

Rendering Medical Images using WebAssembly

Sébastien Jodogne¹

¹*Institute of Information and Communication Technologies, Electronics and Applied Mathematics,
Louvain School of Engineering, Louvain-la-Neuve, Belgium*

sebastien.jodogne@uclouvain.be

Keywords: Medical imaging, DICOM, WebAssembly, data visualization, teleradiology

Abstract: The rendering of medical images is a critical step in a variety of medical applications from diagnosis to therapy. Specialties such as radiotherapy and nuclear medicine must display complex images that are the fusion of several layers. Furthermore, the rise of artificial intelligence applied to medical imaging calls for viewers that can be used in research environments and that can be adapted by scientists. However, desktop viewers are often developed using technologies that are totally different from those used for Web viewers, which results in a lack of code reuse and shared expertise between development teams. In this paper, we show how the emerging WebAssembly standard can be used to tackle these issues by sharing the same code base between heavyweight viewers and zero-footprint viewers. Moreover, we propose a full Web viewer developed using WebAssembly that can be used in research projects or in teleradiology applications. The source code of the developed Web viewer is available as free and open-source software.

1 INTRODUCTION

The volume of medical images that are generated worldwide is in constant growth. This can be explained by the fact that the treatment of more and more chronic diseases requires a longitudinal and multimodal exploitation of medical images. For a highly effective, personalized treatment, it is indeed often important to consider images that have been acquired throughout the entire life of the patient and to combine multiple cues produced by different types of imaging modalities.

The DICOM standard (National Electrical Manufacturers Association, 2021) specifies how medical images are encoded and exchanged. Fortunately, DICOM is adopted by any hospital dealing with digital medical images. Thanks to the fact that DICOM is an open standard, a large ecosystem of free and open-source software exists to handle medical images. For instance, when it comes to the need of storing, communicating and archiving DICOM images in full interoperability with the information systems of a hospital, free and open-source DICOM servers such as dcm4chee (Warnock et al., 2007), Dicoogle (Costa et al., 2011) or Orthanc (Jodogne, 2018) can be used.

Obviously, once stored inside a DICOM server, the medical images must still be displayed. Various use cases exist for viewers of medical images: clinical

review integrated within the electronic health records, specialized tools dedicated to one pathology or treatment, external access for the patient, quality control of modalities, second medical opinion, telemedicine, clinical trials. . . Moreover, the huge interest in artificial intelligence applied to medical imaging requires the development of viewers that can be used to annotate regions of interest for the training of the algorithms, and to display the outputs of such algorithms (e.g. segmentation masks) (Cheng et al., 2021).

Depending on the clinical or pre-clinical scenario, one might either need a desktop software, a mobile application or a Web platform to display the medical images. This led many community projects or commercial products to focus only on one of those three categories of platforms, or to have separate development teams working on distinct viewers for the different types of platforms. In the latter case, developing similar features in different languages depending on the target platform (JavaScript, C++, Java. . .) evidently comes at a large cost because of non-shared source code. Furthermore, distinct code bases might suffer from different issues, or conversely might feature optimizations that are not available for the other platforms. Expertise is also less shared between development teams who are focused on different platforms and languages.

Two major open-source software libraries are cur-

rently used within software displaying medical images. The first one is VTK (Schroeder et al., 2006), that is mature and mainly written in the C++ language. VTK is used by many heavyweight desktop viewers, including the 3D Slicer platform (Kikinis et al., 2014), the well-known OsiriX radiology application (Rosset et al., 2004) and its fork Horos. The second library is Cornerstone (Urban et al., 2017), that is more recent and that is written in the JavaScript language so as to be used as a building block for higher-level Web applications. As it takes its roots in modern Web technologies, Cornerstone is at the core of many zero-footprint, lightweight Web viewers, notably OHIF, and is often encountered within cloud-based proprietary solutions. The scope of Cornerstone is mostly focused on the hardware-accelerated rendering of 2D images by Web browsers, whereas VTK is feature-rich, makes active use of GPU for 3D rendering, and can be used for scientific visualization beyond medical imaging.

The emerging WebAssembly standard might be a game changer in this divided landscape. WebAssembly is an open standard that defines a bytecode for Web applications (Haas et al., 2017). The core specification of WebAssembly was released as an official W3C recommendation in December 2019. WebAssembly is actively backed by the industry, and is now supported by the major Web browsers. Thanks to the Emscripten toolchain, C++ source code can be compiled to WebAssembly bytecode, which can then be executed by Web browsers. This opens the path to the creation of C++ libraries that can be used both by native software (using a standard compiler) and by Web platforms (using the Emscripten toolchain). Such C++ libraries could also be used by mobile applications using Android NDK or an Objective-C wrapper. WebAssembly has thus a huge potential to improve code reuse in multi-platform developments, in particular in the field of medical imaging.

