that a singleton set consisting of a pairwise stable network is a horizon- K farsighted set for any degree of farsightedness greater than or equal to 2. Hence, pairwise stable networks are not only stable when firms are myopic but also when firms are limitedly farsighted.

Proposition 3 *A singleton set $\{g\}$ such that $g \in G^{1/2}$ is a horizon- K farsighted set for every $K \geq 2$.*

Since $g \in D_1$, each $\{g\}$ with $g \in G^{1/2}$ satisfies horizon- K deterrence of external deviations. Obviously, each $\{g\}$ with $g \in G^{1/2}$ also satisfies the minimality requirement. We now provide Lemma 5 and Lemma 6 that are useful for showing that each $\{g\}$ with $g \in G^{1/2}$ satisfies horizon- K external stability for $K \geq 2$, and then we prove Proposition 3. Take any two pairwise stable networks such that the firms belonging to the largest component are not exactly the same. Lemma 5 tells us that there is a sequence of farsighted improving paths of length at most 2 from one of the two pairwise stable networks to some pairwise stable network where firms in the largest component are the same as the ones in the largest component of the other pairwise stable network.

Lemma 5 *Take any $g, g' \in G^{1/2}$ such that $g \neq g', \bar{S}(g) \neq \bar{S}(g')$. Then, there exists $g'' \in \phi_2^\infty(g')$ such that $g'' \in G^{1/2}$ and $\bar{S}(g) = \bar{S}(g'')$.*

Proof Take any $g, g' \in G^{1/2}$ such that $g \neq g', \bar{S}(g) \neq \bar{S}(g')$. There is $i^* \in \bar{S}(g')$ and $j^* \in N \setminus \bar{S}(g')$ such that $i^*, j^* \in \bar{S}(g)$. We now build in steps a sequence of farsighted improving paths (of length at most $K = 2$) from g' to some g'' (i.e. $g'' \in \phi_2^\infty(g')$) such that $g'' \in G^{1/2}$ and $\bar{S}(g'') = \bar{S}(g)$.

Step 1. We build a farsighted improving path of length $K = 2$ from g' where firms look two steps forward such that: $g' \rightarrow g' + i^*j^* \rightarrow g' + i^*j^* - kl$ with $k, l \in N \setminus \bar{S}(g')$, $kl \in g'$ with l being a leaf in $g' + i^*j^*$. Looking two steps forward, firms i^* and j^* have incentives to add the first link i^*j^* since $\Pi_{i^*}(g' + i^*j^* - kl) > \Pi_{i^*}(g')$ and

