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MANUSCRIPT

Deep learning for dose assessment in radiotherapy by the super-localization of vaporized nanodroplets in high frame rate ultrasound imaging

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Abstract (299/300 words)

Objective: External beam radiotherapy is aimed to precisely deliver a high radiation dose to malignancies, while optimally sparing surrounding healthy tissues. With the advent of increasingly complex treatment plans, the delivery should preferably be verified by Quality Assurance methods. Recently, online ultrasound imaging of vaporized radiosensitive nanodroplets was proposed as a promising tool for *in vivo* dosimetry in radiotherapy. Previously, the detection of sparse vaporization events was achieved by applying differential ultrasound (US) imaging followed by intensity thresholding using subjective parameter tuning, which is sensitive to image artifacts.

Approach: A generalized deep learning solution (i.e., BubbleNet) is proposed to localize vaporized nanodroplets on differential US frames, while overcoming the aforementioned limitation. A 5-fold cross-validation was performed on a diversely composed 5747-frame training/validation dataset by manual segmentation. BubbleNet was then applied on a test dataset of 1536 differential US frames to evaluate dosimetric features. The intra-observer variability was determined by scoring the Dice Similarity Coefficient (DSC) on 150 frames segmented twice. Additionally, the BubbleNet generalization capability was tested on an external test dataset of 432 frames acquired by a phased array transducer at a much lower ultrasound frequency and reconstructed with unconventional pixel dimensions with respect to the training dataset. **Main Results:** The median DSC in the 5-fold cross validation was equal to ~ 0.88 , which was in line with the intra-observer variability ($=0.86$). Next, BubbleNet was employed to detect vaporizations in differential US frames obtained during the irradiation of phantoms with a 154 MeV proton beam or a 6MV photon beam. BubbleNet improved the bubble-count statistics by $\sim 30\%$ compared to the earlier established intensity-weighted thresholding. The proton range was verified with a ~ 0.8 mm accuracy. **Significance:** BubbleNet is a flexible tool to localize individual vaporized nanodroplets on experimentally acquired US images, which improves the sensitivity compared to former thresholding-weighted methods.

1. Introduction

The utilization of innovative radiotherapy is one of the key elements for treating cancer (Baskar *et al.*, 2012). Several studies concluded that approximately 50% of all cancer patients worldwide could benefit from receiving radiotherapy at least once during their course of treatment (Barton *et al.*, 2014; Atun *et al.*, 2015; Borrás *et al.*, 2015a; Borrás *et al.*, 2015b). External beam radiotherapy is one of the common approaches used to deliver a precise high-dose distribution localized to the tumor volume, while optimally sparing the surrounding anatomical structures sensitive to radiation. Here, sharp tumor dose gradients can be achieved with increasingly complex radiotherapy treatment plans, of which the delivery should preferably be verified in quality assurance (QA) programs. Most clinics already introduced patient specific QA programs to evaluate the accuracy of complex modulated beams with film dosimeters or ionization chambers prior to actual patient treatment (Agazaryan *et al.*, 2003; Bellec *et al.*, 2017; Li and Hsi, 2017). Despite all efforts (Yeung *et al.*, 2005; Bissonnette *et al.*, 2012; Arjomandy *et al.*, 2019), it is still possible that treatment inaccuracies can occur during the irradiation of an individual patient. These inaccuracies can be introduced due to anatomical changes between the series of treatment fractions (Kwint *et al.*, 2014; Sonke *et al.*, 2019; Noble *et al.*, 2019), patient related motion or misalignments (Brandner *et al.*, 2017), dose calculation errors caused by uncertainties in the CT calibration (Wohlfahrt and Richter, 2020), or possibly sporadic machine failure. Therefore, *in vivo* dosimetry techniques have been suggested, and developed, to detect delivery

errors in radiotherapy treatments, assessing clinically relevant differences between planned and delivered dose on a patient-by-patient basis (Verhaegen *et al.*, 2020).

In photon therapy, electronic portal imaging (van Elmpt *et al.*, 2008; Mijnheer *et al.*, 2013) is one of the most promising dosimetry techniques to detect major treatment errors, but the method is mainly limited to the conventional linac systems, and not directly suited for robotic radiotherapy devices such as the CyberKnife® device, for instance. In hadron therapy, a series of technical solutions exist, or are under development, such as post-treatment PET-based range verification (Parodi *et al.*, 2007), prompt gamma spectroscopy imaging (Hueso-Gonzalez *et al.*, 2018), or ionoacoustic imaging (Kellnberger *et al.*, 2016). Despite these great advances, proton range verification solutions did not manage to disseminate widely in proton therapy centers beyond a few pioneering centers (Knopf *et al.*, 2011; Richter *et al.*, 2016; Hueso-Gonzalez *et al.*, 2018) due to their technological complexity, their extensive workflow, or their additional technological cost, which is already expensive upfront.

