



Validation of Rotorwash Simulation using Blade-resolved and Blade-modeled CFD

The background of the slide is a large, diagonal image showing a CFD simulation of rotorwash. The left half of the image displays a dense, chaotic field of blue and red streamlines, representing a highly turbulent flow. The right half shows a more organized flow with distinct, swirling red and blue structures, possibly indicating vortices or specific flow patterns. The overall color palette is dominated by blue and red, set against a dark background.

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Presented at CFC2023, session MS4-02E, April 27th 2023

Urban Air Mobility



- Urban Air Mobility (UAM) will enable on-demand **passenger-** or **cargo-carrying air services** in metropolitan environments.
- Many different concepts **Vertical Take-Off and Landing** vehicles are under development.
- Aerodynamics are affected by the urban environment, **vertiport design** and **ground effect**.

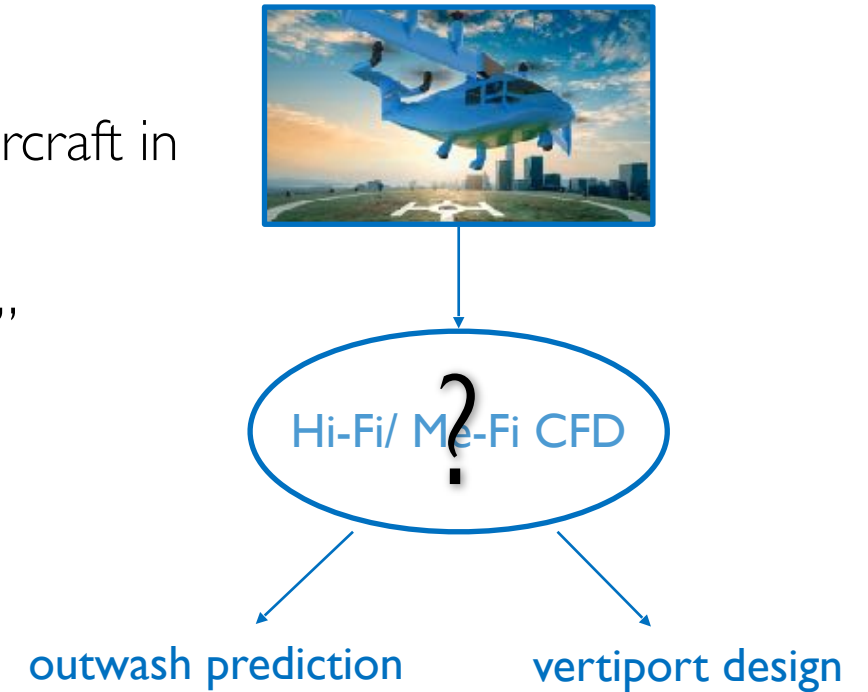


Artist's impression of UAM

Objectives



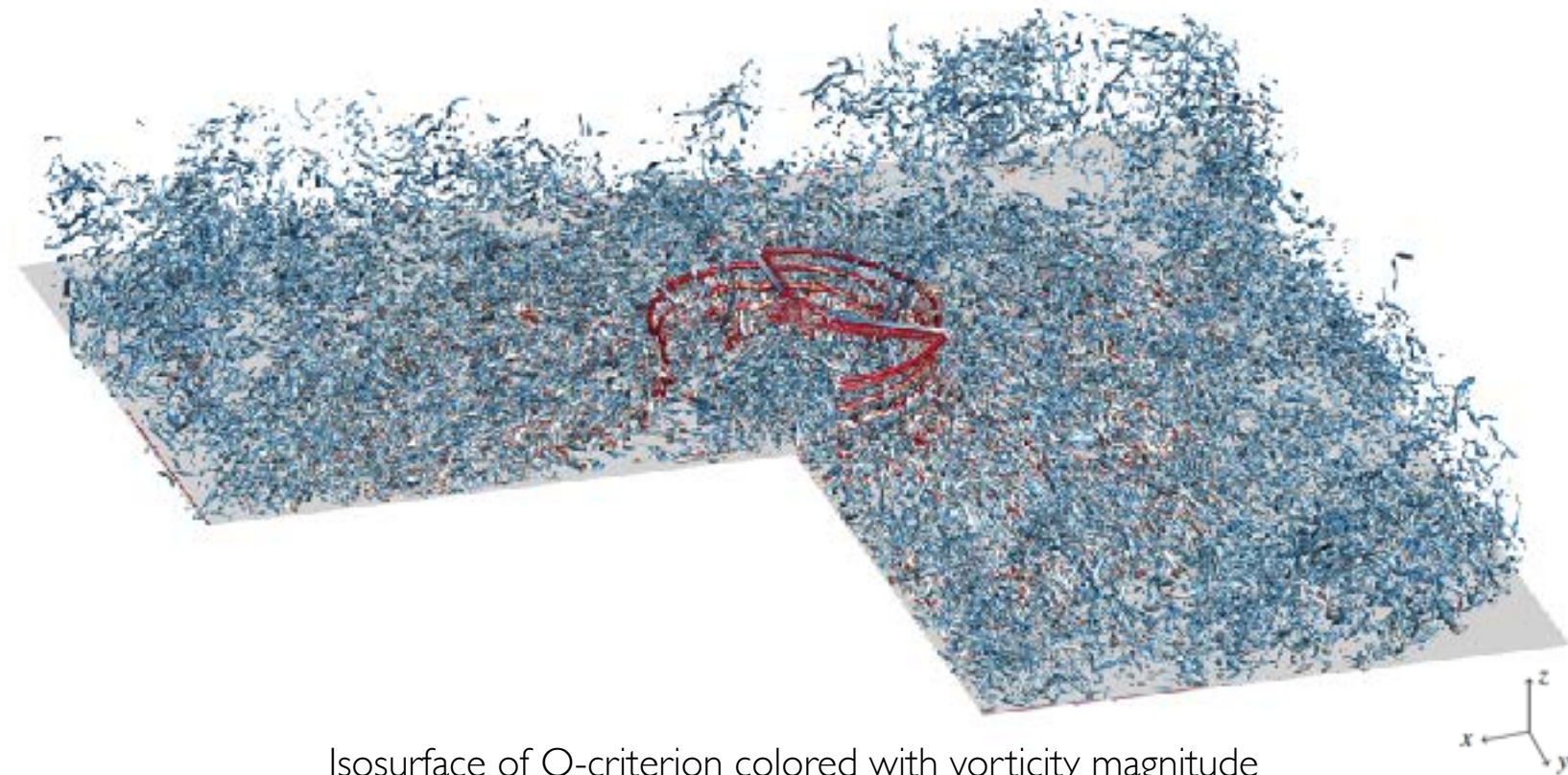
- Adapt existing **best practice** for “high-fidelity” CFD of rotorcraft in ground effect (**IGE**)
- **Assess the accuracy and the potential** of “medium-fidelity” methods
- Application to **single rotor** and **quadrotor** [1]



Can the tools be used to **predict outwash hazardousness** for different configurations of multi-rotor UAM vehicles and **support vertiport design**?

NASA's OVERFLOW solver [2]

- Structured **overset** grids
- **High order** accurate scheme
 - 5th order central differences with scalar/matrix dissipation for convective terms
- **Dual time-stepping**
 - 2nd order accurate
 - 50 implicit sub-iterations
- **Hybrid RANS/LES**
 - Spalart-Allmaras one equation turbulence model near the walls
 - $y^+ \leq 1$



