

# THE INCOMPRESSIBLE NAVIER STOKES FLOW IN TWO DIMENSIONS WITH PRESCRIBED VORTICITY

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*To Dick Wheeden in friendship and appreciation*

ABSTRACT. We study the incompressible two dimensional Navier–Stokes equation with initial vorticity in the homogeneous Sobolev space  $\dot{W}^{1,1}(\mathbb{R}^2)$ . This complements our earlier work for the case when the initial vorticity is in the inhomogeneous Sobolev space  $W^{1,1}(\mathbb{R}^2)$ .

The two-dimensional incompressible Navier–Stokes equation

$$(1) \quad \begin{cases} \mathbf{v}_t + (\mathbf{v} \cdot \nabla) \mathbf{v} = \nu \Delta \mathbf{v} - \nabla p, \\ \nabla \cdot \mathbf{v} = 0, \end{cases}$$

models an incompressible flow a fluid whose velocity and mechanical pressure at position  $x \in \mathbb{R}^2$  and time  $t \in \mathbb{R}$  is represented by the vector  $\mathbf{v}(x, t) \in \mathbb{R}^2$  and with a kinematic viscosity coefficient  $\nu$ . Note we have divided the Navier–Stokes equation by the constant density of the fluid  $\rho$  and thus  $\nu$  in our equation is the dynamic viscosity coefficient divided by the density, assumed constant. Throughout this paper,  $\nabla$  will refer only to the spatial derivatives (i.e. derivative in the  $x$  variables). We also sometimes use the notation  $\partial_x$  to denote a derivative in the  $x$  variables when we have no need to be specific which space variable we are differentiating in.

The vorticity of the Navier–Stokes flow is a scalar in the two-dimensional case, defined by

$$\omega = \partial_{x_1} v_2 - \partial_{x_2} v_1$$

where we wrote  $\mathbf{v} = (v_1, v_2)$ . It propagates according to the convection-diffusion equation

$$\omega_t - \nu \Delta \omega = -\nabla \cdot (\mathbf{v} \omega),$$

which one obtains from (1) by taking the curl of both sides. Formally the velocity  $\mathbf{v}$  in the Navier–Stokes equation can be expressed in terms of the vorticity through the Biot–Savart relation

$$(2) \quad \mathbf{v} = (-\Delta)^{-1}(\partial_{x_2} \omega, -\partial_{x_1} \omega).$$

This follows formally by differentiating  $\omega = \partial_{x_1} v_2 - \partial_{x_2} v_1$ , and using that  $\nabla \cdot \mathbf{v} = 0$ .

Our theorems concern the solution of the vorticity equation when the initial vorticity  $\omega_0$  is in the homogeneous Sobolev space  $\dot{W}^{1,1}(\mathbb{R}^2)$ . Here  $\dot{W}^{1,1}(\mathbb{R}^2)$  is the completion of  $C_c^\infty(\mathbb{R}^2)$  under the norm  $\|u\|_{\dot{W}^{1,1}(\mathbb{R}^2)} := \|\nabla u\|_{L^1(\mathbb{R}^2)}$ . The theorems are as follows:

**Theorem 1.** *Consider the two-dimensional vorticity equation*

$$(3) \quad \omega_t - \nu \Delta \omega = -\nabla \cdot (\mathbf{v} \omega),$$

where  $\mathbf{v}$  is defined through the Biot–Savart relation (2). Suppose we are given an initial vorticity  $\omega_0 \in \dot{W}^{1,1}(\mathbb{R}^2)$  at time  $t = 0$ . If

$$\|\nabla \omega_0(x)\|_{L^1(\mathbb{R}^2)} \leq A_0,$$

then there exists a unique solution to the integral formulation of this vorticity equation up to time  $t_0 = C\nu/A_0^2$ , such that

$$(4) \quad \sup_{t \leq t_0} \|\nabla \omega(x, t)\|_{L^1(\mathbb{R}^2)} \leq 2A_0.$$

Moreover, the solution  $\omega$  depends continuously on the initial data  $\omega_0$ , in the sense that if  $\omega_0^{(i)}$  converges to  $\omega_0$  in  $\dot{W}^{1,1}(\mathbb{R}^2)$  as  $i \rightarrow \infty$ , then the sequence of solutions  $\omega^{(i)}(x, t)$  to (3) with initial data  $\omega_0^{(i)}$  converges to  $\omega(x, t)$  in  $L^\infty([0, t_0], \dot{W}^{1,1}(\mathbb{R}^2))$  as  $i \rightarrow \infty$ .