In this paper, we firstly propose a novel, free and open-source C++ library named “Stone of Orthanc”, whose internal architecture was driven by the constraints of Web development while providing compatibility with native compiler toolchains. The footprint of Stone of Orthanc is as small as possible, and is designed to be as portable and versatile as possible¹. Historically, the Stone of Orthanc project started in 2016 by leveraging the Google’s PNaCl and Mozilla’s asm.js technologies that are now superseded by We-

bAssembly. Secondly, different applications for medical imaging that were built using the Stone of Orthanc library are presented. In particular, the “Stone Web viewer” is introduced as a fully functional Web viewer for medical images that is integrated as a plugin within the Orthanc DICOM server and that can be used by end users.

2 STONE OF ORTHANC

As explained in the Introduction, Stone of Orthanc is a C++ library to render medical images, with the goal of being compatible with WebAssembly. This objective puts strong constraints on the architecture of the library. Indeed, traditional C++ applications are multi-threaded and sequential, whereas Web applications are single-threaded and driven by asynchronous callbacks (closures).

Besides this constrained architecture, the accurate rendering of medical images requires a careful mapping between pixel coordinates and 2D or 3D physical coordinates. The library must also be extensible so as to display the various kinds of overlays (such as segmentation masks or annotations) that might have been produced by artificial intelligence algorithms or manually added by physicians. Furthermore, medical specialties such as nuclear medicine, radiotherapy or protontherapy necessitate to display fusions of different layers (for instance, a dose over a CT-scan, or a contour over a PET signal). To fulfill such needs, the architecture of Stone of Orthanc integrates a portable 2D rendering engine for vectorized graphics with support of overlays.

In the current section, we review how the high-level architecture of Stone of Orthanc has been engineered. Figure 1 provides a summary of this architecture. Because the goal of this paper is not to document the internal components of Stone of Orthanc, only the main concepts that drove the design of Stone of Orthanc are presented. The interested reader is kindly invited to dive into the source code of the project.

2.1 Loaders and Oracle

The Stone of Orthanc library provides developers with many primitives that are necessary to create medical imaging applications. In particular, the library offers facilities to download images from a DICOM server (notably using the DICOMweb standard, but a custom REST API can be used as well). In this way, Stone of Orthanc features C++ classes that contain 2D or 3D medical images, and that are filled by C++ classes that are referred to as “Loaders”. In the

¹This intimacy with the lightweight architecture of the Orthanc project for medical imaging (Jodogne, 2018) explains the name of the Stone of Orthanc library, the latter being a tribute to the *palantír* that resides inside the tower of Orthanc in *The Lord of the Rings* by J. R. R. Tolkien.

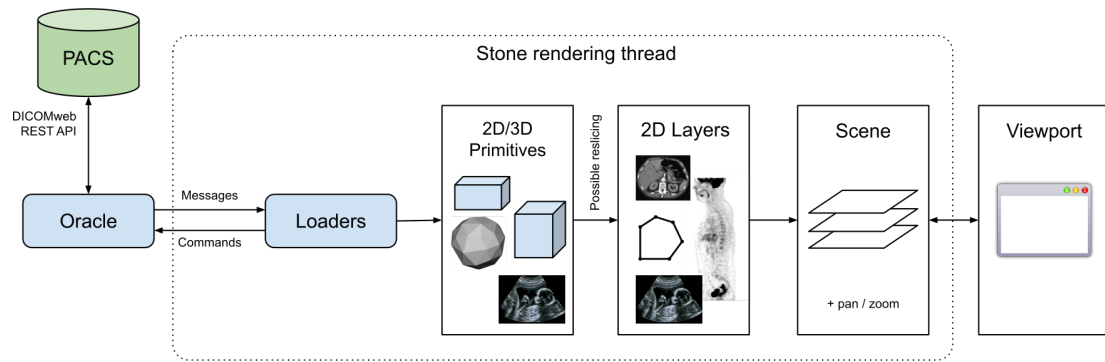


Figure 1: High-level view of the components of the Stone of Orthanc library. The Oracle abstracts the runtime environment. The Loaders are responsible for loading the graphical primitives that have to be displayed. These primitives are converted into a set of 2D Layers (in particular, primitives corresponding to 3D volumes can be sliced along a cutting plane). The Layers are then assembled as a Scene that is finally composed onto the rendering surface of the Viewport. The user can interact with the Viewport to update the affine transform (pan/zoom) that is associated with the Scene.

case of 3D dense volumes, the associated Loaders automatically sort the individual 2D slices of the volume according to their 3D location².

However, as written above, the JavaScript and WebAssembly engines are inherently single-threaded. As a consequence, in order to be compatible with the Web runtimes, the core of the Stone of Orthanc library is not allowed to launch threads or to maintain a pool of threads for the Loaders to download the images, which contrasts with what would be done in a traditional C++ application. The solution adopted by Stone of Orthanc is to introduce a so-called “Oracle” singleton object that abstracts the way asynchronous operations such as downloads are actually processed. In the case of WebAssembly, the Oracle essentially corresponds to a wrapper that abstracts the primitives offered the Web browser itself. In the case of native applications, the Oracle abstracts the system SDK associated with the target platform: For instance, in order to handle downloads, the Oracle internally manages a set of worker threads connected to a shared queue of pending HTTP requests. Besides downloading DICOM instances, other examples of asynchronous operations include reading files from the filesystem, or sleeping for a certain amount of time.