Isosurface of Q-criterion colored with vorticity magnitude

Overset Grid Generation

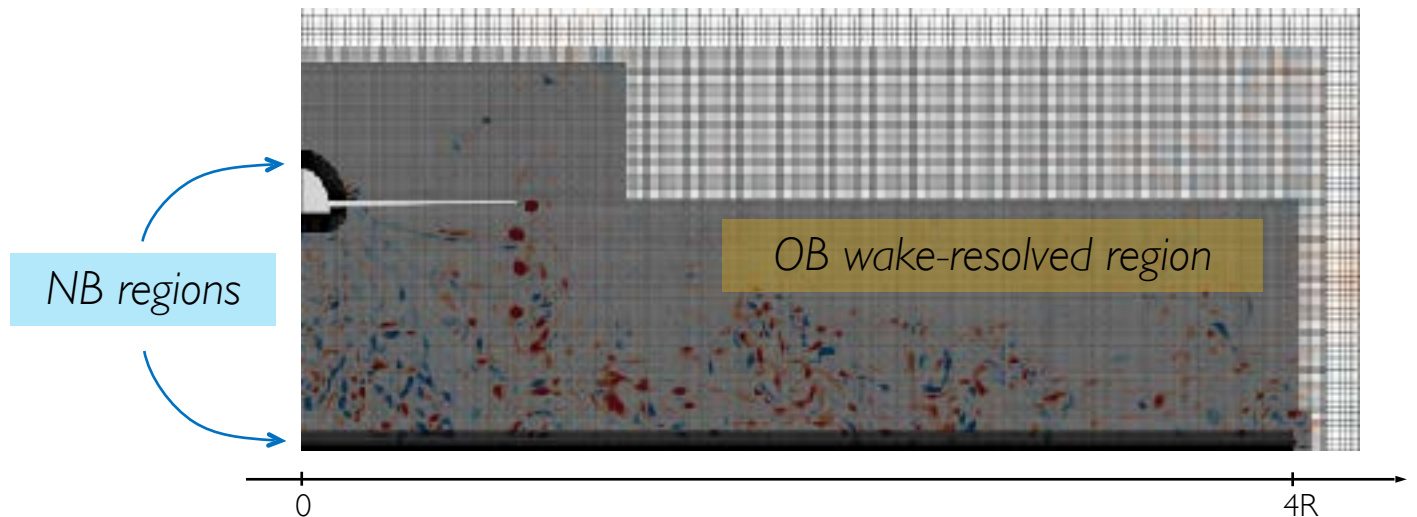
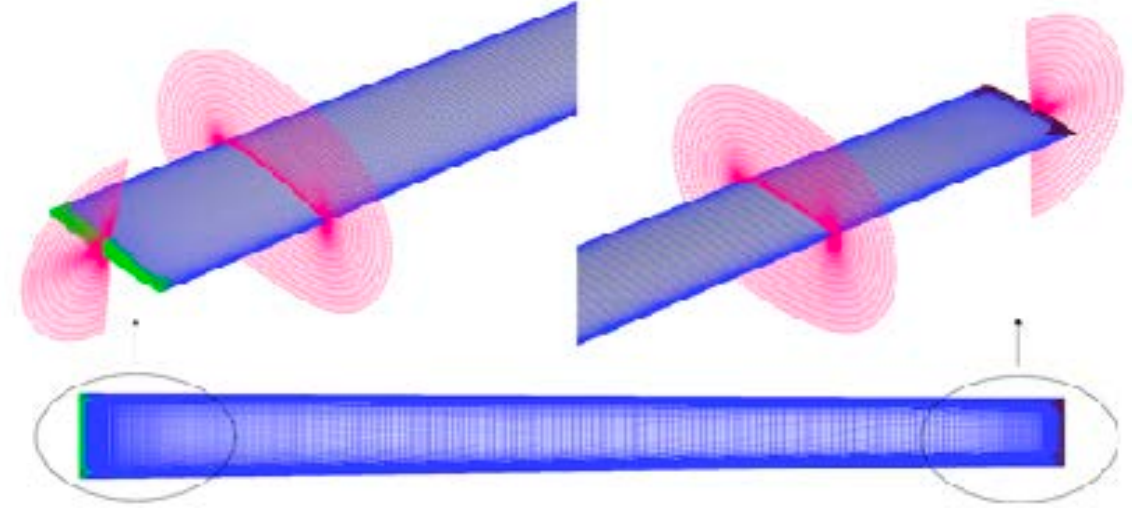


NASA's Chimera Grid Tools (CGT) software [3]

- **Geometry processing**
 - Clean geometry definition
 - Obtained from CAD or 3D scan techniques
- **Surface grid generation**
 - Clustering in high-gradient regions
 - Mesh generation with hyperbolic marching or transfinite interpolation
- **Volume grid generation**
 - Hyperbolic near-body (NB)
 - Cartesian off-body (OB)
- **Domain connectivity**

See also CFC23: MS4-02E (Ventura Diaz et al.)