- $\Pi_{j^*}(g' + i^*j^* - kl) > \Pi_{j^*}(g')$ by **P4**, even though $\Pi_{i^*}(g' + i^*j^*) < \Pi_{i^*}(g')$ and $\Pi_{j^*}(g' + i^*j^*) > \Pi_{j^*}(g')$. From $g' + i^*j^*$ to $g' + i^*j^* - kl$, firm k that is not a leaf has incentives (looking one step forward) to delete its link with the leaf l since $\Pi_k(g' + i^*j^*) < \Pi_k(g' + i^*j^* - kl)$ by **P5**. Notice that $\bar{S}(g' + i^*j^* - kl) = N \setminus \{l\}$.
- Step 2.** We build a sequence of farsighted improving paths of length $K = 1$ from $g' + i^*j^* - kl$, where firms that were belonging to $N \setminus \bar{S}(g')$ are isolated one by one with firm j^* being the last one to be isolated. That is, starting from $g' + i^*j^* - kl$, we have a sequence of deviations $g' + i^*j^* - kl \rightarrow g' + i^*j^* - kl - k_1l_1 \rightarrow g' + i^*j^* - kl - k_1l_1 - k_2l_2 \rightarrow \dots \rightarrow g' + i^*j^* - \{kl \mid kl \in g' \text{ and } k, l \in N \setminus \bar{S}(g')\}$ where at each step m firm k_m deletes its link to firm l_m that is a leaf, with $k_m, l_m \neq j^*$, $k_m \neq l_m, k_m, l_m \in N \setminus \bar{S}(g'), m = 1, \dots, \#(N \setminus \bar{S}(g')) - 2$. Firm k_m that is not a leaf has incentives (looking one step forward) to delete its link with the leaf firm l_m since $\Pi_{k_m}(g' + i^*j^* - k_1l_1 - \dots - k_{m-1}l_{m-1}) < \Pi_{k_m}(g' + i^*j^* - k_1l_1 - \dots - k_{m-1}l_{m-1} - k_m l_m)$ by **P5**. Next firm i^* deletes its link with firm j^* to isolate firm j^* and we reach a network $g_1 = g' - \{ij \mid ij \in g' \text{ and } i, j \in N \setminus \bar{S}(g')\}$ where $\bar{S}(g_1) = \bar{S}(g')$ and all firms that were belonging to $N \setminus \bar{S}(g')$ are isolated. Next those isolated firms add one by one links between them to form a star component with firm j^* in the centre. By **P3**, firm j^* and each firm k have incentives to add the link j^*k to the current network looking one step forward. We reach $g_2 = g_1 + \{j^*k \mid k \neq j^*, k \in N \setminus \bar{S}(g')\}$. Notice that $\bar{S}(g_2) = \bar{S}(g')$ and $g_2 \in G^{1/2}$.
- Step 3.** We build a farsighted improving path of length $K = 2$ from $g_2 = g_1 + \{j^*k \mid k \neq j^*, k \in N \setminus \bar{S}(g')\}$ where, looking two steps forward ($K = 2$), firm i^* and firm j^* first build the link i^*j^* and next firm j^* deletes its link to some firm l with $l \in N \setminus \bar{S}(g_2)$ and $l \notin \bar{S}(g)$ so that firm l becomes isolated. Indeed, looking two steps forward, firms j^* and i^* have incentives to add the link i^*j^* since $\Pi_{i^*}(g_2 + i^*j^* - j^*l) > \Pi_{i^*}(g_2)$ and $\Pi_{j^*}(g_2 + i^*j^* - j^*l) > \Pi_{j^*}(g_2)$ by **P4**, even though $\Pi_{i^*}(g_2 + i^*j^*) < \Pi_{i^*}(g_2)$ and $\Pi_{j^*}(g_2 + i^*j^*) > \Pi_{j^*}(g_2)$. From $g_2 + i^*j^*$ to $g_2 + i^*j^* - j^*l$, firm j^* that is not a leaf has incentives (looking one step forward) to delete its link with firm l that is a leaf in $g_2 + i^*j^*$ since $\Pi_{j^*}(g_2 + i^*j^*) < \Pi_{j^*}(g_2 + i^*j^* - j^*l)$ by **P5**. Notice that $\bar{S}(g_2 + i^*j^* - j^*l) = N \setminus \{l\}$. Let $g_3 = g_2 + i^*j^* - j^*l$.
- Step 4.** We build a sequence of farsighted improving paths of length $K = 1$ from $g_3 \rightarrow g_{31} \rightarrow \dots \rightarrow g_{3\bar{m}}$ with $g_{30} = g_3, \bar{m} = \#(N \setminus \bar{S}(g)) - 1$, and $g_{3m} = g_{3m-1} - k_m l_m$ where $l_m \in \{i \notin \bar{S}(g) \mid i \text{ leaf in } g_{3m-1}\}$ if $\{i \notin \bar{S}(g) \mid i \text{ leaf in } g_{3m-1}\} \neq \emptyset$, $l_m \in \{i \in \bar{S}(g) \mid i \text{ leaf in } g_{3m-1}\}$ and $k_m l_m \notin g''$ if $\{i \notin \bar{S}(g) \mid i \text{ leaf in } g_{3m-1}\} = \emptyset$. That is, along this sequence we isolate at each step a firm that is a leaf giving priority to firms in $N \setminus \bar{S}(g)$. We so proceed up to the number of isolated firms is equal to $\#(N \setminus \bar{S}(g))$. If $\bar{S}(g_{3\bar{m}}) = \bar{S}(g)$ we go to Step 6. If $\bar{S}(g_{3\bar{m}}) \neq \bar{S}(g)$ we build a star network component between the isolated firms in $g_{3\bar{m}}$. From $g_{3\bar{m}}$, isolated firms have incentives by **P3** to add one by one links between them to form a star component with some firm $k^* \in \bar{S}(g)$ such that $N_{k^*}(g_{3\bar{m}}) = \emptyset$ in the centre. We reach $g_4 = g_{3\bar{m}} + \{k^*l \mid l \neq k^*, N_l(g_{3\bar{m}}) = \emptyset\}$. Let g'' be such that $\{k^*l \mid l \neq k^*, N_l(g_{3\bar{m}}) = \emptyset, l \in \bar{S}(g)\} \subseteq g''$. Links added from $g_{3\bar{m}}$ to g_4 between k_* and other firms belonging $\bar{S}(g)$ are not deleted later on. We next go to Step 5.
- Step 5.** We build a farsighted improving path of length $K = 2$ from $g_4 = g_{3\bar{m}} + \{k^*l \mid l \neq k^*, N_l(g_{3\bar{m}}) = \emptyset\}$ where, looking two steps forward ($K = 2$), firm j^* and firm k^* first build the link j^*k^* and next firm k^* deletes its link to some firm l with $l \in N \setminus \bar{S}(g_4)$ and $l \notin \bar{S}(g)$ so that firm l becomes isolated. Indeed, looking two steps forward, firms j^* and k^* have incentives to add the link j^*k^* since $\Pi_{j^*}(g_4 + j^*k^* - k^*l) > \Pi_{j^*}(g_4)$ and $\Pi_{k^*}(g_4 + j^*k^* - k^*l) > \Pi_{k^*}(g_4)$ by **P4**, even though $\Pi_{j^*}(g_4 + j^*k^*) < \Pi_{j^*}(g_4)$