**Theorem 2.** Let  $\omega_0 \in \dot{W}^{1,1}(\mathbb{R}^2)$ , and  $\omega$  be the solution to the integral formulation of the vorticity equation (3) given by Theorem 1, with initial vorticity  $\omega_0$ . Define a velocity vector  $\mathbf{v}$  by the Biot–Savart relation (2). Then  $\mathbf{v}$  is a distributional solution to the 2-dimensional incompressible Navier–Stokes (1) up to time  $t_0 := C\nu\|\nabla \omega_0\|_{L^1(\mathbb{R}^2)}^{-2}$ , in the sense that

$$\begin{cases} \int_0^{t_0} \int_{\mathbb{R}^2} [\mathbf{v} \cdot \partial_t \Phi + \nu \mathbf{v} \cdot \Delta \Phi + \mathbf{v} \cdot (\mathbf{v} \cdot \nabla) \Phi] dx dt = - \int_{\mathbb{R}^2} \mathbf{v}(x, 0) \cdot \Phi(x, 0) dx \\ \int_0^{t_0} \int_{\mathbb{R}^2} \mathbf{v} \cdot \nabla \psi dx dt = 0 \end{cases}$$

holds for any  $\psi \in C_c^\infty(\mathbb{R}^2 \times [0, t_0], \mathbb{R})$ , and any  $\Phi \in C_c^\infty(\mathbb{R}^2 \times [0, t_0], \mathbb{R}^2)$  that satisfies  $\nabla \cdot \Phi = 0$  for all  $t \in [0, t_0]$ . We also have

$$(5) \quad \sup_{t \leq t_0} \|\mathbf{v}(x, t)\|_{L^\infty(\mathbb{R}^2)} + \sup_{t \leq t_0} \|\nabla \mathbf{v}(x, t)\|_{L^2(\mathbb{R}^2)} \leq c \|\nabla \omega_0\|_{L^1(\mathbb{R}^2)},$$

and the pressure  $p(x, t) := (-\Delta)^{-1} \nabla \cdot ((\mathbf{v} \cdot \nabla) \mathbf{v})$  satisfies

$$(6) \quad \sup_{t \leq t_0} \|\nabla p(x, t)\|_{L^2(\mathbb{R}^2)} \leq c \|\nabla \omega_0\|_{L^1(\mathbb{R}^2)}^2.$$

Note that in these theorems, we are only assuming that the initial vorticity  $\omega_0$  is in the homogeneous Sobolev space  $\dot{W}^{1,1}(\mathbb{R}^2)$ , contrary to [6] where we assumed the stronger assumption that the initial vorticity is in the inhomogeneous Sobolev space  $W^{1,1}(\mathbb{R}^2) = \dot{W}^{1,1}(\mathbb{R}^2) \cap L^1(\mathbb{R}^2)$ . Giga, Miyakawa, Osada [8] and Kato [9] showed that the vorticity equation is globally well-posed under the hypothesis that the initial vorticity is a measure; see also an alternative approach in Ben-Artzi [1], and a stronger uniqueness result in Brezis [4]. We point out though that the scaling of their results is different from ours: we are assuming that the *gradient* of the initial vorticity is in  $L^1$ . This explains why the solution constructed by Kato satisfies the estimate

$$\|\mathbf{v}(\cdot, t)\|_{L^\infty(\mathbb{R}^2)} + \|\nabla \mathbf{v}(\cdot, t)\|_{L^2(\mathbb{R}^2)} \leq Ct^{-\frac{1}{2}}, \quad t \rightarrow 0$$

(see equation (0.5) of [9]), whereas we can obtain bounds on  $\|\mathbf{v}(\cdot, t)\|_{L^\infty(\mathbb{R}^2)}$  and  $\|\nabla \mathbf{v}(\cdot, t)\|_{L^2(\mathbb{R}^2)}$  that are uniform in  $t$ . Indeed it is known that they could not have done better, without further assumptions on the vorticity: the famous example of the *Lamb–Oseen vortex* for  $\nu = 1$  [10] consists of an initial vorticity  $\omega_0 = \alpha_0 \delta_0$ , a Dirac mass at the origin of  $\mathbb{R}^2$  where  $\alpha_0$  is a constant (called the total circulation of the vortex). The corresponding solution  $\omega$  to the vorticity equation (3) with this initial vorticity, and its corresponding velocity  $\mathbf{v}$ , are given by

$$\omega(x, t) = \frac{\alpha_0}{4\pi t} e^{-\frac{|x|^2}{4t}}, \quad \mathbf{v}(x, t) = \frac{\alpha_0}{2\pi} \frac{(-x_2, x_1)}{|x|^2} \left(1 - e^{-\frac{|x|^2}{4t}}\right).$$