Same geometry as in [4]

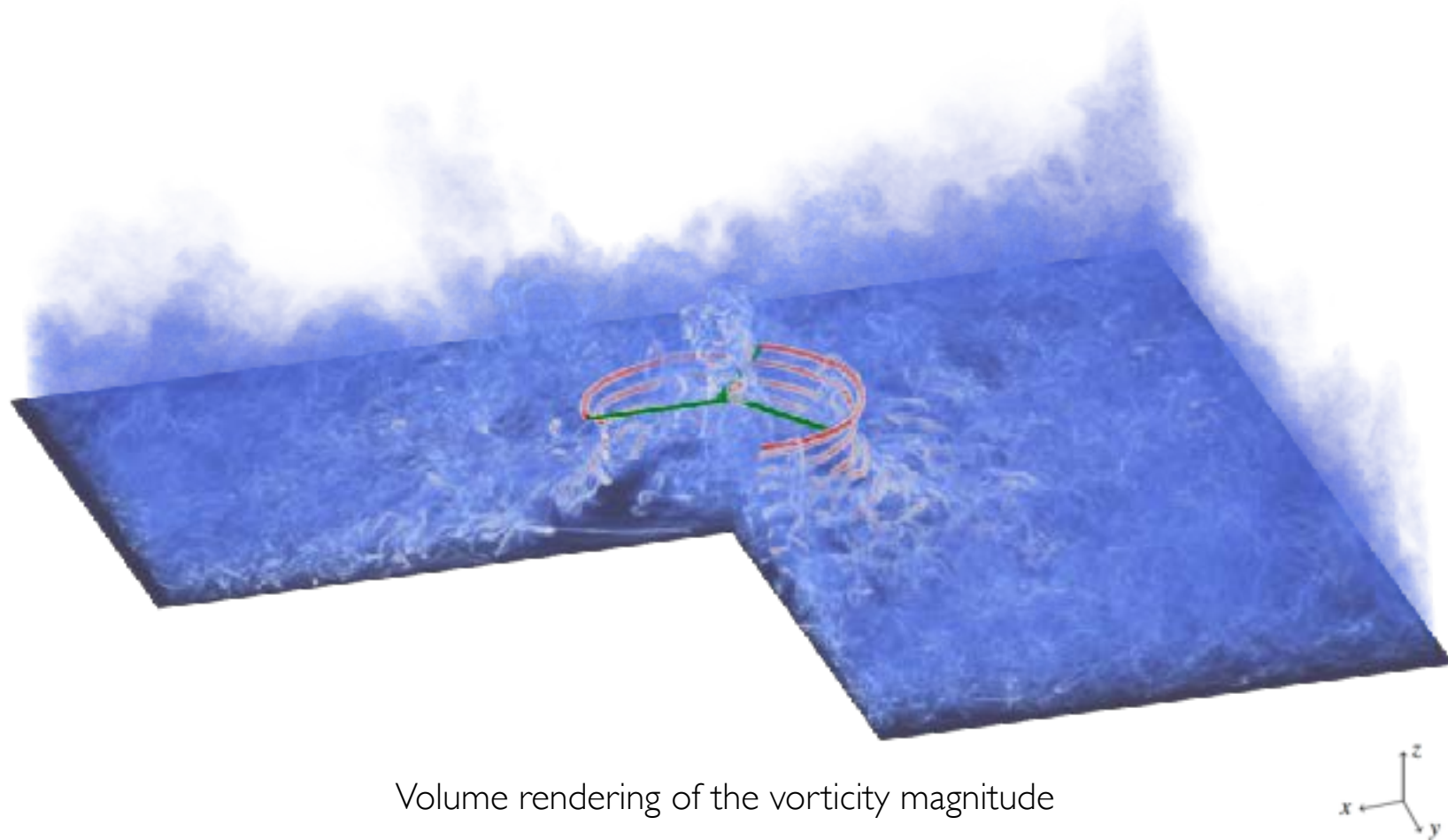


[3] W. Chan, R. Gomez, S. Rogers, and P. Buning, "Best Practices in Overset Grid Generation", AIAA Paper 2002-3191.

[4] P. Ventura Diaz and S. Yoon, "High-fidelity simulations of a quadrotor vehicle for urban air mobility," AIAA Paper 2022-0152.