and $\Pi_{k^*}(g_4 + j^*k^*) > \Pi_{k^*}(g_4)$. From $g_4 + j^*k^*$ to $g_4 + j^*k^* - k^*l$, firm k^* that is not a leaf has incentives (looking one step forward) to delete its link with firm l that is a leaf in $g_4 + j^*k^*$ since $\Pi_{k^*}(g_4 + j^*k^*) < \Pi_{k^*}(g_4 + j^*k^* - k^*l)$ by **P5**. Notice that $\bar{S}(g_4 + j^*k^* - k^*l) = N \setminus \{l\}$. We next repeat the process from Step 4 starting with $g_5 = g_4 + j^*k^* - k^*l$ instead of g_3 .

- Step 6. We build a sequence of farsighted improving paths of length $K = 1$ from $g_{3\bar{m}}$ with $\bar{S}(g_{3\bar{m}}) = \bar{S}(g)$, where all isolated firms belong to $N \setminus \bar{S}(g)$ and by **P3** they have incentives to add one by one links between them to form a star component with some firm $\hat{k} \in N \setminus \bar{S}(g)$ in the centre. We reach the end network $g'' = g_{3\bar{m}} + \{\hat{k}l \mid \hat{k}, l \in N \setminus \bar{S}(g), l \neq \hat{k}, \#N_{\hat{k}}(g'') = \#(N \setminus \bar{S}(g)) - 1, \#N_l(g'') = 1\}$. Thus, we have built a sequence of farsighted improving paths (of length at most $K = 2$) from g' to g'' (i.e. $g'' \in \phi_2^\infty(g')$) such that $g'' \in G^{1/2}$ and $\bar{S}(g'') = \bar{S}(g)$. □

Take any two pairwise stable networks such that the same firms belong to the largest component. Lemma 6 tells us that there is a sequence of farsighted improving paths of length at most 2 from each pairwise stable network to the other one.

Lemma 6 Take any $g, g' \in G^{1/2}$ such that $g \neq g', \bar{S}(g) = \bar{S}(g')$. Then, $g \in \phi_2^\infty(g')$.

Proof Take any $g, g' \in G^{1/2}$ such that $g \neq g', \bar{S}(g) = \bar{S}(g')$. We now build in steps a sequence of farsighted improving paths (of length at most $K = 2$) from g' to g , i.e. $g \in \phi_2^\infty(g')$.

- Step 1. Let $g_0 = g'$. We build a farsighted improving path of length $K = 2$ from g_0 where firms look two steps forward such that: $g_0 \rightarrow g_0 + ij \rightarrow g_0 + ij - kl$ with $i \in \bar{S}(g_0)$, $j, k, l \in N \setminus \bar{S}(g_0)$, $kl \in g_0$ with l being a leaf in $g_0 + ij$. Looking two steps forward, firms i and j have incentives to add the first link ij since $\Pi_i(g_0 + ij - kl) > \Pi_i(g_0)$ and $\Pi_j(g_0 + ij - kl) > \Pi_j(g_0)$ by **P4**, even though $\Pi_i(g_0 + ij) < \Pi_i(g_0)$ and $\Pi_j(g_0 + ij) > \Pi_j(g_0)$. From $g_0 + ij$ to $g_0 + ij - kl$, firm k that is not a leaf has incentives (looking one step forward) to delete its link with the leaf l since $\Pi_k(g_0 + ij) < \Pi_k(g_0 + ij - kl)$ by **P5**. Notice that $\bar{S}(g_0 + ij - kl) = N \setminus \{l\}$.
- Step 2. We build a farsighted improving path of length $K = 2$ from $g_0 + ij - kl$ where firms look two steps forward such that: $g_0 + ij - kl \rightarrow g_0 + ij - kl + i_1j_1 \rightarrow g_0 + ij - kl + i_1j_1 - k_1l_1$ with $i_1, j_1 \in \bar{S}(g_0)$, $i_1j_1 \in g$, $i_1j_1 \notin g_0$, $l_1 \in N \setminus \bar{S}(g_0)$, $k_1l_1 \in g_0 + ij - kl + i_1j_1$ with l_1 being a leaf in $g_0 + ij - kl + i_1j_1$. Looking two steps forward, firms i_1 and j_1 have incentives to add the first link i_1j_1 since $\Pi_{i_1}(g_0 + ij - kl + i_1j_1 - k_1l_1) > \Pi_{i_1}(g_0 + ij - kl)$ and $\Pi_{j_1}(g_0 + ij - kl + i_1j_1 - k_1l_1) > \Pi_{j_1}(g_0 + ij - kl)$ by **P5**, even though $\Pi_{i_1}(g_0 + ij - kl + i_1j_1) < \Pi_{i_1}(g_0 + ij - kl)$ and $\Pi_{j_1}(g_0 + ij - kl + i_1j_1) < \Pi_{j_1}(g_0 + ij - kl)$. From $g_0 + ij - kl + i_1j_1$ to $g_0 + ij - kl + i_1j_1 - k_1l_1$, firm k_1 that is not a leaf has incentives (looking one step forward) to delete its link with the leaf l_1 since $\Pi_{k_1}(g_0 + ij - kl + i_1j_1) < \Pi_{k_1}(g_0 + ij - kl + i_1j_1 - k_1l_1)$ by **P5**.
- Step 3. We build a farsighted improving path of length $K = 1$ from $g_0 + ij - kl + i_1j_1 - k_1l_1$ to $g_0 + ij - kl + i_1j_1 - k_1l_1 - i_2j_2$ with $i_2, j_2 \in \bar{S}(g_0)$, $i_2j_2 \notin g$, $i_2j_2 \in g_0 + ij - kl + i_1j_1 - k_1l_1$, where i_2j_2 is a superfluous link in the largest component and it does not belong to the end network g ,²² and so, $\Pi_{i_2}(g_0 + ij - kl + i_1j_1 - k_1l_1) <$