We then have

$$\|\omega(\cdot, t)\|_{W^{1,1}(\mathbb{R}^2)} \sim \|\mathbf{v}(\cdot, t)\|_{L^\infty(\mathbb{R}^2)} \sim \|\nabla \mathbf{v}(\cdot, t)\|_{L^2(\mathbb{R}^2)} \sim ct^{-\frac{1}{2}}, \quad t \rightarrow 0.$$

Hence the assumption that the initial vorticity is a measure cannot yield an estimate like in Theorems 1 or 2.

In order to prove Theorem 1, we rely on a basic proposition that follows from the work of Bourgain and Brezis [2, 3].

**Proposition 3.** *If  $\omega(\cdot, t) \in \dot{W}^{1,1}(\mathbb{R}^2)$  at a time  $t$ , then one can define a vector-valued function  $\mathbf{v}(\cdot, t)$  via the Biot–Savart relation (2) at this time  $t$ , in which case we will have*

$$\|\mathbf{v}(\cdot, t)\|_{L^\infty(\mathbb{R}^2)} + \|\nabla \mathbf{v}(\cdot, t)\|_{L^2(\mathbb{R}^2)} \leq C \|\nabla \omega(\cdot, t)\|_{L^1(\mathbb{R}^2)}$$

at this time  $t$ . Here  $C$  is a constant independent of  $t$  and  $\omega$ .

*Proof of Proposition 3.* For simplicity, let's fix the time  $t$ , and drop the dependence of  $\omega$  and  $\mathbf{v}$  on  $t$  in the notation. Note that  $(-\partial_{x_2}\omega, \partial_{x_1}\omega)$  is a vector field in  $\mathbb{R}^2$  with vanishing divergence. The desired conclusion then follows from (2) and the two-dimensional result of Bourgain and Brezis [3].

Since the proof of the two-dimensional result of Bourgain and Brezis [3] is actually quite simple, we adapt it here in our particular setting, for the convenience of the reader.

The main point here is that if  $\omega \in C_c^\infty(\mathbb{R}^2)$ , then  $\mathbf{v} = (v_1, v_2) := (-\Delta)^{-1}(\partial_{x_2}\omega, -\partial_{x_1}\omega)$  satisfies

$$v_1(x) := \frac{1}{2\pi} \int_{\mathbb{R}^2} \partial_2 \omega(x-y) \log \frac{1}{|y|} dy = \frac{1}{2\pi} \int_{\mathbb{R}^2} \omega(x-y) \frac{-y_2}{|y|^2} dy$$

so

$$|v_1(x)| \leq \frac{1}{2\pi} \int_{\mathbb{R}^2} |\omega(x-y)| \frac{1}{|y|} dy \leq c \|\nabla \omega(x-\cdot)\|_{L^1(\mathbb{R}^2)}$$

the last inequality following from an application of Hardy's inequality (alternatively, one can see that the last inequality holds, by writing  $\frac{1}{|y|}$  as  $\nabla \cdot \frac{y}{|y|}$ , and by integrating by parts). This shows

$$\|v_1\|_{L^\infty(\mathbb{R}^2)} \leq c \|\nabla \omega\|_{L^1(\mathbb{R}^2)}.$$

Similarly one shows  $\|v_2\|_{L^\infty(\mathbb{R}^2)} \leq c \|\nabla \omega\|_{L^1(\mathbb{R}^2)}$ , so

$$\|\mathbf{v}\|_{L^\infty(\mathbb{R}^2)} \leq c \|\nabla \omega\|_{L^1(\mathbb{R}^2)}.$$

Finally,

$$\|\nabla \mathbf{v}\|_{L^2(\mathbb{R}^2)} \leq \|\nabla^2 (-\Delta)^{-1} \omega\|_{L^2(\mathbb{R}^2)} \leq \|\omega\|_{L^2(\mathbb{R}^2)} \leq c \|\nabla \omega\|_{L^1(\mathbb{R}^2)},$$

the last inequality following from the Gagliardo–Nirenberg inequality. The above proves the desired conclusion of the proposition under the extra assumption that  $\omega \in C_c^\infty(\mathbb{R}^2)$ . Since such functions are dense in  $\dot{W}^{1,1}(\mathbb{R}^2)$ , a standard approximation argument shows that these estimates extend to the general case when  $\omega \in \dot{W}^{1,1}(\mathbb{R}^2)$ . Hence the full proposition follows.  $\square$

*Proof of Theorem 1.* In the sequel by a scaling we may assume without loss of generality that the viscosity coefficient  $\nu = 1$ .