Alternatively, ultrasound (US) imaging of radiosensitive superheated nanodroplets was explored as a promising solution for on- or offline *in vivo* dosimetry purposes in radiotherapy with photons or hadrons (Carlier *et al.*, 2020; Heymans *et al.*, 2021; Toumia *et al.*, 2021; Collado-Lara *et al.*, 2022). These nanodroplets are intended to be injected intravenously, whereafter they diffuse in the patient's vasculature. Considering that the perfluorocarbon liquid core of the nanodroplets is operated at a superheated state (i.e., at a temperature above its boiling point) during irradiation, the entire nanodroplet can be converted into a microbubble US contrast agent if sufficient energy is deposited by the ionizing radiation over a certain length (i.e., the radiation exhibits sufficient LET).

Former studies (Toumia *et al.*, 2021; Carlier *et al.*, 2020; Heymans *et al.*, 2021; Collado-Lara *et al.*, 2022) focused on demonstrating the feasibility of nanodroplet-assisted radiation sensing using rather rudimentary US processing techniques. For example, Collado-Lara *et al.*, 2022 demonstrated that the distribution of vaporization events is closely related to the ion distribution produced by the proton therapy beam. In this study, the vaporized nanodroplets were detected by means of consecutive frame subtraction in the B-mode ultrasound images, which revealed the newly formed microbubbles in each differential frame as sparse bright spots. Each event with an intensity above a given threshold was counted as a vaporization. Importantly, the thresholding algorithms adopted to identify vaporization events suffer from exhaustive parameter tuning, especially for unseen US datasets. Here, new widely applicable methods are essential to localize nanodroplet vaporizations, and to evolve into a more matured technique for dose assessment in radiotherapy. Moreover, recent developments have revealed the capability of deep neural networks to segment and localize vaporized nanodroplets in super-resolution US images (Liu *et al.*, 2020; Park *et al.*, 2020; van Sloun *et al.*, 2021). In this work, the authors propose to extend the use of deep neural networks to detect the vaporizations of the radiosensitive nanodroplets induced by radiotherapeutic beams.

A deep convolutional neural network, named BubbleNet, was developed to localize individual vaporized radiosensitive nanodroplets on differential high-resolution US images. The neural network was trained on a set of manually segmented experimental data. The performance of BubbleNet was evaluated on an extensive and diverse measurement dataset, and the dose monitoring abilities were

demonstrated to measure the proton range and to report a relative measure of the photon dose distribution.

2. Materials and methods

2.1. Nanodroplet and phantom synthesis

A combination of retrospective datasets was used in this study to evaluate the performance of our proposed neural network architecture in a variety of irradiation and ultrasound imaging conditions. Briefly, the nanodroplets used in this retrospective study contain a perfluorobutane liquid core (C_4F_{10} , boiling point -2°C) encapsulated in a polyvinyl alcohol shell (PVA-PFB) and were synthesized following the protocols described elsewhere (Toumia *et al.*, 2021; Heymans *et al.*, 2021; Collado-Lara *et al.*, 2022). Nanodroplets (size range: 200 nm-8 μm) were all homogeneously dispersed and immobilized in an aqueous gel made of 0.1% Carbopol, prepared as described in (Collado-Lara *et al.*, 2022), and pre-heated to the desired temperature (50°C for proton irradiations, and 65°C for photon irradiations).

2.2. Irradiation conditions and imaging setup

The aqueous phantoms (Figure 1) were immersed in a water tank equipped with temperature control and heated to the desired temperature (50°C or 65°C). Phantom irradiations were conducted with (i) a 154 MeV monoenergetic proton pencil beam (Holland PTC, Delft, the Netherlands), using the same procedure as in (Collado-Lara *et al.*, 2022), or (ii) a 6 MV photon beam (TrueBeam®, Varian Medical Systems) at the clinical radiotherapy facility of UZ Leuven (Belgium). The specifications related to the adopted irradiation geometries and the conducted irradiations are summarily described in Subsections 2.2.1 and 2.2.2.

2.2.1. Proton irradiations

The proton beam irradiations were planned to pass through the center of every phantom's cross section, while the 80% distal fall-off was approximately located in the middle of the phantom length (Figure 1a and Figure 1c). Online US imaging was performed using a linear US array operating at 8.9 MHz (ATL L12-5, 38 mm aperture) positioned at the center of the phantom length and connected to an US research system (Verasonics Vantage 256, Kirkland, USA). The phantom was imaged at a frame rate of 1kHz for a duration of 10 seconds, encompassing the irradiation time (5-7 seconds), using a plane wave imaging sequence (one angle of 0° and no compounding). Additionally, an external test dataset was acquired using a lower frequency US array (P4-2v, 19 mm aperture, 2.72 MHz transmit frequency) which transmitted three diverging waves (-18° , 0° , 18°) and imaged the phantom at a lower frame rate of 152 Hz. The US images were beamformed offline by the Verasonics beamformer.

2.2.2. Photon irradiations

The phantoms were irradiated with photon beams from their side with a square field of $10 \times 10 \text{ cm}^2$ at isocenter. The source-to-skin distance was set to 90 cm, and the phantom center was located at 10 cm distance from the beam entrance point. The top left boundary of the radiation field, defined as the position where the radiation dose dropped to 50% of its maximum, was located within the phantom (Figure 1b). The delivered radiation doses ranged from 0.1 to 4.0 Gy, and the dose rates varied between 0.1 and 4.0 Gy/min.