²² By adding the link i_1j_1 , there are now two paths connecting i_1 and j_1 in the network, and so there is a superfluous link that does not belong to the end network on the path that connects indirectly i_1 and j_1 .

- $\Pi_{i_2}(g_0 + ij - kl + i_1j_1 - k_1l_1 - i_2j_2)$ and $\Pi_{j_2}(g_0 + ij - kl + i_1j_1 - k_1l_1) < \Pi_{j_2}(g_0 + ij - kl + i_1j_1 - k_1l_1 - i_2j_2)$.
- Step 4. We repeat the process from Step 2 until **(i)** every firm belonging to $N \setminus \bar{S}(g_0)$ is now isolated, or **(ii)** each link $ij \in g$ such that $i, j \in \bar{S}(g)$ belongs to $g_0 + ij - kl + i_1j_1 - k_1l_1 - i_2j_2 + \dots + i_{\bar{m}-1}j_{\bar{m}-1} - k_{\bar{m}-1}l_{\bar{m}-1} - i_{\bar{m}}j_{\bar{m}}$ and each link $ij \notin g$ such that $i, j \in \bar{S}(g)$ does not belong to $g_0 + ij - kl + i_1j_1 - k_1l_1 - i_2j_2 + \dots + i_{\bar{m}-1}j_{\bar{m}-1} - k_{\bar{m}-1}l_{\bar{m}-1} - i_{\bar{m}}j_{\bar{m}}$, with $\bar{m} = \#\{ij \in g \mid ij \notin g_0 \text{ and } i, j \in \bar{S}(g)\}$. If $\#(N \setminus \bar{S}(g)) - 1 < \bar{m}$ then **(i)** is first satisfied and go to Step 5. If $\#(N \setminus \bar{S}(g)) - 1 > \bar{m}$ then **(ii)** is first satisfied and go to Step 6. If $\#(N \setminus \bar{S}(g)) - 1 = \bar{m}$ then **(i)** and **(ii)** are both satisfied and go to Step 7.
- Step 5. From Step 4 we have reached the network $g_1 = g_0 + ij - kl + i_1j_1 - k_1l_1 - i_2j_2 + \dots + i_{\bar{m}-1}j_{\bar{m}-1} - k_{\bar{m}-1}l_{\bar{m}-1} - i_{\bar{m}}j_{\bar{m}}$ where all firms in $N \setminus \bar{S}(g)$ are isolated and $\bar{S}(g) = \bar{S}(g_1)$. Notice that $\#\{ij \in g \mid ij \notin g_0 \text{ and } i, j \in \bar{S}(g)\} = \bar{m} \leq \#\bar{S}(g) - 1$ and $\#\bar{S}(g) - \#(N \setminus \bar{S}(g)) \leq 2$. Hence, $\bar{m} - \#(N \setminus \bar{S}(g)) + 1 \leq 2$. First, we build a sequence of farsighted improving paths of length $K = 1$ from g_1 to $g_1 + \{k^*l \mid l \in N \setminus \bar{S}(g), l \neq k^*\} \in G^{1/2}$, where each firm $l \neq k^*$ belonging to $N \setminus \bar{S}(g)$ adds successively links to firm $k^* \in N \setminus \bar{S}(g)$ to form a star component with k^* in the centre. By **P3**, firm k^* and each firm l have incentives to add the link k^*l to the current network looking one step forward. Next, we repeat the process from Step 1 to Step 4 starting with $g_0 = g_1 + \{k^*l \mid l \in N \setminus \bar{S}(g), l \neq k^*\}$, followed by Step 6.²³
- Step 6. We build a sequence of farsighted improving paths of length $K = 1$ from $g_0 + ij - kl + i_1j_1 - k_1l_1 - i_2j_2 + \dots + i_{\bar{m}-1}j_{\bar{m}-1} - k_{\bar{m}-1}l_{\bar{m}-1} - i_{\bar{m}}j_{\bar{m}}$ to $\{ij \in g \mid i, j \in \bar{S}(g)\}$, where each firm $i \in \bar{S}(g_0 + ij - kl + i_1j_1 - k_1l_1 - i_2j_2 + \dots + i_{\bar{m}-1}j_{\bar{m}-1} - k_{\bar{m}-1}l_{\bar{m}-1} - i_{\bar{m}}j_{\bar{m}})$ such that $i \notin \bar{S}(g)$ and i is (or becomes during the process) a leaf is isolated one by one. We reach the network $\{ij \in g \mid i, j \in \bar{S}(g)\}$ where every firm $i \notin \bar{S}(g)$ is isolated. Next, go to Step 8.
- Step 7. From Step 4 we have already reached the network $\{ij \in g \mid i, j \in \bar{S}(g)\}$ where all firms belonging to $\bar{S}(g)$ are exactly as in the end network g while all firms belonging to $N \setminus \bar{S}(g)$ are isolated. Next, go to Step 8.
- Step 8. Finally, firms belonging to $N \setminus \bar{S}(g)$ have incentives by **P3** to add successively links between them to form the network $g \in G^{1/2}$. Thus, we have built in steps a sequence of farsighted improving paths (of length at most $K = 2$) from g' to g , i.e. $g \in \phi_2^\infty(g')$.