Let  $K_t$  be the heat kernel on  $\mathbb{R}^2$ , i.e.

$$K_t(x) = \frac{1}{4\pi t} e^{-\frac{|x|^2}{4t}}.$$

Rewriting (3) as an integral equation for  $\omega$  using Duhamel's theorem, where  $\omega_0$  is the initial vorticity, we have,

$$(7) \quad \omega(x, t) = K_t \star \omega_0(x) + \int_0^t \partial_x K_{t-s} \star [\mathbf{v}\omega(x, s)] ds$$

where  $\mathbf{v}$  is given by (2).

We apply a Banach fixed point argument to the operator  $T$  given by

$$(8) \quad T\omega(x, t) = K_t \star \omega_0(x) + \int_0^t \partial_x K_{t-s} \star [\mathbf{v}\omega(x, s)] ds,$$

where again  $\mathbf{v}$  is given by (2). Let us set

$$E = \left\{ g : \mathbb{R}^2 \times [0, t_0] \rightarrow \mathbb{R} \mid \sup_{0 \leq t \leq t_0} \|\nabla g(x, t)\|_{L^1(\mathbb{R}^2)} \leq A \right\}.$$

We will first show that  $T$  maps  $E$  into itself, for  $t_0$  chosen as in the theorem.

Differentiating (8) in the space variable once, we get

$$(T\omega(x, t))_x = K_t \star (\omega_0)_x + \int_0^t \partial_x K_{t-s} \star (\mathbf{v}_x \omega) ds + \int_0^t \partial_x K_{t-s} \star (\mathbf{v} \omega_x) ds.$$

By Young's convolution inequality, we have

$$\|(T\omega(\cdot, t))_x\|_{L^1(\mathbb{R}^2)} \leq \|(\omega_0)_x\|_{L^1(\mathbb{R}^2)} + C \int_0^t (t-s)^{-1/2} (\|\mathbf{v}_x \omega\|_{L^1(\mathbb{R}^2)} + \|\mathbf{v} \omega_x\|_{L^1(\mathbb{R}^2)}) ds.$$

Now we apply Proposition 3 to each of the terms in the integral on the right hand side. For the first term we have, by Cauchy-Schwarz followed by Gagliardo–Nirenberg, that

$$\|\mathbf{v}_x \omega\|_{L^1(\mathbb{R}^2)} \leq C \|\nabla \mathbf{v}\|_{L^2(\mathbb{R}^2)} \|\omega\|_{L^2(\mathbb{R}^2)} \leq C \|\nabla \mathbf{v}\|_{L^2(\mathbb{R}^2)} \|\omega_x\|_{L^1(\mathbb{R}^2)}.$$

We control  $\|\nabla \mathbf{v}\|_{L^2(\mathbb{R}^2)}$  with Proposition 3: this gives

$$\|\mathbf{v}_x \omega\|_{L^1(\mathbb{R}^2)} \leq C \|\omega_x\|_{L^1(\mathbb{R}^2)}^2.$$

Similarly, by Proposition 3, for the second term, we have

$$\|\mathbf{v} \omega_x\|_{L^1(\mathbb{R}^2)} \leq \|\mathbf{v}\|_{L^\infty(\mathbb{R}^2)} \|\omega_x\|_{L^1(\mathbb{R}^2)} \leq C \|\omega_x\|_{L^1(\mathbb{R}^2)}^2.$$

Altogether, we have,

$$\|(T\omega)_x\|_{L^1(\mathbb{R}^2)} \leq \|\nabla \omega_0\|_{L^1(\mathbb{R}^2)} + C \int_0^t (t-s)^{-1/2} \|\nabla \omega\|_{L^1(\mathbb{R}^2)}^2 ds.$$

Thus if  $\|\nabla \omega_0\|_{L^1(\mathbb{R}^2)} \leq A_0$ , then since  $\omega \in E$ , we have

$$\sup_{0 \leq t \leq t_0} \|\nabla(T\omega)(x, t)\|_{L^1(\mathbb{R}^2)} \leq A_0 + C t_0^{1/2} A^2.$$

By choosing  $A$  so that  $A_0 = A/2$  and  $t_0 = 1/(2CA)^2$ , we see that if  $\omega \in E$ , then

$$\sup_{0 \leq t \leq t_0} \|\nabla_x(T\omega)(x, t)\|_{L^1(\mathbb{R}^2)} \leq A,$$

i.e.  $T\omega \in E$ . It remains to show that  $T$  is a contraction on  $E$ .