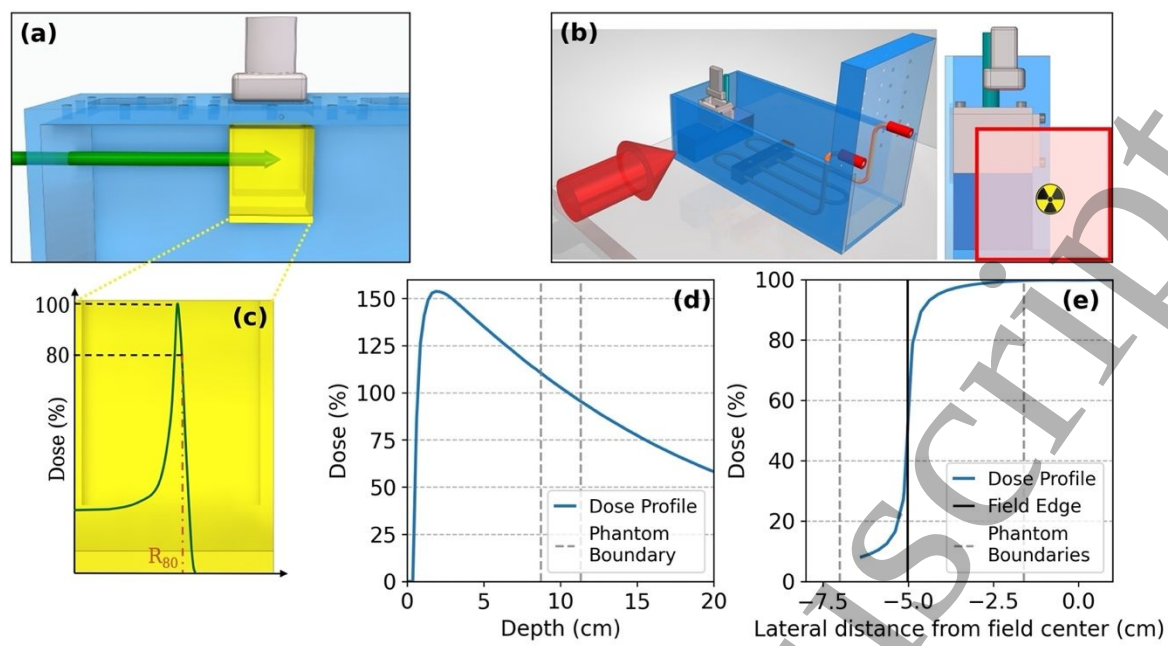


Figure 1. Online ultrasound imaging during irradiation of phantoms with PVA-PFB nanodroplets using a proton beam (green arrow, a) and a photon beam (red arrow, b). During the proton irradiation, the phantom was imaged parallel to the beam direction (c, as range verification), while for the photon irradiation (d), the ultrasound (US) imaging plane is transverse to the radiation beam (e, detection of lateral dose fall-off).

The phantoms were imaged during the photon irradiation by a 7.5 MHz linear array (L7-XTech, Vernon, France) and connected to a research US system (DiPhAs, Fraunhofer IBMT, Germany). The probe was positioned orthogonal to the direction of the radiation beam and was imaging a cross-section of the center of the phantom (Figure 1b). Plane wave imaging was employed (5 angles compounding) at pressures sufficiently low to avoid acoustic nanodroplet vaporization at 65°C. The US images were continuously acquired at a 10Hz frame rate (images were beamformed in real-time by DiPhAs). A detailed table with the irradiation conditions (particle type, dose, dose rate, concentration) and ultrasound imaging conditions (center frequency, frame rate, array type, image size) per phantom setup was added as [Supplementary Material A](#).

2.3. US Image Processing and Neural network training

Sparse vaporization events (i.e., resulting microbubbles) were detected on a frame-by-frame basis by means of differential imaging, which consists in the subtraction of consecutively acquired US frames (Collado-Lara *et al.*, 2022). A post-processing step was added to denoise and smoothen the differential US images with a 2D Wiener filter and a 2D Gaussian filter. All image related filter settings are listed in [Supplementary Material A](#). The differential images were normalized to [0, 1] between the minimum and the maximum image intensity values. A training- and cross-validation dataset of 5747 frames was composed manually from several phantom acquisitions, by segmenting all individual bubbles that appeared in a series of differential US frames. Differential US frames ($n=672$ out of 5747) without the presence of vaporized nanodroplets were also included in the training dataset. These bubbleless frames were acquired prior or after the irradiations. The training- and cross-validation dataset includes a variety of measurement data from 14 different phantoms setups and/or irradiation conditions ([Supplementary Material A](#)). The US pixel dimensions of the training dataset acquired at 7.5-8.9 MHz

varied between 71 μm -86 μm in the US radial dimension, and between 99 μm -250 μm in the US lateral dimension. Additionally, 1536 differential US frames from one phantom irradiation with 154 MeV protons were manually segmented to assess the BubbleNet performance on a never seen test dataset. Moreover, the generalization capability of BubbleNet was evaluated on an external test dataset of 432 manually segmented US frames, which were acquired with a different US frequency than the training dataset (2.7 MHz), and a correspondingly larger pixel size of 283 x 495 μm^2 . Ultimately, the intra-observer variability was evaluated on 150 differential US frames, which were segmented twice by the same annotator within a sufficiently long waiting period of approximately 5 months.

