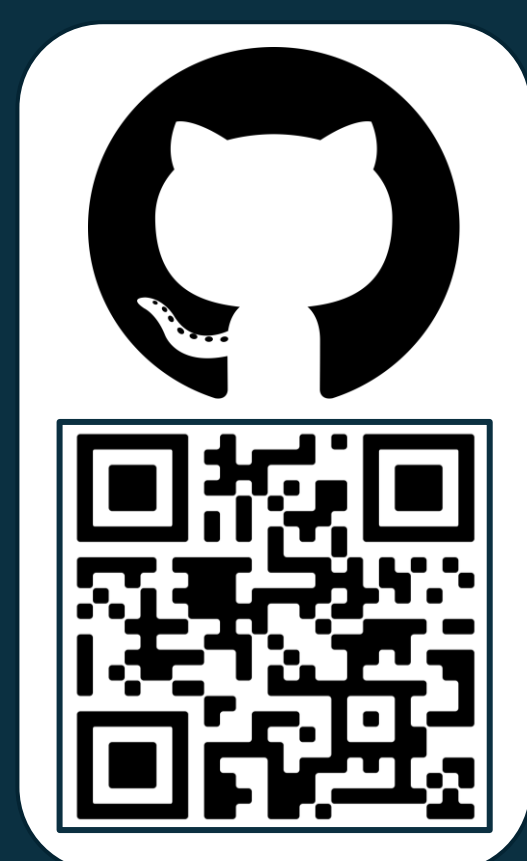


Enhancing Remote Sensing Vision-Language Models for Zero-Shot Scene Classification



Karim El Khoury^{*1}, Maxime Zanella^{*1,2}, Benoît Gérin^{*1}, Tiffanie Godelaine^{*1}
Benoît Macq¹, Saïd Mahmoudi², Christophe De Vleeschouwer¹, Ismail Ben Ayed³

¹UCLouvain, Belgium

²UMons, Belgium

³ETS Montreal, Canada

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*Denotes Equal Contribution

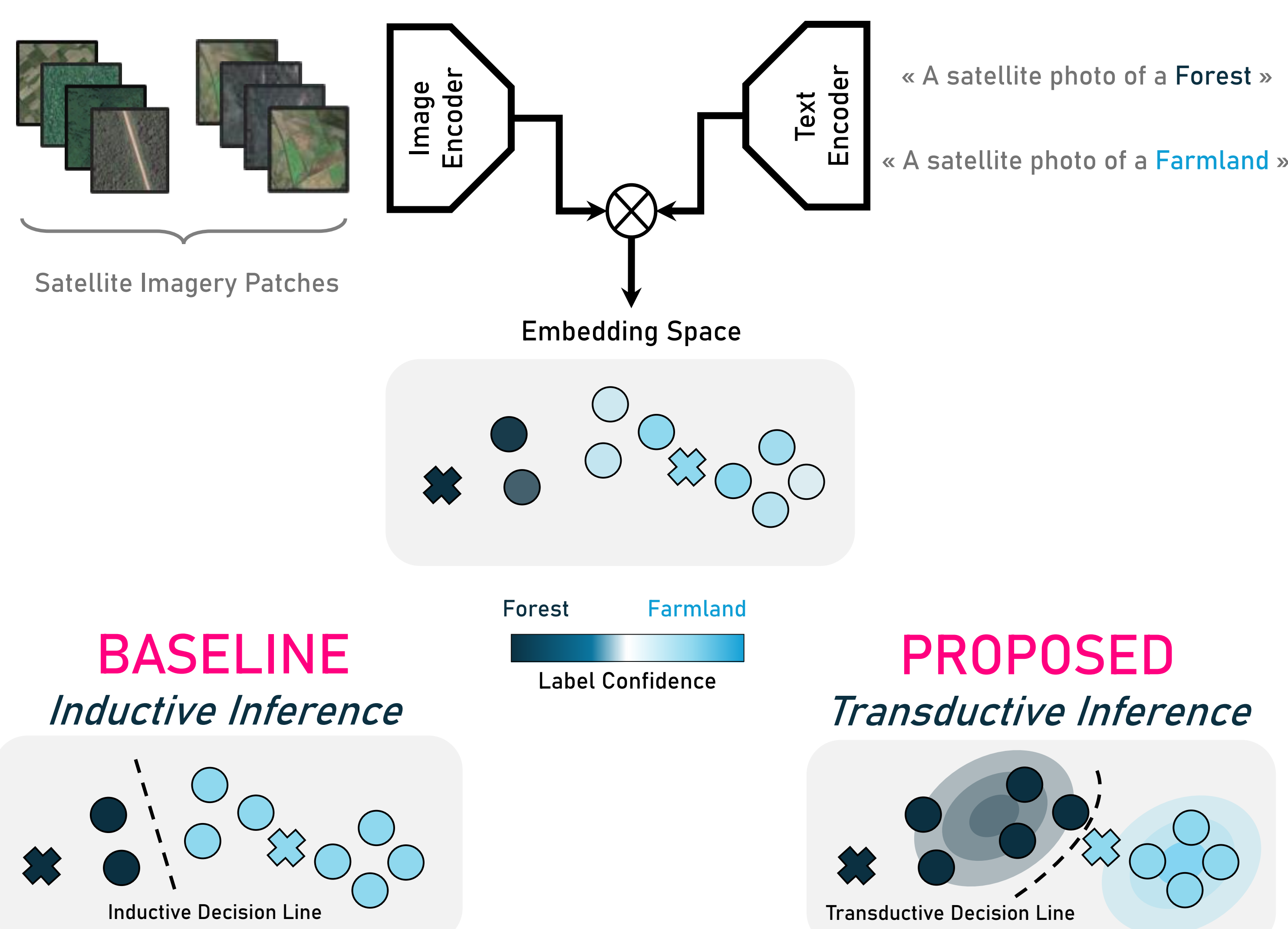
► Paper CONTRIBUTION (TL;DR)