□

Proof (Proof of Proposition 3) Take any $g \in G^{1/2}$. We show that a singleton set $\{g\}$ is a horizon- K farsighted set for every $K \geq 2$.

- (i) We first show that each $\{g\}$ satisfies horizon- K external stability for $K \geq 2$. Notice that if $g \in \phi_1^\infty(g')$ and $g' \in \phi_2^\infty(g'')$ then $g \in \phi_2^\infty(g'')$. **(i.a)** From Lemma 1, Lemma 2, Lemma 3 and Lemma 4 it directly follows that for any $g \in \mathcal{G} \setminus G^{1/2}$ it holds that $\phi_1^\infty(g) \cap G^{1/2} \neq \emptyset$. **(i.b)** From Lemma 5 and Lemma 6 we have that, for any $g, g' \in G^{1/2}$, $g \neq g'$, $g' \in \phi_2^\infty(g)$. Hence, from **(i.a)** and **(i.b)** it follows that $g \in \phi_2^\infty(g')$ for all $g' \in \mathcal{G} \setminus \{g\}$.

²³ Since the number of links in the smallest component (i.e. $\#N \setminus \bar{S}(g) - 1$ links) is greater than or equal to the maximum number of links that belong to the end network and are still missing in the largest component (i.e. 2 links), we only need to repeat one time the process from Step 1 to Step 4, and so, we go directly from Step 4 to Step 6 after the first repetition.