According to this discussion, the Oracle receives a stream of “Command” objects that specify the asynchronous operations that must be carried on. Following the observer design pattern (Gamma et al., 1994), each Command to be processed is associated with an “Observer” object that will receive a “Message” object that contains the result of the Command once it has been processed. For instance, in the case of the

download of a DICOM instance from some REST API, the Command would contain the URL to download, the Observer would correspond to the Loader object that populates the target medical image, and the Message would contain the raw bytes of the DICOM instance. Sending a Command to the Oracle is a non-blocking operation, which reflects the asynchronous nature of the Oracle. The Observer is specified as a C++ “pointer to member function”, with a slight use of C++ templates as syntactic sugar, and the Oracle invokes this member function upon completion of the Command. The Oracle is the key component that enables the writing of source code that can be run indifferently by WebAssembly and by native applications.

The Oracle is part of the global context of the Stone of Orthanc library, and each class that must execute asynchronous operations keeps a reference to the Oracle. In order to map the single-threaded aspect of WebAssembly into native environments supporting multi-threading, it is assumed that the global context is only accessed from one distinguished user thread that is responsible for the rendering. A mutex is included in the global context to prevent the Messages emitted by the Oracle from interfering with the rendering thread. Reference counting using shared pointers ensures that the Observer objects are not destructed before all the scheduled Commands they are receivers of have been processed³.

It is worth noticing that the Oracle mechanism can be used as an accelerator for certain operations that can be time-intensive. For instance, Stone of Orthanc introduces a Command to download then parse DI-

²The 3D location is determined by the “image position patient” (0020,0032) and “image orientation patient” (0020,0037) DICOM tags if available, or by the “instance number” (0020,0013) DICOM tag.

³The observer design pattern and reference counting are used elsewhere in Stone of Orthanc for sending messages from one object to another, and for broadcasting messages from one object to a set of Observers using a subscription mechanism.

COM instances as a single operation: In the case of a multi-threaded environment, this allows to offload the DICOM parsing to a thread without locking the mutex of Stone of Orthanc, which brings more concurrency in native environments⁴. This also allows to maintain a cache of parsed DICOM files. As another example, a new type of Command could be defined to delegate some expensive computation to the CPU (such as projecting a DICOM RT-STRUCT along the sagittal or coronal planes) or to the GPU (such as generating a maximum intensity projection – MIP – rendering of a 3D volume).

2.2 Viewports and Layers

When it comes to the client-side rendering of medical images, the 2D operations of panning, zooming and changing windowing must be as fast as possible. This calls for taking advantage of the 2D hardware acceleration that is provided by any GPU. To this end, both native applications and WebAssembly applications have access to the OpenGL API, the former through development libraries such as Qt or SDL, the latter through WebGL.

On the other hand, in order to reduce the network bandwidth in the presence of large images (typically 3D volumes), the developers of viewers might want to use streaming: In this scenario, a central server generates a stream of “screenshots” of projections of the volumes it stores in its RAM, and those renderings are then sent to a thin client in charge of their actual display to the user. In the case of streaming, GPU is not necessarily available on the server, as multiple users might be connected to the same server. GPU might also be unavailable if printing an image, if generating a secondary capture image, or if the viewer runs on a low-power or embedded computer (such as the popular Raspberry Pi).

To accommodate with all such situations in a cross-platform and lightweight way, the architecture of Stone of Orthanc is designed to support both hardware acceleration (using OpenGL) and software rendering (using the widespread `cairo` drawing library). Furthermore, in order to maximize portability, the Stone of Orthanc library implements its own OpenGL shaders for the GPU-accelerated drawing of lines, texts and bitmaps.

Internally, each rendering surface (the application widget, the HTML5 canvas or the memory buffer) is associated with a so-called “Viewport” abstract class that is responsible for the rendering of a 2D “Scene”. The Scene is an object that encodes a superposition

of “Layer” objects, each Layer being a 2D vectorized graphics with an alpha layer to allow for transparency. Each Scene and Layer is agnostic of the actual rendering surface. In a nuclear medicine application for instance, a Scene would consist of three superimposed Layers, the foremost being the contours (as encoded in a DICOM RT-STRUCT instance), the second being the PET-scan signal (with a heat colormap having transparency), and the background being the CT-scan slice. The Scene also contains a 2D-to-2D affine transform that maps the coordinates of Layers to the Viewport coordinates. Altering this transform is used to pan and zoom the Scene onto the Viewport.

Depending on the type of its rendering surface, the Viewport will use a different algorithm to render a Scene, following the strategy design pattern. This separation of concerns between Viewports and Scenes, is similar to that between the Oracle and Commands. If a Layer containing a bitmap must be rendered, the Viewport is also responsible for the proper conversion of the pixel values (that typically correspond to floating-point numbers or 16 bit integers) to a bitmap that is suitable for rendering onto the surface (in general, red/green/blue/alpha values in 8 bits per pixel). This conversion must take into account the windowing parameters of the Layers, if any. Note that a single application is allowed to manage multiple Viewports in order to show different Scenes.