RS-TransCLIP: Unsupervised clustering boosting Remote Sensing Vision-Language Models **by 17%** in only **0.3 seconds**

► CONTEXT

- ◊ RS-VLMs^{1,2,3} rely on **inductive inference** where each patch is **predicted individually**
- ◊ We employ **transductive inference**⁴ to leverage the data structure within the feature space and **predict all patches simultaneously**

► TRANSDUCTIVE VS INDUCTIVE INFERENCE



► RS-TRANSCLIP OBJECTIVE FUNCTION

$$\mathcal{L}(\mathbf{z}, \boldsymbol{\mu}, \boldsymbol{\Sigma}) = \underbrace{-\frac{1}{|\mathcal{Q}|} \sum_{i \in \mathcal{Q}} \mathbf{z}_i^T \log(\mathbf{p}_i)}_{(A)} - \underbrace{\sum_{i \in \mathcal{Q}} \sum_{j \in \mathcal{Q}} \omega_{ij} \mathbf{z}_i^T \mathbf{z}_j}_{(B)} + \underbrace{\sum_{i \in \mathcal{Q}} \text{KL}(\mathbf{z}_i ||) \hat{\mathbf{y}}_i}_{(C)}$$

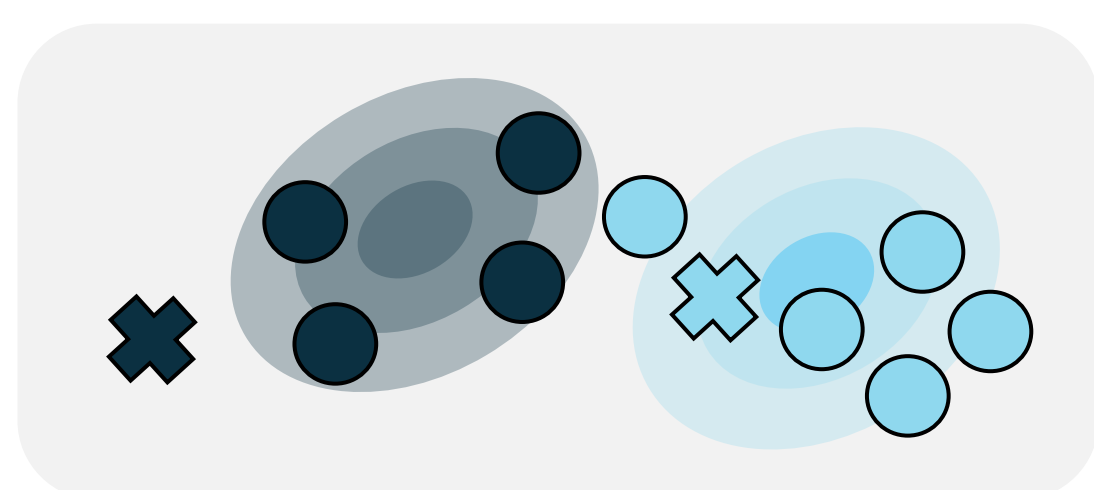
(A) Gaussian Mixture Model Clustering

(B) Laplacian Regularization

(C) Kullback-Leibler Regularization

(A) Gaussian Mixture Model Clustering

→ Model the likelihood of target data as a balanced mixture of Gaussian distributions