Vortex Particle-Mesh method [4]

- Hybrid **Lagrangian-Eulerian**
 - Vorticity-velocity form. of N.-S.
 - Advection solved with **particles**
 - Background **Cartesian grid** to solve RHS with **4th order finite differences**
 - High-order particles-grid interpolation
 - RK3 time integration
- **Features**
 - Regularized Variational Multiscale Model **sub-grid scale model** [5]
 - **Remeshing** and **reprojection**
 - **Immersed lifting line** method [6]
 - Unbounded and **no-slip BC**



Volume rendering of the vorticity magnitude

See also CFC23: MS2-03A (Colognesi *et al.*), MS5-01E (Billuart *et al.*)

[4] P. Chatelain, A. Curioni, M. Bergdorf, D. Rossinelli, W. Andreoni, and P. Koumoutsakos, "Billion vortex particle Direct Numerical Simulations of aircraft wakes," *Comp Meth in Appl Mech and Eng*, vol. 197, Feb 2008.

[5] H. Jeanmart and G. Winckelmans, "Investigation of eddy-viscosity models modified using discrete filters," *Physics of Fluids*, vol. 19, May 2007.

[6] D.-G. Caprace, A. Ning, P. Chatelain, and G. Winckelmans, "Effects of rotor-airframe interaction on the aeromechanics and wake of a quadcopter in forward flight," *Aerospace Science and Technology*, 2022.

Computational Setup – Single Rotor

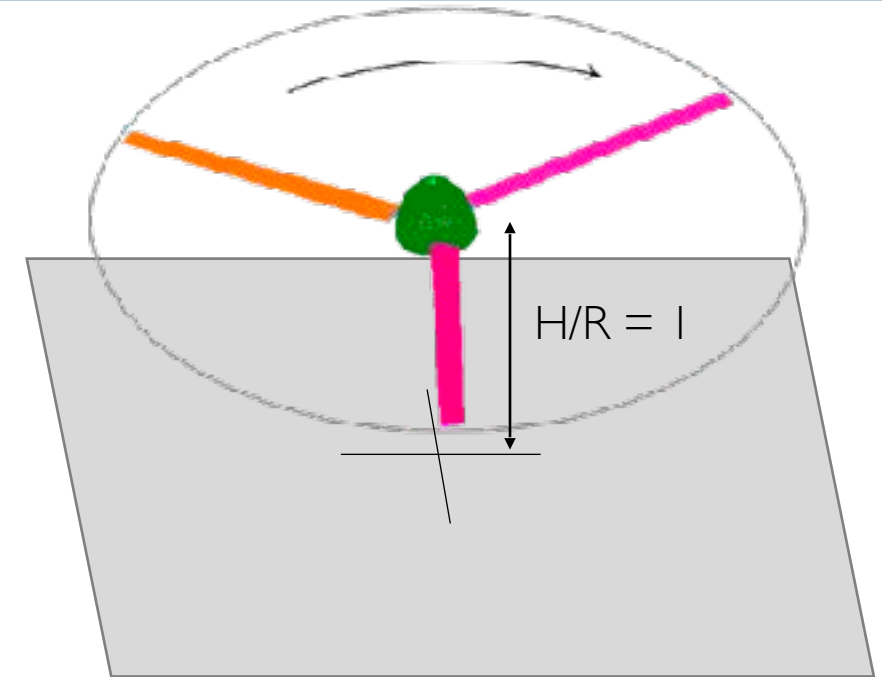


OVERFLOW

- based on validated best-practice for rotorcraft simulation [7,8]
 - grid resolution 10% c_{tip} (439M points)
 - 4th order, matrix dissipation, 0.25° per time step
- ~ 2000 CPUs x 1 month = 1.89M CPUh

VPM method

- 3 different mesh resolutions
 - 32 particles per R (19M particles)
 - 48 particles per R (65M particles)
 - 64 particles per R (153M particles)
- $CFL_{tip} = 4$
- ~ 288 CPUs x 24 h = 7k CPUh