According to this discussion, the rendering engine of Stone of Orthanc is inherently oriented toward 2D vectorized graphics. This choice is similar to that of the Cornerstone library, but contrasts with the VTK library, that is more 3D-oriented. The advantage of focusing on 2D rendering is to make the rendering of multi-layer scenes more natural to the developers than if 3D must also be taken into account. Importantly, just like the Oracle/Commands/Observers architecture, this Viewport/Scene/Layers architecture is compatible with both native applications and WebAssembly applications. It is worth noticing that Stone of Orthanc could be used as a rendering engine for vectorized graphics in native, mobile or Web applications out of the field of medical imaging.

Evidently, viewers for medical imaging need to display 3D volumes, not just 2D images. Section 2.1 explained how Loaders are used to download 3D images and store them into RAM. To render 3D volumes, Stone of Orthanc introduces the concept of “VolumeReslicer” that is an abstract class taking as its inputs one 3D image and one cutting 3D plane, and producing as its output a 2D slice. This slice can then be injected as a Layer into the Scene to be rendered. Volume reslicers are currently implemented for multiplanar reconstruction (MPR, cf. Section 3.3)

⁴In the future, similar optimizations could be offered in the WebAssembly environment by leveraging Web workers.

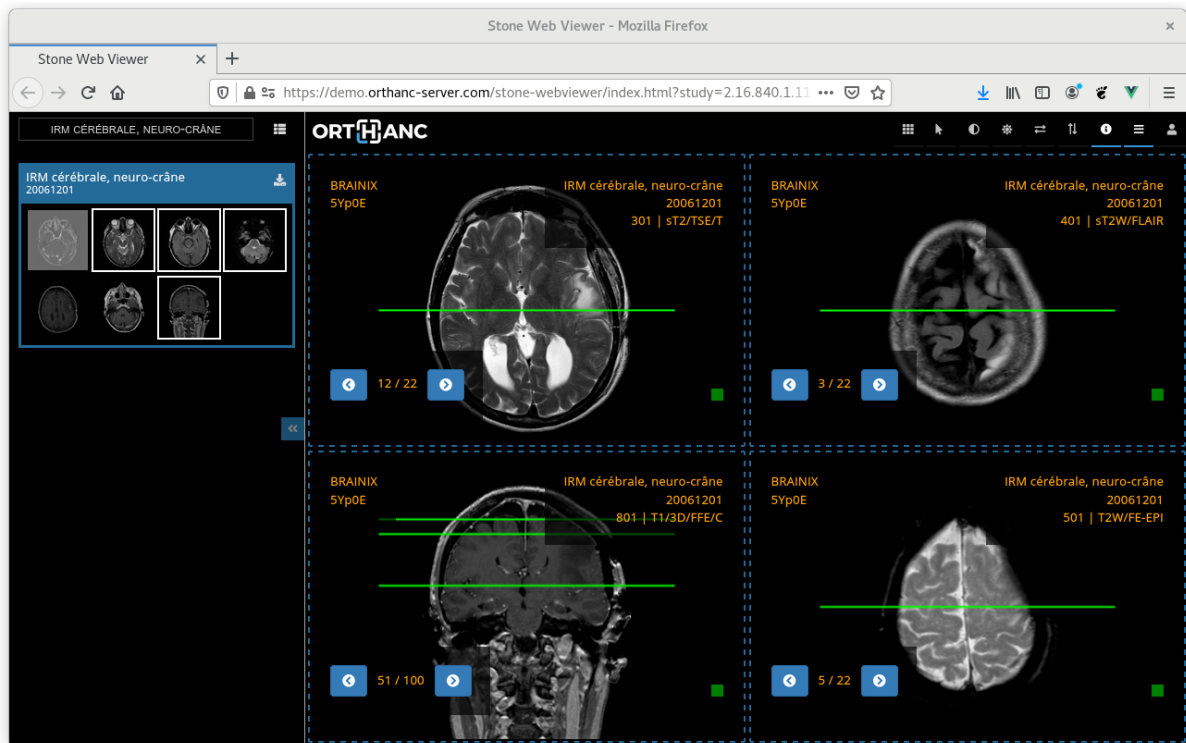


Figure 2: Screenshot of the Stone Web viewer.

and for reslicing along an arbitrary cutting plane (cf. Section 3.4). As discussed above, more reslicers will be implemented in the future for MIP rendering, possibly using the Oracle as an accelerator for the computations.

3 APPLICATIONS

The core features of the Stone of Orthanc library have been explained in the previous sections. In this section, several higher-level applications that were built using Stone of Orthanc are reviewed.

3.1 Simple desktop viewer

The source code of Stone of Orthanc comes with a basic viewer that can be used to display one 2D frame of a DICOM instance downloaded from an Orthanc server. This viewer is a standalone desktop application that is started from the command line by providing the URL of the Orthanc REST API, and the identifier of the DICOM instance to be displayed.