2.4. BubbleNet - Network architecture

A nested U-Net architecture (i.e., U-Net++ L^2) (Zhou *et al.*, 2020) was built using Keras v2.4.2 (Chollet, 2015) to segment the vaporized nanodroplets in the differential US images. The U-Net++ L^2 network architecture, named BubbleNet, consists of an encoder-decoder pathway connected via skip connections and a nested convolutional block (Figure 2). The nested convolutional block bridges the semantic gap between the encoder and decoder feature maps. Every block of the encoder path applies successive 3 x 3 convolutional layers followed by a rectified linear unit (ReLU). Batch normalization operations were initiated to better stabilize the learning process. The spatial resolution in both dimensions is halved every block by applying a 2 x 2 max pooling layer. The number of feature maps after each block doubles along the encoder path from 32 to 128. The decoder path is symmetrical to the encoding path, with the exception that the convolution of each block is replaced by a transposed convolutional layer. Adam was employed as stochastic training optimizer with an initial learning rate of 1E-5 and was parametrized with $\beta_1 = 0.900$, $\beta_2 = 0.999$ (Kingma and Lei, 2015). The binary cross-entropy metric was adopted as probabilistic loss function to train BubbleNet, the fixed batch size was set to 18, and the number of epochs to 100. Data augmentation was applied every epoch in the form of random flipping, scaling [95%-105%] and translational [-3 px, 3 px] operations. Varying US image sizes are handled by the fully connected neural network architecture because the image width and image height are automatically padded to a value that is equal to a multiple of four, considering the two max pooling operations. A 5-fold cross validation according to an 80% train-validation ($n=4697/5747$) and 20% test ($n=1050/5747$) test scheme was employed in the model evaluation procedure to prevent the risk of unanticipated overfitting. All network calculations were performed on a single NVIDIA Volta V100 GPU using the Tier2 high-performance computer of the Flemish supercomputer center.

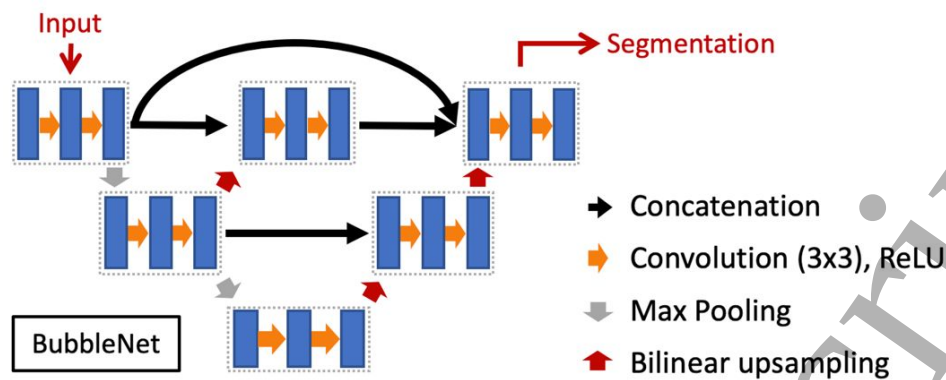


Figure 2. The BubbleNet network architecture (U-Net++) to segment and identify individual vaporized nanodroplets in differential Ultrasound (US) images.

2.5. BubbleNet – Network performance evaluation

The segmentation performance of BubbleNet was mainly evaluated with the Dice Similarity Coefficient (DSC). The DSC is a metric that represents the two-dimensional overlap between two segmentations made on one reference image. More specifically, a DSC value equal to 1 indicates a perfect overlap with identical segmentations, while a DSC value equal to 0 indicates no overlap. Then, the individual bubble coordinates (i.e., centers-of-mass) are determined by two-dimensional weighting of the bubble segmentation mask on top of the intensity values of the differential US image, regardless of the bubble segmentation technique. The bubble coordinates are then conventionally binned to obtain one-or two-dimensional histograms, and subsequently, to assess the radiation dose in one or more of the preferred dimensions.

For the proton irradiations, the one-dimensional histograms were compared to a verified model of the proton Bragg peak (Bortfeld, 1997). In the verification process of this model, the proton depth dose distribution was measured with a multi-layer ionization chamber (QubeNext, DE.TEC.TOR, Turin, Italy) and fitted to an analytical model of the Bragg peak, as explained in (Collado-Lara *et al.*, 2021; Collado-Lara *et al.*, 2022). To evaluate the proton range after bubble localization, Gaussian curves were fitted through the middle of the histogram bins for each of the bubble localization methods. A Gaussian distribution was fitted through the histogram at the end of the projected proton range where most of the primary protons reach their maximal LET value, and hence they can trigger droplet vaporizations (Collado-Lara *et al.*, 2022). The center position of the Gaussian fit is expected to coincide with the mean proton range at which 50% of the protons have stopped (Paganetti, 2012), i.e., the 80% distal dose fall-off (R_{80}). The R_{80} values obtained by BubbleNet, intensity-weighted thresholding, and manual segmentation will be compared with the analytical model, as a reference. For the photon irradiations, a comparison was made between the obtained two-dimensional histograms, and the isodose lines exported from the clinical treatment planning system, assuming a homogeneously distributed aqueous material.