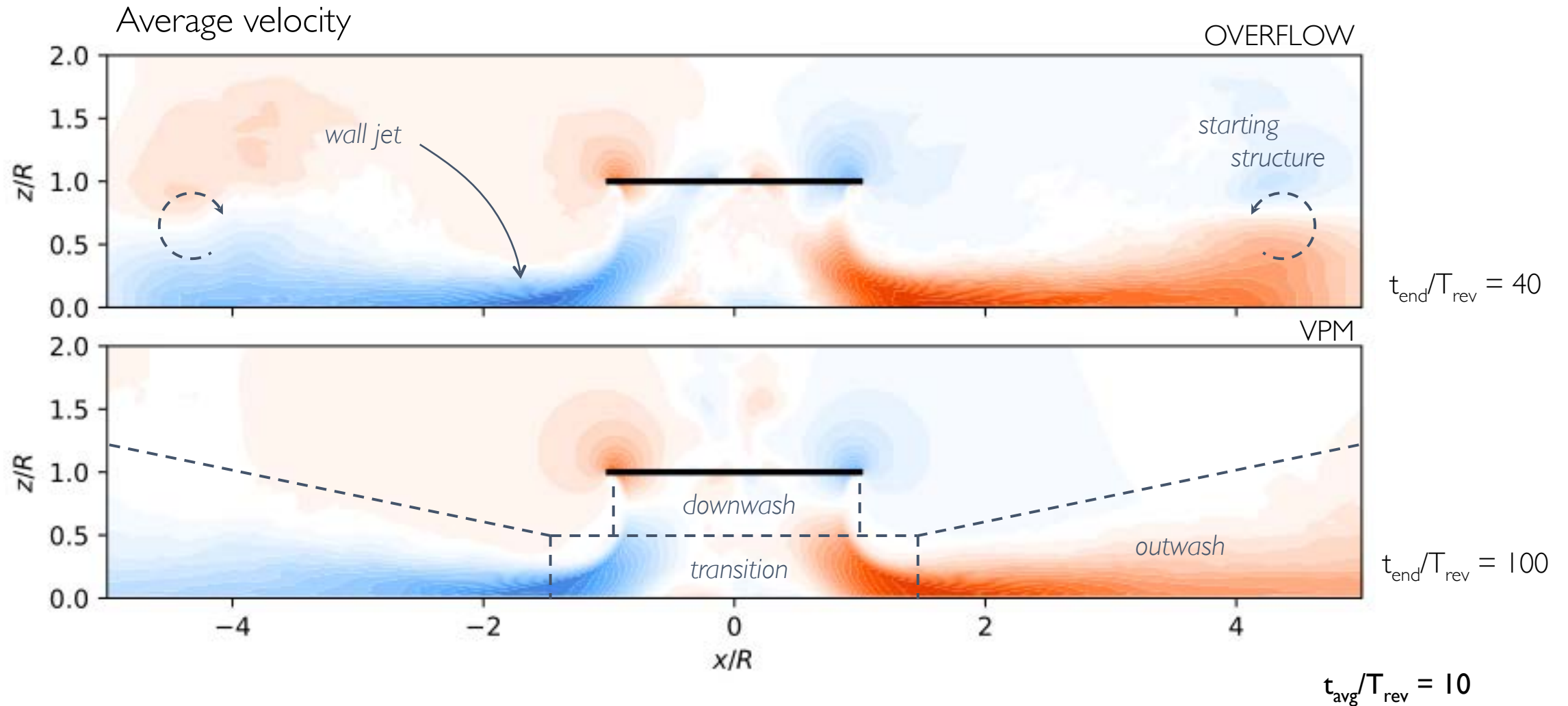
Operating conditions

- hover
- $Re = 1.7M$
- $M_{tip} = 0.48$
- CT_{OGE} intermediate

[7] S.Yoon, N. M. Chaderjian, T. H. Pulliam, and T. L. Holst, "Effect of Turbulence Modeling on Hovering Rotor Flows," Paper AIAA 2015-2766, 2015.

[8] N. M. Chaderjian, and J. Ahmad, "Navier-Stokes Assessment of Test Facility Effects on Hover Performance," 71st Annual Forum of the AHS, May 2015.