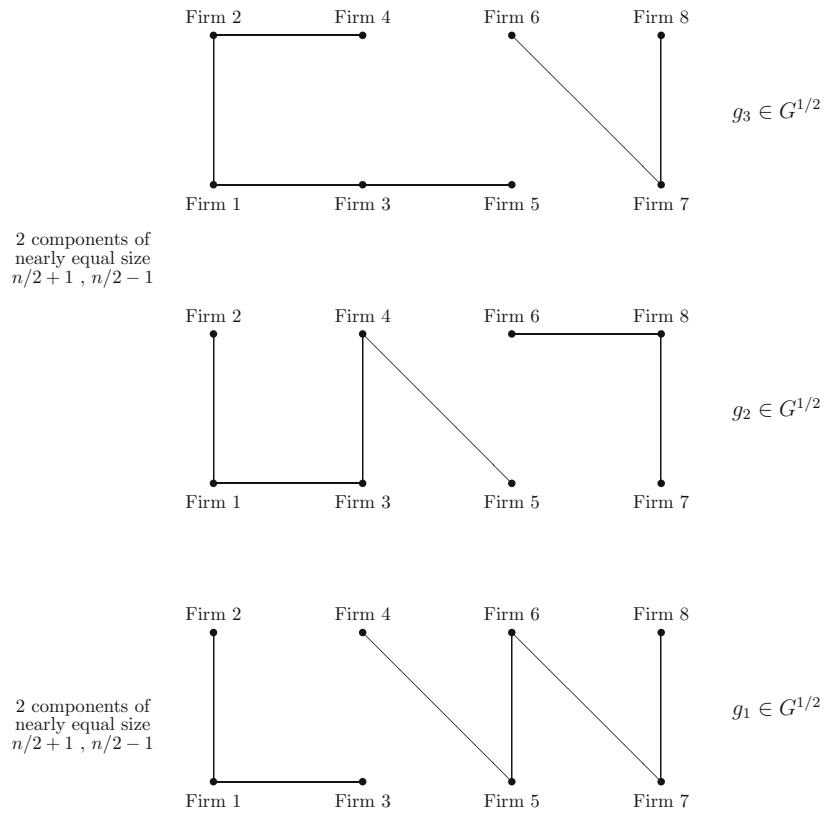


Fig. 1 Some R&D networks in $G^{1/2}$ when $n = 8$

- (ii) We now show that each $\{g\}$ satisfies horizon- K deterrence of external deviations for $K \geq 2$. From Proposition 1, we have that $D_1 = G^{1/2}$ and each $g \in G^{1/2}$ defeats every adjacent network g' to g , so $g \in \phi_1(g') \subseteq \phi_2(g')$. Hence, $\{g\}$ satisfies horizon- K deterrence of external deviations for $K \geq 2$.
- (iii) Since $\{g\}$ is a singleton set, it satisfies minimality.

□

Example 1 We illustrate the proofs of Lemma 5 and Lemma 6 in the case of eight firms ($n = 8$). In Fig. 1, we depict three R&D networks, $g_1, g_2, g_3 \in G^{1/2}$ to show that $g_2 \in \phi_2^\infty(g_1)$ and $g_3 \in \phi_2^\infty(g_2)$ so that $g_3 \in \phi_2^\infty(g_1)$. Notice that $\bar{S}(g_2) = \bar{S}(g_3)$ and so $N \setminus \bar{S}(g_2) = N \setminus \bar{S}(g_3)$ but $g_2 \neq g_3$. Starting from $g_1 \in G^{1/2}$, we build a sequence of farsighted improving paths of length at most 2 ending in $g_2 \in G^{1/2}$. First, (looking two steps forward) $g_1 \rightarrow g_1 + 34 \rightarrow g_1 + 34 - 78 = g_{11}$, followed by (looking one step forward) $g_{11} \rightarrow g_{11} - 67 \rightarrow g_{11} - 67 - 56 = g_{12}$, followed by (looking one step forward) $g_{12} \rightarrow g_{12} + 68 \rightarrow g_{12} + 68 + 78 = g_2$; so $g_2 \in \phi_2^\infty(g_1)$. Starting from g_2 , we build a sequence of farsighted improving paths of length at most 2 ending in g_3 . First, (looking two steps forward) $g_2 \rightarrow g_2 + 58 \rightarrow g_2 + 58 - 68 = g_{21}$, followed by (looking two steps forward) $g_{21} \rightarrow g_{21} + 24 \rightarrow g_{21} + 24 - 78 = g_{22}$, followed

by (looking one step forward) $g_{22} \rightarrow g_{22} - 34 = g_{23}$, followed by (looking two steps forward) $g_{23} \rightarrow g_{23} + 35 \rightarrow g_{23} + 35 - 58 = g_{24}$, followed by (looking one step forward) $g_{24} \rightarrow g_{24} + 67 \rightarrow g_{24} + 67 + 78 = g_3$; so $g_3 \in \phi_2^\infty(g_2)$. Thus, $g_3 \in \phi_2^\infty(g_1)$.

Next proposition shows that, meanwhile each singleton set $\{g\}$ with $g \in G^{1/2}$ is a horizon- K farsighted set for every $K \geq 2$, networks that are not pairwise stable cannot be a singleton horizon- K farsighted set. Hence, pairwise stable R&D networks seem robust to limited farsightedness.

Proposition 4 *Take any $g \notin G^{1/2}$ such that $\#\mathcal{P}(g) \leq 2$ and every $h \in C(g)$ is minimally connected. Then, $\{g\}$ is never a horizon- K farsighted set for $K \geq 2$.*

Proof We show that for any $g \notin G^{1/2}$ such that $\#\mathcal{P}(g) \leq 2$ and every $h \in C(g)$ is minimally connected, the singleton set $\{g\}$ violates horizon- K deterrence of external deviations.