This viewer uses SDL to manage its window, making it eminently cross-platform. A screenshot of this application can be found in Figure 3. Zooming, panning and windowing are supported, as well as taking

measures. The mouse interactions are handled by a dedicated abstract class called “ViewportInteractor” that is responsible for tracking the mouse events, and that is part of the Stone of Orthanc library. Interestingly, because the DICOM image is downloaded from the Orthanc server, it is decoded server-side, which frees the viewer from handling the various transfer syntaxes of the DICOM standard, hereby simplifying the development.

3.2 Stone Web viewer

The so-called “Stone Web viewer” is currently the main application that leverages the Stone of Orthanc library. The Stone Web viewer is a fully functional teleradiology solution, as depicted in Figure 2. It can display multiple DICOM series, and implements features such as measurements, synchronized browsing, 3D cross-hair, and 3D reference lines. The Stone Web viewer communicates with a DICOM server using the DICOMweb protocol, so it is in theory compatible with any PACS environment equipped with DICOMweb. Contrarily to the simple desktop viewer described in Section 3.1, the Stone Web viewer doesn’t rely on the remote server to decode the DICOM files, and embeds the DCMTK library in the WebAssembly bytecode to this end.

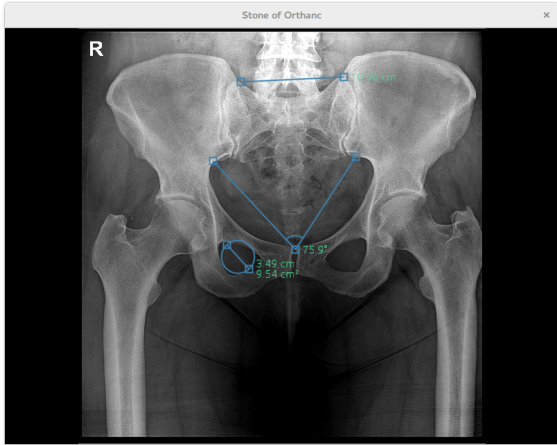


Figure 3: Simple 2D viewer displaying a radiography image. In this case, the Viewport is a SDL window, with one background Layer containing a 16bpp bitmap. The windowing can be changed using the mouse. The viewer can be used to take measures of lines, circles and angles in physical coordinates. These measures are geometric primitives stored in the foreground Layers of the Scene.

Very importantly, to the best of our knowledge, the Stone Web viewer is the first free and open-source viewer of medical images that uses WebAssembly. Most of its source code is written in C++ and compiled using the Emscripten toolchain. The buttons and the HTML5 canvas are managed by a simple Vue.js application that calls the WebAssembly bytecode using an automatically generated JavaScript wrapper.

The Stone Web viewer is a client-side application that is entirely run by the Web browser. Its assets only consist of a set of static resources (HTML files, JavaScript sources and WebAssembly bytecode) that can be served by any HTTP server (such as nginx, Apache or Microsoft IIS). To fulfill the same-origin security policy, it is advised to map the DICOMweb server as a reverse proxy by the HTTP server. The configuration file of the Stone Web viewer has an option to provide the root of the DICOMweb API.

However, this manual configuration of a HTTP server might sound complex to users without a background in network administration. To ease the deployments, a plugin for Orthanc has been developed to directly serve the assets of the Stone Web viewer using the embedded HTTP server of Orthanc. Thanks to this Stone Web viewer plugin and thanks to the DICOMweb plugin for Orthanc, it is extremely easy to start the Stone Web viewer. Furthermore, this plugin is directly available in the Docker images, the Microsoft Windows installers and the macOS packages provided by the Orthanc project⁵.

⁵An online demo of the Stone Web viewer plugin is also available at: <https://demo.orthanc-server.com/>

Figure 4 provides the big picture of the different components that are involved in the Stone Web viewer. The Stone Web viewer is a high-level application that is built on the top of the Stone of Orthanc library. As can be seen, the Stone of Orthanc library reuses some classes from the Orthanc project that are referred to as the “Orthanc Framework”. The Stone Web viewer can either be served from a HTTP server, or be run as a plugin to the main Orthanc server.

3.3 Rendering oncology images

In the context of radiotherapy, patients rarely have the opportunity to view the images of their own treatment plan from home. This is because the Web portals used in hospitals are mostly focused on the radiology workflow, and thus are typically unable to display advanced information such as contours or dose delivery. Yet, viewing one’s own treatment plan might have positive impact on the empowerment of the patient and on the reduction of stress during the treatment.

In collaboration with the radiotherapy department of the University Hospital of Liège, we have contributed to a controlled randomized clinical trial in order to evaluate the impact of a viewer of radiotherapy plans in the context of patient education. The radiotherapy viewer that is used in this trial is a desktop application built using the Qt toolkit and the Stone of Orthanc library. In this clinical trial, the patients receive a USB key containing their own images and the viewer application, after a personal meeting with their oncologist and with a nurse who explains how to use the viewer. This clinical trial is still work in progress.