Rotorwash – Single Rotor

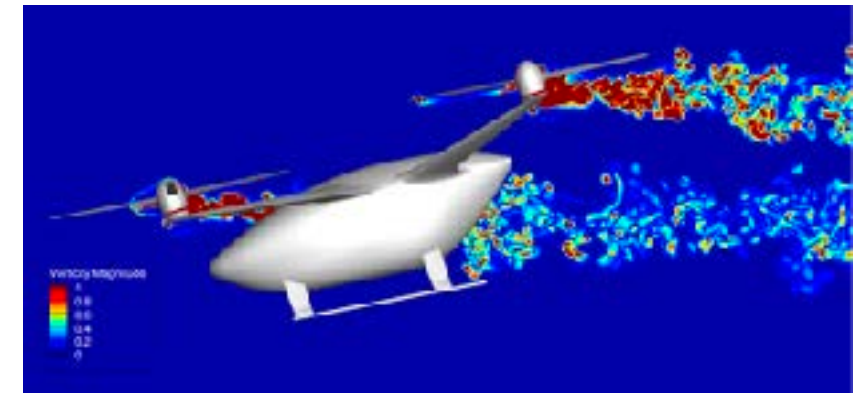
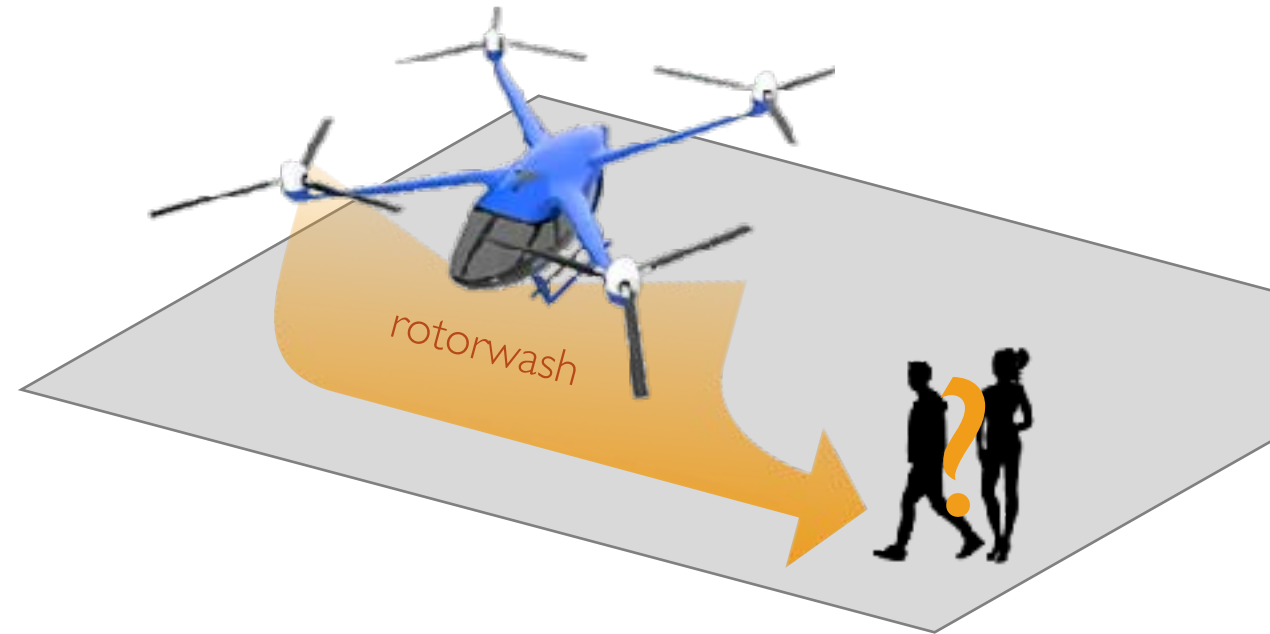
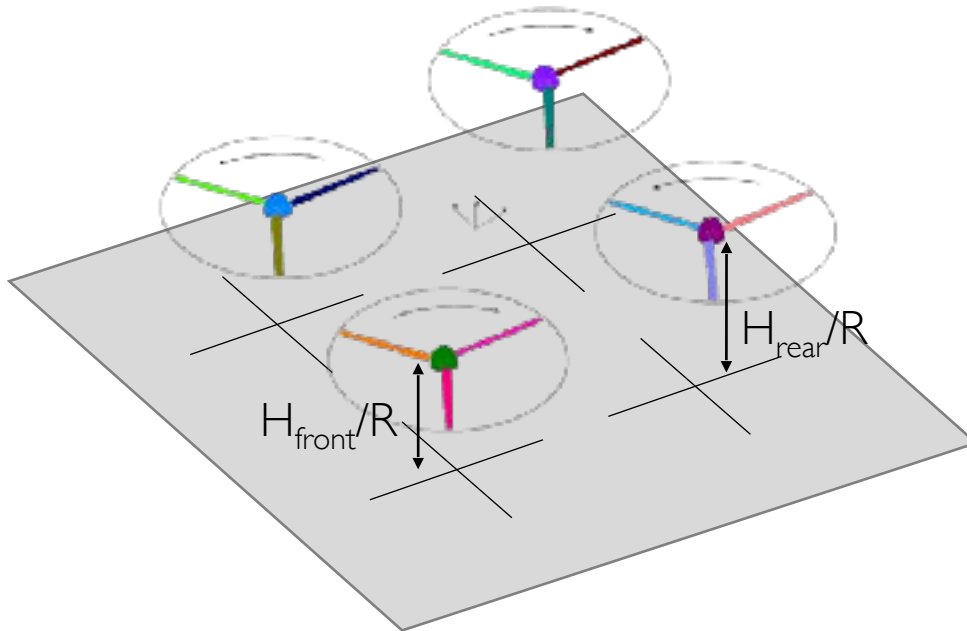