- (i) Take a minimally connected network g such that $\mathcal{P}(g) = \{N\}$ and an adjacent network $g' = g - ij$ to g where j is a leaf in g . Then, all firms in $\bar{S}(g')$ are strictly better off in g' than in g , and so they will not participate to any deviation from g' towards g . Hence, $g \notin \phi_{K-1}(g')$, $K \geq 2$ and the deviation to $g' = g - ij$ is not deterred.
- (ii) Take a network g such that $\mathcal{P}(g) = \{S_1(g), S_2(g)\}$ with $\#S_1(g) = \#S_2(g)$, each $h \in C(g)$ is minimally connected and an adjacent network $g' = g + ij$ to g where $i \in S_1(g)$ and $j \in S_2(g)$. Then, all firms in $S_1(g)$ and $S_2(g)$ are strictly better off in g' than in g , and so they will not participate to any deviation from g' towards g . Hence, $g \notin \phi_{K-1}(g')$, $K \geq 2$ and the deviation to $g' = g - ij$ is not deterred.
- (iii) Take a network g such that $\mathcal{P}(g) = \{S_1(g), S_2(g)\}$ with $\#S_1(g) > \lfloor (n+3)/2 \rfloor$ if n even and $\#S_1(g) > (n+1)/2$ if n odd, and each $h \in C(g)$ is minimally connected. Take an adjacent network $g' = g - ij$ to g where $ij \in g$, $i, j \in \bar{S}(g) = S_1(g)$, j is a leaf in g and $\mathcal{P}(g') = \{S_1(g) \setminus \{j\}, \{j\}, S_2(g)\}$. Then, all firms in $S_1(g) \setminus \{j\} = \bar{S}(g')$ and in $S_2(g)$ are strictly better off in g' than in g , and so they will not participate to any deviation from g' towards g . Hence, $g \notin \phi_{K-1}(g')$, $K \geq 2$ and the deviation to $g' = g - ij$ is not deterred.

□

From Proposition 4, we have that only singleton sets $\{g\}$ with $g \in G^{1/2}$ are horizon- K farsighted sets for every $K \geq 2$. Singleton sets provide precise predictions and thus reinforce the robustness of R&D networks consisting of two components of nearly equal size. However, for $K \geq 2$, limitedly farsighted firms can profitably move away from the pairwise stable R&D networks. Indeed, $\phi_K(g) \neq \emptyset$ for $g \in G^{1/2}$ with $K \geq 2$. Hence, the stability of non-singleton sets is not excluded.

When the degree of farsightedness is great enough ($K \geq n' + 1$), then a subset of the networks that are stable when all firms are farsighted become a horizon- K farsighted set. Indeed, Mauleon et al. [21] show that $G^{3/4}$ is a pairwise farsightedly stable set, while Herings et al. [11] find that, for every pairwise farsightedly stable set G_∞ there exists some $G \subseteq G_\infty$ such that G is a horizon- $(n' + 1)$ farsighted set where n' is the cardinality of \mathcal{G} . Hence, together with Proposition 4, we obtain the following corollary.

Corollary 1 *There is $G \subseteq G^{3/4}$ such that G is a horizon- $(n' + 1)$ farsighted set and $\#G \neq 1$.*

5 Conclusion

We study the R&D networks that will emerge in the long run when firms are neither myopic nor fully farsighted but have some limited degree of farsightedness. We adopt the horizon- K farsighted set of Herings et al. [11], and we find that a singleton set consisting of a pairwise stable network is a horizon- K farsighted set for any degree of farsightedness greater than or equal to 2. That is, each R&D network consisting of two components of nearly equal size satisfies both horizon- K deterrence of external deviations and horizon- K external stability for $K \geq 2$. On the contrary, each R&D network consisting of two components with the largest one comprising three-quarters of firms, predicted when all firms are fully farsighted, violates horizon- K deterrence of external deviations. Thus, when firms are homogeneous in their degree of farsightedness, R&D networks consisting of two components of nearly equal size are robust to limited farsightedness.

The intuition behind this result is that any deviation engaged by limitedly farsighted firms from any network with two components of nearly equal size is not only costly in the short run but also risky in the long run. Limitedly farsighted firms are not able to forecast perfectly where any deviation may lead to in the long run. Indeed, starting new R&D collaborations or putting an end to existing ones may lead to a network with asymmetric components without the guarantee of ending up in the largest component. Hence, long-run losses are not excluded. In addition, any deviation from any network with two components of nearly equal size is costly in the short run for the deviating firms. Thus, when firms have limited farsightedness, the industry reaches more equal distribution of profits.

As already mentioned, the properties **P1-P6** on the profit function can also be satisfied in the case of nonlinear inverse demand functions (e.g. constant-elasticity inverse demand function or iso-elastic inverse demand function) under some conditions. However, the pairwise stable networks under the linear demand function could then be defeated by some adjacent network. Nevertheless, when any R&D network with two components of nearly equal size remains pairwise stable, all our results still hold.

Acknowledgements Ana Mauleon and Vincent Vannetelbosch are, respectively, Research Director and Senior Research Associate of the National Fund for Scientific Research (FNRS). Financial support from the Fonds de la Recherche Scientifique—FNRS research grant T.0143.18 is gratefully acknowledged. Jose J. Sempere-Monerris gratefully acknowledges financial support from the Spanish Ministry of Science and Innovation, AEI and FEDER under the project PID2019-107895RB-I00, as well as from Generalitat Valenciana under the project PROMETEO/2019/095.