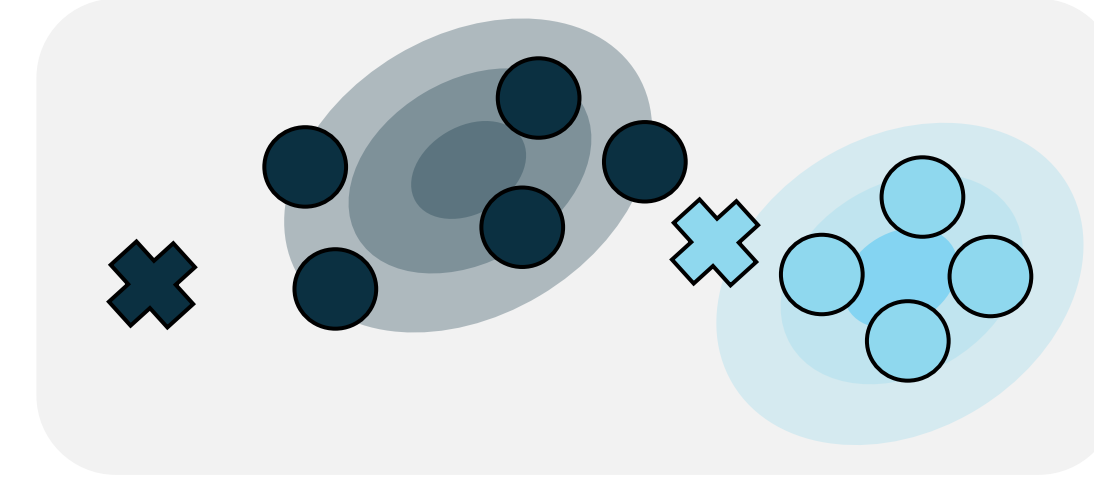


(B) Laplacian Regularization

→ Favor pair of samples with high affinity to have similar assignment variables

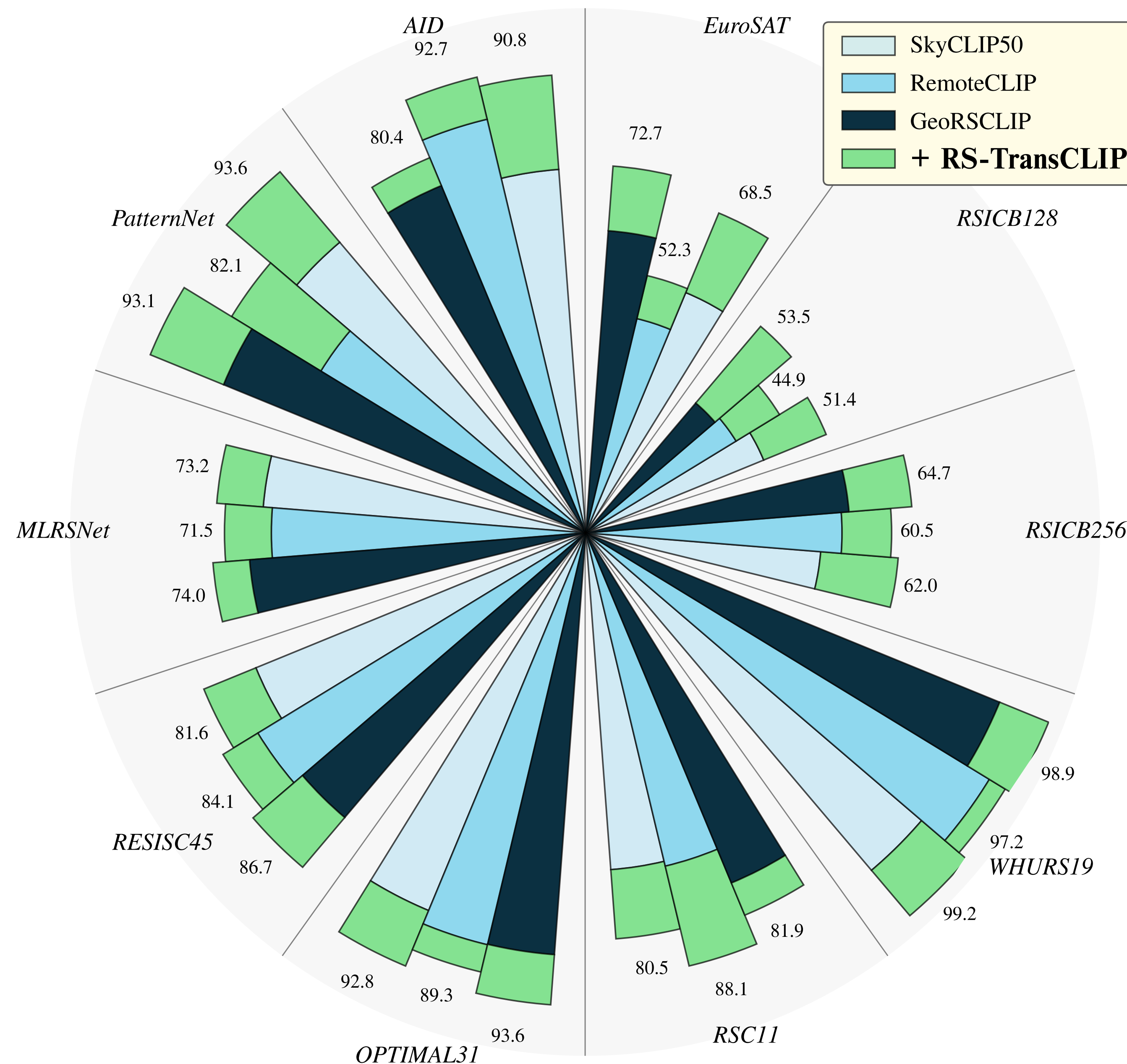
(C) Kullback-Leibler Regularization

→ Prevent assignment variables to deviate significantly from initial pseudo-labels



► RESULTS

→ **RS-TransCLIP boosts zero-shot accuracy** even when inductive performance is high



→ **While maintaining fast inference** thanks to negligible computational cost

RS dataset	Total patches	Features encoding time	+ RS-TransCLIP time
WHURS19	~ 10 ³	~ 8 seconds	~ 0.3 seconds
AID	~ 10 ⁴	~ 40 seconds	~ 2 seconds
MLRSNet	~ 10 ⁵	~ 6 minutes	~ 25 seconds

Model	AID	EuroSAT	MLRSNet	OPTIMAL31	PatternNet	RESISC45	RSC11	RSICB128	RSICB256	WHURS19	Average
CLIP	55.4	28.3	45.0	64.5	46.4	52.8	56.7	23.4	30.4	71.3	47.4
+ RS-TransCLIP	69.6	48.1	54.2	79.6	69.6	69.6	77.8	34.3	46.8	95.9	64.5
GeoRSClip	89.1	26.7	43.0	64.0	43.6	51.6	67.0	15.0	36.4	95.4	53.2
+ RS-TransCLIP	93.3	34.4	58.0	85.0	53.6	72.9	87.2	19.1	48.2	98.4	65.0
CLIP	66.4	45.3	51.2	73.0	59.6	60.7	55.5	27.7	40.3	81.1	56.1
+ RS-TransCLIP	80.7	49.0	64.2	82.9	76.6	74.1	67.0	33.2	46.4	90.3	66.5