3. Results

3.1. BubbleNet – Model accuracy and performance

The bubble segmentation performance between BubbleNet and a manual annotator is compared qualitatively on randomly picked frames out of our test dataset ($n=1536$) in Figure 3. A cropped US field-of-view is shown for optimal visualization purposes. Figure 3 depicts the bubble predictions on four differential US frames that were acquired at a high-frame rate of 1000 fps (a-d), which indirectly resulted in a low bubble count at the employed dose rates (i.e., 1-3 counts per frame in these examples). The individual DSC values were equal to 0.79, 0.92, 0.90, and 0.86 for the frames presented in Figure 3a-d respectively.

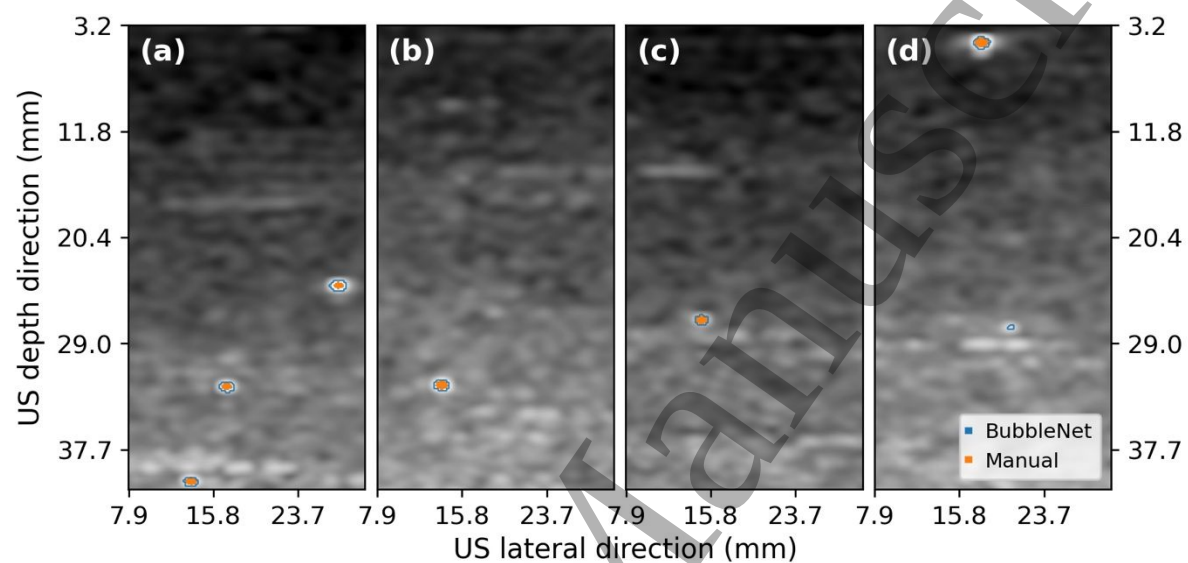


Figure 3. A comparison in the bubble identification performance between BubbleNet and a manual annotator on four (a-d) randomly picked differential Ultrasound frames with a low number of vaporizations per frame. BubbleNet produces a segmentation map, but for visualization purposes, only the outline of the segmentation is displayed.

In Figure 4, the bubble segmentation predictions are shown on four randomly picked differential US frames out of our test dataset ($n=1536$) that were acquired with an irradiation-imaging combination that resulted in substantially higher bubble counts (i.e., 18-40 counts per frame in these examples) than the results presented in Figure 3. The individual DSC values were equal to 0.71, 0.77, 0.73, and 0.79 for the frames presented in Figure 4a-d respectively.