Practical Use Case – Quadcopter Air Taxi



Objectives

- Determine **dangerous areas** in the rotorwash...
 - overturning forces and moments
 - biophysical injury
- ...for **different vehicle designs**



Forward flight simulation from [4]

Flow Visualization – Quadcopter Air Taxi



Operating conditions

- identical to single rotor
- with different rear rotors heights

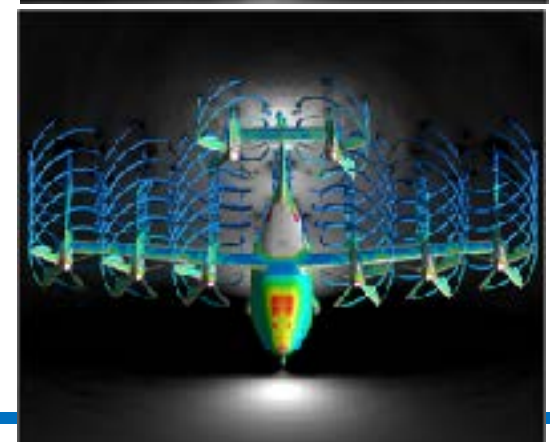
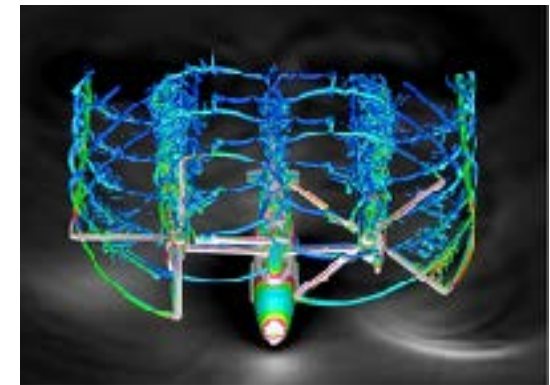
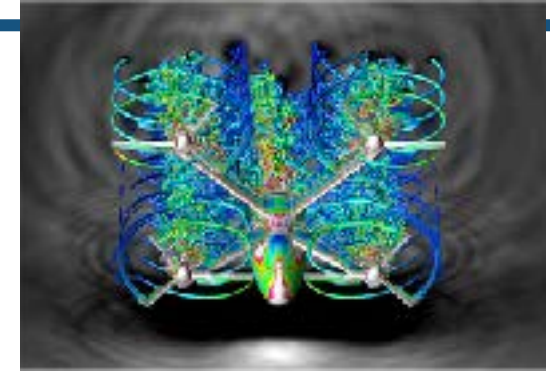
$H_{\text{front}}/R = 1.31$

$H_{\text{rear}}/R = 1.66$

Summary



- Although **blade-resolved simulation** is computationally intensive, it can be used to **verify lower fidelity tools**.
- **Blade-modeled** simulation enables parametric studies with a **reasonable accuracy**.
- High velocity regions are found between the rotors of a **quadcopter air taxi**.
- Further **experimental validation** is needed towards more complex geometries.



Acknowledgements



- Resources supporting this work were provided by the **NASA High-End Computing (HEC)** Program through the NASA Advanced Supercomputing (NAS) Division at Ames Research Center.
- D.-G. Caprace is supported by an appointment to the NASA Postdoctoral Program at NASA Ames Research Center, administered by **Oak Ridge Associated Universities** under contract with NASA.
- The authors express their deep gratitude to Profs. Philippe Chatelain and Grégoire Winckelmans (**UCLouvain**, Belgium) for providing access to the source code of VPM4x.