The user interface of the viewer is depicted in Figure 5 and is designed to be as simple as possible. It displays the fusion of the simulation CT-scan, the planned dose (DICOM RT-DOSE), and the different contours (DICOM RT-STRUCT) following a MPR (multiplanar reconstruction) layout. The user can select which contours are displayed.

Following the terminology of Section 2.2, the user interface of this application is made of three different Scene objects: one for the axial projection, one for the sagittal projection, and one for the coronal projection. In turn, each of these three Scene objects contains three Layer objects: The foremost Layer renders polygons that correspond to the contours, the central Layer renders a colorized version of the slice of the dose (with an alpha channel for transparency), and the backward Layer renders the CT-scan slice. The multimodal fusion is thus solved by blitting the three 2D Layer objects of each Scene onto its drawing surface.

From an algorithmic point of view, the surface rendering of the 3D contours is done by reading the

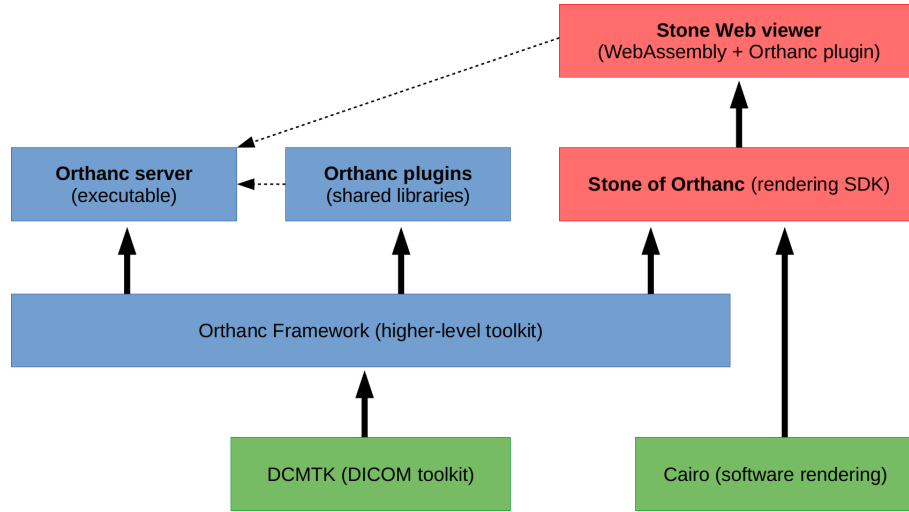


Figure 4: Overview of the high-level architecture of the Stone Web viewer. The green boxes indicate third-party libraries, the blue boxes represent components provided by the Orthanc project, and the red boxes correspond to the Stone of Orthanc project.



Figure 5: Desktop application for patient education in the context of external radiotherapy.

content of one RT-STRUCT instance. In such an instance, the contours of each volume are specified as a list of polygons on the individual axial slices. As a consequence, the rendering of one specific slice in the axial projection simply consists in drawing the polygons that intersect with this plane of interest. The sagittal and coronal projections are more complex to deal with. We first select the polygons that intersect with the given sagittal or coronal slice. Each of those intersections define a 2D box in the plane of interest. The final rendering is done by drawing a set of polygons that corresponds to the union of all those 2D boxes, for which well-known computational geometry algorithms are available (Rivero and Feito, 2000).

On the other hand, the extraction of an axial, sagittal or coronal slice out of the CT-scan volume stored

in RAM whose voxels are indexed by (i, j, k) integers is straightforward: It consists in setting i , j or k to the value of interest, then implementing nested loops over the two other dimensions. The same algorithm can be applied to the RT-STRUCT volume, as long as its axes are aligned with those of the CT-scan volume. Section 3.4 describes a solution if these two volumes are not aligned.

Note that besides radiotherapy, the Stone of Orthanc library can be used to render similar images in the field of nuclear medicine. For instance, Figure 6 illustrates another desktop application that provides an advanced rendering of a PET-CT-scan using a layout that is commonly encountered in professional applications. Evidently, those two applications could be ported to Web environments thanks to WebAssembly.

3.4 Real-time volume reslicing

As explained in Section 2.2, Stone of Orthanc doesn't use the GPU if extracting one slice out of a 3D volume along an arbitrary cutting plane: Volume reslicing is done entirely in RAM. This raises the question of the impact of this technical choice on the performance. To evaluate the performance, a simple WebAssembly application was developed that is depicted in Figure 7. The mouse was used in order to change the orientation of the cutting plane.

From an algorithmic point of view, the cutting plane is specified by one 3D point indicating the origin of the plane, and by two orthonormal 3D vectors indicating the directions of the X and Y axes in the plane. The intersection of the source volumetric im-

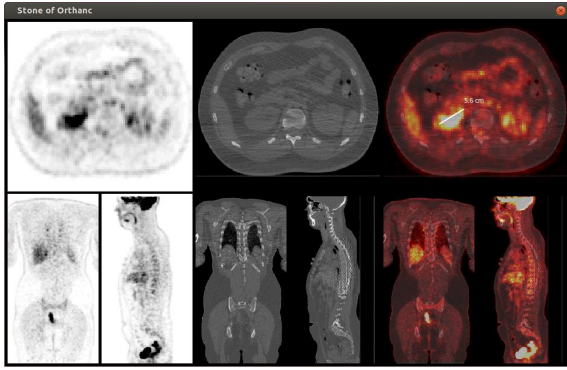


Figure 6: Desktop application for the rendering of PET-CT-scans using a clinical-like layout.