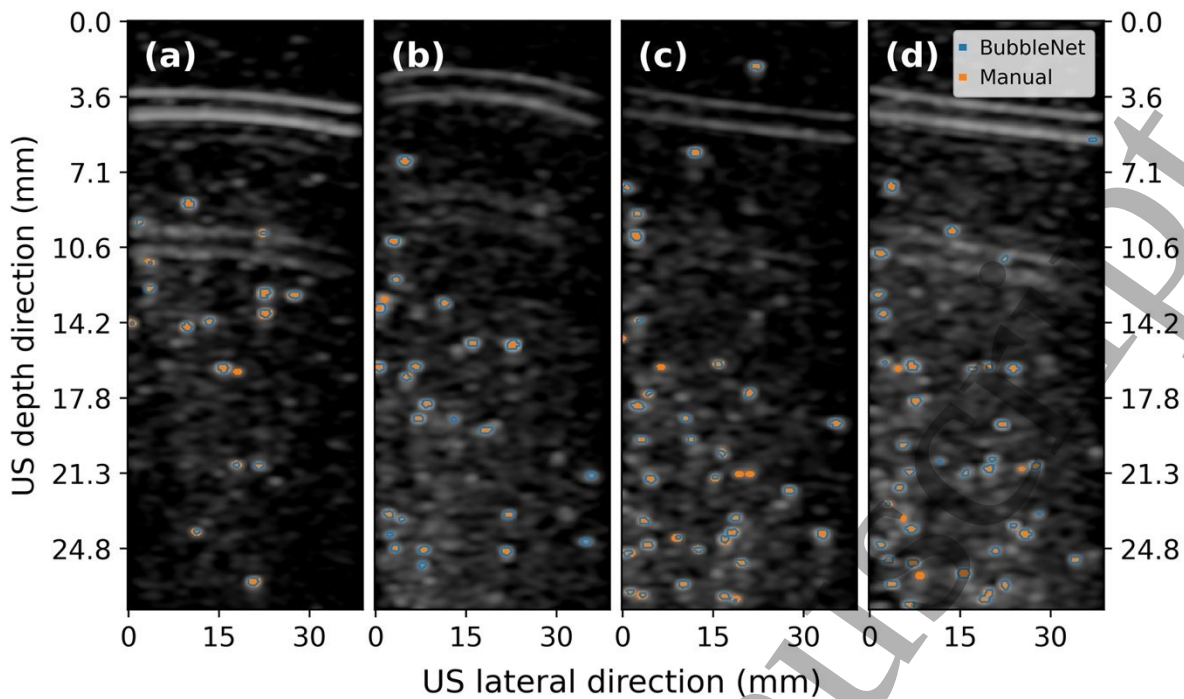


Figure 4. A comparison in the bubble identification performance between BubbleNet and a manual annotator on four (a-d) randomly picked differential Ultrasound frames with a high number of vaporizations per frame.

A largely different external test dataset ($n=432$) in terms of imaging frequency (2.72 MHz instead of 7.5-8.9 MHz), field-of-view (phased array instead of linear array), and pixel size ($283 \times 495 \mu\text{m}^2$ instead of e.g., $71 \times 250 \mu\text{m}^2$, $86 \times 99 \mu\text{m}^2$, etc.) was included in the evaluation procedure of BubbleNet to evaluate the generalization performance of the deep convolutional neural network. An illustration is found in Figure 5, for which the segmentation performance of BubbleNet is qualitatively assessed with respect to a manual annotator. Although these imaging conditions were different with respect to the training dataset, relatively good DSCs were found; 0.79, 0.89, 0.85, and 0.88 for Figure 5a-d respectively.

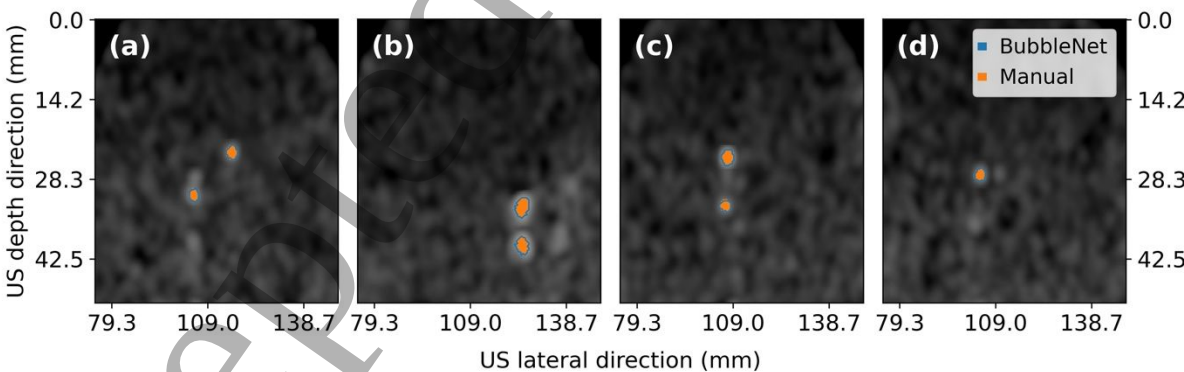


Figure 5. A comparison in segmentation performance on four (a-d) randomly picked differential Ultrasound frames between BubbleNet (blue solid line) and a manual annotator (orange segmentation map) for an unseen dataset with different acoustic imaging settings.

Quantitatively, the boxplots presented in Figure 6a indicate the DSC range of every batch in the 5-fold cross validation ($n=5747$), of which the median DSC is reported inside the box. The frame percentage identified as a statistical outlier was reported at the bottom left of the boxplot panel. An outlier suggests a serious segmentation mismatch between the manual segmentation and the segmentation