For this let  $\omega_1(x, t), \omega_2(x, t) \in E$ . We just need to observe that from Proposition 3, we get

$$\|\mathbf{v}_1 - \mathbf{v}_2\|_\infty + \|\nabla \mathbf{v}_1 - \nabla \mathbf{v}_2\|_2 \leq C \|\nabla(\omega_1 - \omega_2)\|_{L^1(\mathbb{R}^2)}.$$

Thus repeating our earlier computations, we see that

$$\sup_{0 \leq t \leq t_0} \|\nabla(T\omega_1 - T\omega_2)\|_{L^1(\mathbb{R}^2)} \leq Ct_0^{1/2}A \sup_{0 \leq t \leq t_0} \|\nabla(\omega_1 - \omega_2)\|_{L^1(\mathbb{R}^2)}.$$

By the choice of  $t_0$ , it is seen that  $T$  is a contraction. Thus using the Banach fixed point theorem on  $E$ , we obtain our operator  $T$  has a fixed point and so the integral equation (7) has a unique solution in  $E$ . The continuous dependence on initial data can be proved in an identical way, and we will not repeat the details here.  $\square$

*Proof of Theorem 2.* Let  $\omega_0 \in \dot{W}^{1,1}(\mathbb{R}^2)$ , and  $\omega(x, t)$  be the unique solution to (7) given above. Let  $\mathbf{v}(x, t)$  be defined by the Biot–Savart relation (2) as in Proposition 3. If  $\omega_0^{(i)}$  is a sequence of functions in  $C_c^\infty(\mathbb{R}^2)$  converging to  $\omega_0$  in  $\dot{W}^{1,1}(\mathbb{R}^2)$ , then the corresponding solution  $\omega^{(i)}(x, t)$  to the vorticity equation (3) converges to  $\omega(x, t)$  in  $L^\infty([0, t_0], \dot{W}^{1,1}(\mathbb{R}^2))$ . Thus the velocities  $\mathbf{v}^{(i)} := (-\Delta)^{-1}(-\partial_{x_2}\omega^{(i)}, \partial_{x_1}\omega^{(i)})$  converges in  $L^\infty([0, t_0]; L^\infty(\mathbb{R}^2))$  to  $\mathbf{v}$ . But since  $\omega_0^{(i)} \in C_c^\infty(\mathbb{R}^2)$ , which are in particular in the inhomogeneous Sobolev space  $W^{1,1}(\mathbb{R}^2)$ , so we may apply Theorem II of Kato [9] as in [6], and conclude that the  $\mathbf{v}^{(i)}$  defined above solves the Navier–Stokes equation (1), at least in the distributional sense. We can now pass to limit as  $i \rightarrow \infty$ , using the convergence of  $\mathbf{v}^{(i)}$  to  $\mathbf{v}$  in  $L^\infty([0, t_0], L^\infty(\mathbb{R}^2))$  we obtained above, and appealing to the dominated convergence theorem: this shows that  $\mathbf{v}(x, t)$  is also a distributional solution to (1) up to time  $t_0$ , in the sense that

$$\left\{ \begin{array}{l} \int_0^{t_0} \int_{\mathbb{R}^2} [\mathbf{v} \cdot \partial_t \Phi + \mathbf{v} \cdot \Delta \Phi + \mathbf{v} \cdot (\mathbf{v} \cdot \nabla) \Phi] dx dt = - \int_{\mathbb{R}^2} \mathbf{v}(x, 0) \cdot \Phi(x, 0) dx \\ \int_0^{t_0} \int_{\mathbb{R}^2} \mathbf{v} \cdot \nabla \psi dx dt = 0 \end{array} \right.$$

holds for any  $\psi \in C_c^\infty(\mathbb{R}^2 \times [0, t_0], \mathbb{R})$ , and any  $\Phi \in C_c^\infty(\mathbb{R}^2 \times [0, t_0], \mathbb{R}^2)$  that satisfies  $\nabla \cdot \Phi = 0$  for all  $t \in [0, t_0]$ . The estimate (5) then follows from Proposition 3 and (4). Lastly we observe that the estimate (6) follows, from the fact that the pressure  $p(x, t)$  satisfies the equation

$$-\Delta p = \nabla \cdot ((\mathbf{v} \cdot \nabla) \mathbf{v}),$$

which is a consequence of taking the divergence of the Navier–Stokes equation.  $\square$

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