GeoRSClip	70.3	53.4	65.0	79.6	75.8	68.8	68.3	29.0	46.5	88.8	64.5
+ RS-TransCLIP	78.2	60.0	71.9	87.3	94.5	79.5	78.6	42.8	61.8	98.7	76.2
CLIP	91.7	35.5	56.3	77.6	55.9	68.1	61.8	26.0	41.5	95.2	61.0
+ RS-TransCLIP	95.6	51.0	65.8	87.8	70.7	79.4	79.7	31.1	49.2	97.9	70.8
CLIP	70.3	52.6	61.2	78.5	73.8	66.7	61.2	29.0	47.1	91.0	64.5
+ RS-TransCLIP	78.7	64.5	73.2	85.2	87.6	77.3	77.1	49.4	59.1	97.8	75.0
CLIP	69.7	60.1	64.1	80.6	74.7	71.3	67.3	37.9	47.2	85.5	65.8
+ RS-TransCLIP	84.2	71.9	74.5	92.4	91.8	82.2	80.5	43.9	60.5	99.1	77.1
GeoRSClip	74.4	59.9	66.7	83.7	77.4	73.8	75.0	33.7	52.2	88.5	68.5
+ RS-TransCLIP	80.4	72.7	74.0	91.6	83.1	86.7	81.9	53.5	64.7	98.9	78.9
CLIP	84.1	43.6	62.2	83.8	61.4	76.0	67.8	34.8	50.7	93.5	65.3
+ RS-TransCLIP	92.7	52.3	71.5	93.3	82.1	84.1	88.1	44.9	60.5	97.2	76.3
CLIP	72.1	51.5	64.0	80.9	75.3	70.5	66.8	38.0	46.6	87.5	65.3
+ RS-TransCLIP	83.8	61.5	73.2	92.8	93.6	81.6	80.5	51.4	62.9	99.2	78.4
GeoRSClip	76.3	68.3	67.4	84.8	82.7	73.8	77.4	43.1	56.5	90.4	72.1
+ RS-TransCLIP	83.8	91.2	78.1	94.5	96.2	88.0	83.3	54.8	72.8	99.7	84.2

► REFERENCES

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- [4] Zanella, Gérin and Ben Ayed, Boosting Vision-Language Models with Transduction, NeurIPS 2024