1 predicted by BubbleNet. E.g., a false negative or a false positive bubble localization. Here, the outlier
2 percentage ranged between 3.5% and 6.5%. In [Figure 6b-c](#), the average DSC (± 1 SD) learning curves
3 for training ([Figure 6b](#)) and validation ([Figure 6c](#)) are plotted against the number of epochs. For the
4 representation of the five validation learning curves in [Figure 6c](#), a decreased standard deviation and
5 a lower degree of fluctuation is observed near the end of training (i.e., epoch 100), indicating a
6 stabilized neural network for each of the individual batches. The number of manually segmented
7 frames per bubble category is visualized in a horizontal bar chart ([Figure 6d](#)) and represents a total of
8 15050 localized bubbles on 5747 differential US frames. It should be noted that this bar chart does
9 not include the 1536 manually segmented differential US frames to assess the proton range
10 estimation capabilities, and the 432 manually segmented differential US frames to assess the
11 performance on an unseen external dataset with challenging imaging parameters. A bar chart
12 representation on the total number of manually segmented frames (7715 frames, =17989 bubbles)
13 was added as [Supplementary Material B](#). Additionally, in the intra-observer variability comparison,
14 the median DSC (Quartile 1-Quartile 3) was determined to be 0.86 (0.79-0.95) on a duplicate
15 segmentation dataset of 150 differential US frames. In this comparison, the minimum DSC was equal
16 to 0.43 and the maximum DSC was equal to 0.99. Furthermore, the average computing time (± 1 SD)
17 required to train BubbleNet for 100 epochs was 201 ± 47 minutes, and the average BubbleNet
18 prediction time (± 1 SD) was 27.9 ± 0.6 milliseconds per US difference frame.

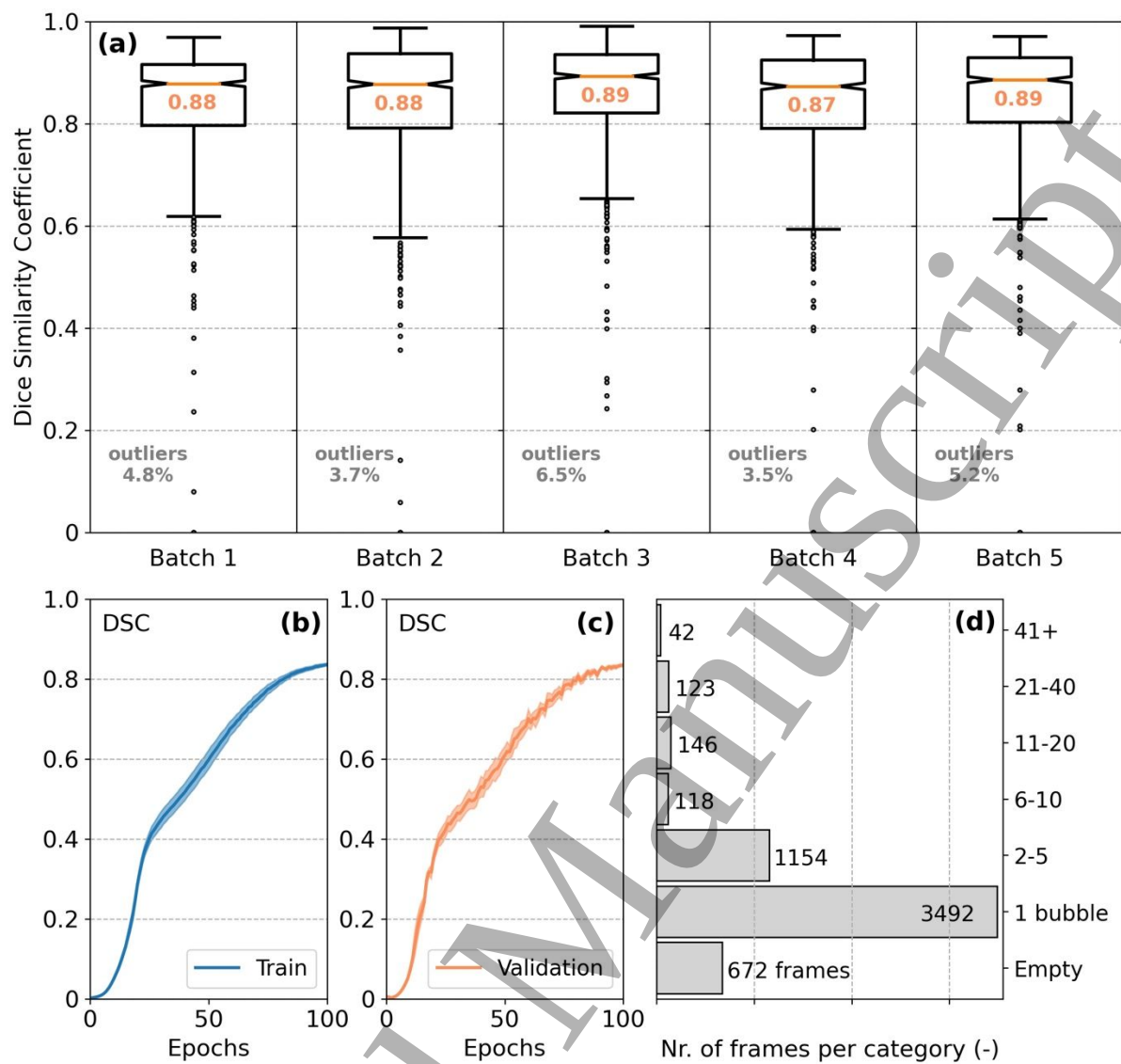


Figure 6. The boxplots in (a) show the Dice Similarity Coefficient (DSC) values from every batch covered by the 5-fold cross validation. The average DSC learning curves of BubbleNet (± 1 SD, standard deviation) are plotted against the number of epochs for training (b) and validation (c) data. The number of manually segmented frames in the training and cross-validation dataset is visualized in a horizontal bar chart per bubble category (d).