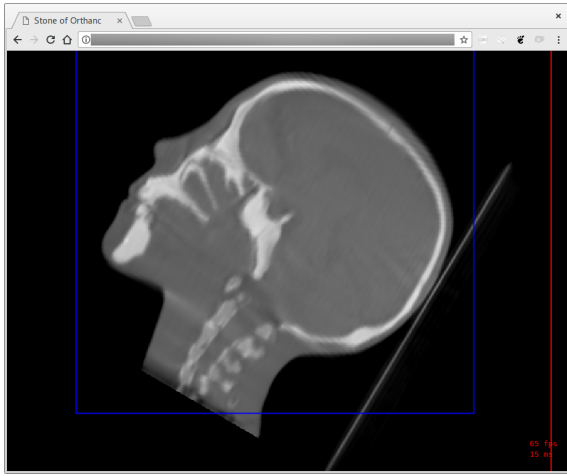


Figure 7: Real-time reslicing of a 3D volume by a Web browser.

age (which is a rectangular cuboid) with the cutting plane is first computed. If non-empty, this intersection defines a polygon with 3 to 6 vertices in the cutting plane. Secondly, the bounding box of this polygon in the reference system of the cutting plane defines the physical extent of the 2D image to be generated. The width and height of the extracted image is derived from the desired pixel spacing. Finally, the extracted image is filled by looping over its pixels, looking for the value of the voxel in the source volume that is the closest to the coordinates of each 2D pixel on the 3D cutting plane. Bilinear or trilinear interpolation can possibly be applied.

On a standard computer (Intel Core i7-3770 at 3.4GHz), the rendering of one slice of size $512 \times 512 \times 502$ voxels in 16bpp takes about 25 milliseconds (40 frames per second), which is fully compatible with real-time requirements. On an old, entry-level smartphone (Samsung Galaxy A3 2017), the same rendering takes about 100 milliseconds (10 frames per second), which is still usable in practice.

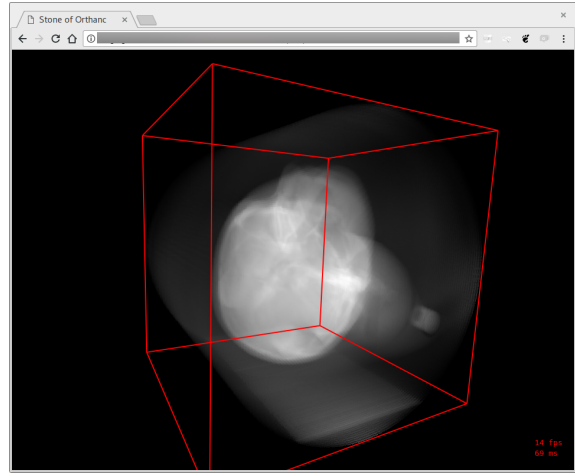


Figure 8: Web rendering of a digitally reconstructed radiograph (DRR) from a CT-scan. The projection is computed client-side by the Web browser in near-real-time (a few frames per second).

3.5 Digitally reconstructed radiographs

The Stone of Orthanc library also features some computational geometry primitives to deal with volume rendering. It notably contains C++ classes in order to generate a digitally reconstructed radiograph (DRR) from a CT volume, which can be useful in the context of radiotherapy. The DRR is the 2D radiograph that would be imaged using a virtual X-ray camera centered at a given 3D point with a given focal length.

DRR can be computed by raytracing each voxel of the CT volume according to the perspective transform, which is a costly computation. Stone of Orthanc optimizes this computation by using the “shear-warp transform” (Lacroute and Levoy, 1994). The intuitive idea behind shear-warp is to postpone as much as possible the application of the perspective transformation, and to apply it only once to a single so-called “*intermediate image*” (this is the “warp” step). This intermediate image is created from the summation of the individual slices of the volume after the application of an affine transform in which the X and Y axes are left uncoupled, which enables a fast computation (this is the “shear” step that is separately applied to each slice). The shear-warp transform provides an efficient algorithm for volume rendering.

Figure 8 shows a WebAssembly application that computes a DRR in near-real-time. On a standard computer, the full rendering of a $512 \times 512 \times 502$ volume in 16bpp takes about 1 second. While moving the virtual camera, the number of slices used for the rendering can be reduced in order to improve speed, thus enhancing the user experience. The GPU could evidently be used to speed up this computation by implementing an appropriate Oracle command. Besides

DRR, the shear-warp algorithm could also be applied for MIP rendering by putting the virtual camera at infinity, and by replacing the summation by a “max” operation.