References

1. Amir R (2000) Modelling imperfectly appropriable R&D via spillovers. *Int J Ind Org* 18:1013–1032
2. Bloch F (1995) Endogenous structures of association in oligopolies. *Rand J Econ* 26:537–556
3. Bloch F (2005) Group and network formation in industrial organization: a survey. In: Demange G, Wooders M (eds) *Group formation in economics: Networks, clubs and coalitions*. Cambridge University Press, Cambridge
4. Caulier J-F, Mauleon A, Vannetelbosch V (2013a) Contractually stable networks. *Int J Game Theory* 42:483–499
5. Caulier J-F, Mauleon A, Sempere-Monerris JJ, Vannetelbosch V (2013b) Stable and efficient coalitional networks. *Rev Econ Des* 17:249–271
6. Chwe MS (1994) Farsighted coalitional stability. *J Econ Theory* 63:299–325
7. Dutta B, Ghosal S, Ray D (2005) Farsighted network formation. *J Econ Theory* 122:143–164
8. Goyal S, Joshi S (2003) Networks of collaboration in oligopoly. *Games Econ Behav* 43:57–85
9. Goyal S, Moraga-Gonzalez JL (2001) R&D networks. *RAND J Econ* 32:686–707

10. Herings PJJ, Mauleon A, Vannetelbosch V (2004) Rationalizability for social environments. *Games Econ Behav* 49:135–156
11. Herings PJJ, Mauleon A, Vannetelbosch V (2009) Farsightedly stable networks. *Games Econ Behav* 67:526–541
12. Herings PJJ, Mauleon A, Vannetelbosch V (2019) Stability of networks under horizon- K farsightedness. *Econ Theory* 68:177–201
13. Herings PJJ, Mauleon A, Vannetelbosch V (2020) Matching with myopic and farsighted players. *J Econ Theory* 190:105125
14. Jackson MO, Watts A (2002) The evolution of social and economic networks. *J Econ Theory* 106:265–295
15. Jackson MO, Wolinsky A (1996) A strategic model of social and economic networks. *J Econ Theory* 71:44–74
16. Kamien M, Muller E, Zang I (1992) Research joint ventures and R&D cartels. *Am Econ Rev* 85:1293–306
17. Katz M (1986) An analysis of cooperative R&D. *Rand J Econ* 17:527–43
18. Kirchsteiger G, Mantovani M, Mauleon A, Vannetelbosch V (2016) Limited farsightedness in network formation. *J Econ Behav Org* 128:97–120
19. Luo C, Mauleon A, Vannetelbosch V (2021) Network formation with myopic and farsighted players. *Econ Theory* 71:1283–1317
20. Mauleon A, Sempere-Monerris JJ, Vannetelbosch V (2008) Networks of knowledge among unionized firms. *Can J Econ* 41:971–997
21. Mauleon A, Sempere-Monerris JJ, Vannetelbosch V (2014) Farsighted R&D networks. *Econ Lett* 125:340–342
22. Mauleon A, Sempere-Monerris JJ, Vannetelbosch V (2016) Contractually stable alliances. *J Public Econ Theory* 18:212–225
23. Mauleon A, Sempere-Monerris JJ, Vannetelbosch V (2018) R&D network formation with myopic and farsighted firms. CORE Discussion Paper 2018-26, UCLouvain, Belgium
24. Mauleon A, Vannetelbosch V (2004) Farsightedness and cautiousness in coalition formation games with positive spillovers. *Theory Decision* 56:291–324
25. Mauleon A, Vannetelbosch V (2016) Network formation games. In: Bramoullé Y, Galeotti A, Rogers BW (eds) *The Oxford handbook of the economics of networks*. Oxford University Press, Oxford
26. Mauleon A, Vannetelbosch V, Vergote W (2011) von Neumann Morgenstern farsightedly stable sets in two-sided matching. *Theor Econ* 6:499–521
27. Page FH Jr, Wooders M, Kamat S (2005) Networks and farsighted stability. *J Econ Theory* 120:257–269
28. Page FH Jr, Wooders M (2009) Strategic basins of attraction, the path dominance core, and network formation games. *Games Econ Behav* 66:462–487
29. Petrakis E, Tsakas N (2018) The effect of entry on R&D networks. *RAND J Econ* 49:706–750
30. Ray D, Vohra R (2015) The farsighted stable set. *Econometrica* 83:977–1011
31. Roketskiy N (2018) Competition and networks of collaboration. *Theor Econ* 13:1077–1110
32. Xue L (1998) Coalitional stability under perfect foresight. *Econ Theory* 11:603–627
33. Yi SS (1997) Stable coalition structures with externalities. *Games Econ Behav* 20:201–237
34. Yi SS, Shin H (2000) Endogenous formation of research coalitions with spillovers. *Int J Ind Org* 18:229–56

Publisher's Note Springer Nature remains neutral with regard to jurisdictional claims in published maps and institutional affiliations.

Springer Nature or its licensor holds exclusive rights to this article under a publishing agreement with the author(s) or other rightsholder(s); author self-archiving of the accepted manuscript version of this article is solely governed by the terms of such publishing agreement and applicable law.