4 CONCLUSIONS

This paper introduces Stone of Orthanc as a library to render medical images, in a way that is compatible with desktop, mobile and Web applications. Stone of Orthanc is fully written in C++, and leverages the emerging WebAssembly standard if targeting Web applications. Sample applications of Stone of Orthanc are described as well. In particular, the Stone Web viewer is introduced as the first free and open-source teleradiology solution that uses WebAssembly. The source code of the Stone of Orthanc library is publicly released under the LGPL license, whereas the Stone Web viewer is licensed under the AGPL⁶.

As shown in this paper, WebAssembly can be used to maximize code reuse in applications for medical imaging. The same approach could be used in many other scientific fields, where C++ code is traditionally used for numerical computations.

Future work will focus on the exploitation of Stone of Orthanc for artificial intelligence applications in radiology. In particular, we plan to work on the rendering of DICOM SR (structured reports), DICOM SEG (image segmentation) and DICOM GSPS (grayscale softcopy presentation state), as the outputs of AI algorithms. The integration of MPR rendering and whole-slide imaging (Jodogne et al., 2017) directly within the Stone Web viewer will also be investigated. Finally, performance of volume rendering will be improved, for instance by taking advantage of the GPU and Web workers in the Oracle.

ACKNOWLEDGMENTS

The author wishes to thank Benjamin Golinvaux, Alain Mazy and Osimis for their contributions to the development of the Stone of Orthanc project.

REFERENCES

Cheng, P. M., Montagnon, E., Yamashita, R., Pan, I., Cadrin-Chênevert, A., Perdigón Romero, F., Char-

trand, G., Kadoury, S., and Tang, A. (2021). Deep learning: An update for radiologists. *RadioGraphics*, 41(5):1427–1445. PMID: 34469211.

Costa, C., Ferreira, C., Bastião, L., Ribeiro, L., Silva, A., and Oliveira, J. L. (2011). Dicoogle – an open source peer-to-peer PACS. *Journal of Digital Imaging*, 24(5):848–856.

Gamma, E., Helm, R., Johnson, R., and Vlissides, J. M. (1994). *Design Patterns: Elements of Reusable Object-Oriented Software*. Addison-Wesley Professional, 1st edition.

Haas, A., Rossberg, A., Schuff, D. L., Titzer, B. L., Holman, M., Gohman, D., Wagner, L., Zakai, A., and Bastien, J. F. (2017). Bringing the Web up to speed with WebAssembly. In Cohen, A. and Vechev, M. T., editors, *Proceedings of the 38th ACM SIGPLAN Conference on Programming Language Design and Implementation, PLDI 2017, Barcelona, Spain, June 18-23, 2017*, pages 185–200. ACM.

Jodogne, S. (2018). The Orthanc ecosystem for medical imaging. *Journal of Digital Imaging*, 31(3):341–352.

Jodogne, S., Lenaerts, E., Marquet, L., Erpicum, C., Greimers, R., Gillet, P., Hustinx, R., and Delvenne, P. (2017). Open implementation of DICOM for whole-slide microscopic imaging. In *VISIGRAPP (6: VIS-APP)*, pages 81–87.

Kikinis, R., Pieper, S. D., and Vosburgh, K. G. (2014). *3D Slicer: A Platform for Subject-Specific Image Analysis, Visualization, and Clinical Support*, pages 277–289. Springer New York, New York, NY.

Lacroute, P. and Levoy, M. (1994). Fast volume rendering using a shear-warp factorization of the viewing transformation. In *Proceedings of the 21st Annual Conference on Computer Graphics and Interactive Techniques, SIGGRAPH '94*, pages 451–458, New York, NY, USA. ACM.

National Electrical Manufacturers Association (2021). ISO 12052 / NEMA PS3, Digital Imaging and Communications in Medicine (DICOM) standard. <http://www.dicomstandard.org>.

Rivero, M. and Feito, F. (2000). Boolean operations on general planar polygons. *Computers & Graphics*, 24(6):881–896. Calligraphic Interfaces: Towards a new generation of interactive systems.

Rosset, A., Spadola, L., and Ratib, O. (2004). OsiriX: An open-source software for navigating in multidimensional DICOM images. *Journal of Digital Imaging*, 17(3):205–216.

Schroeder, W., Martin, K., and Lorensen, B. (2006). *The Visualization Toolkit: An object-oriented approach to 3D graphics*. Kitware, Inc., 4 edition.

Urban, T., Ziegler, E., Lewis, R., Hafey, C., Sadov, C., Van den Abbeele, A. D., and Harris, G. J. (2017). LesionTracker: Extensible open-source zero-footprint web viewer for cancer imaging research and clinical trials. *Cancer Research*, 77(21):e119–e122.

Warnock, M. J., Toland, C., Evans, D., Wallace, B., and Nagy, P. (2007). Benefits of using the DCM4CHE DICOM archive. *Journal of Digital Imaging*, 20(Supp. 1):125–129.

⁶The source code of the Stone of Orthanc project is available at:

<https://hg.orthanc-server.com/orthanc-stone/>