3.2. Range verification in proton therapy

The range of a 154 MeV proton beam was measured using three different bubble localization methods with a 0.8 mm bin width (Figure 7): BubbleNet, manual bubble segmentation, and intensity-weighted thresholding (Collado-Lara *et al.*, 2022). The performance for each of these methods was directly compared to a reference dose distribution that was obtained via a verified analytical model of the proton Bragg peak (Bortfeld, 1997) in our experimental conditions. The 95% confidence interval extracted from the analytical Bragg peak model (± 0.23 mm) was superior to the reported interpolated resolution of the QubeNext multi-layer ionization chamber in water of ± 0.50 mm. A similar accuracy offset (Δx) of -0.8 mm was found for all three methods with respect to R_{80} . Nevertheless, better bubble count statistics were observed in the BubbleNet-based proton range ($n=1966$ bubbles) compared to the previously adopted intensity thresholding-based localization

method ($n=1520$ bubbles), while manually, 1841 bubbles were segmented. The range determination method was repeated for two other irradiation setups for which the manual segmentations were lacking, and with a lower original nanodroplet concentration ($20\mu\text{M}$ instead of $31\mu\text{M}$). Here, the BubbleNet accuracy offset compared to the analytical model was -0.8 mm and -0.9 mm , while the accuracy of the intensity-weighted thresholding method was -0.8 mm and -1.0 mm .

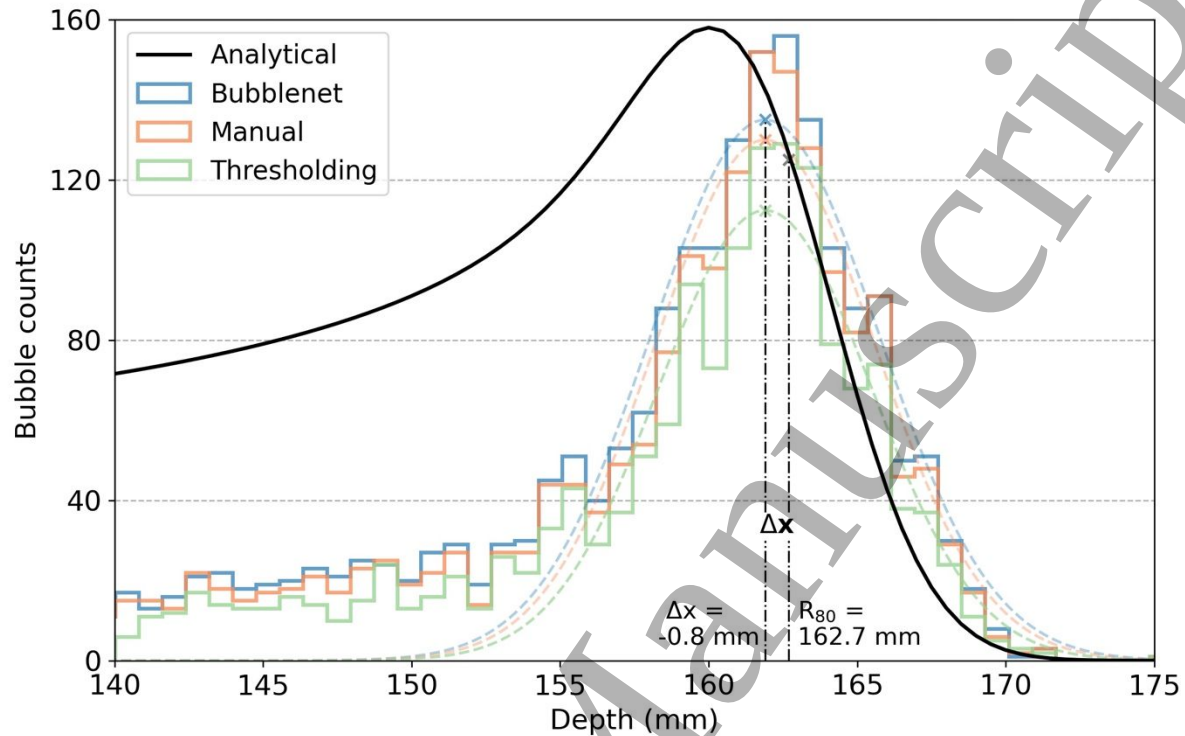


Figure 7. The 154 MeV proton range determination with BubbleNet (blue), a manual segmentation of the individual frames (orange), and by simple dataset-specific bubble intensity thresholding (green).

3.3. Lateral dose profile assessment in photon therapy

The two-dimensional intensity distribution ($0.8 \times 0.8\text{ mm}^2$ bins) of vaporized nanodroplets was evaluated for a 6MV photon irradiation in a Carbolph phantom, whose dimension is indicated by the dashed black box in Figure 8a-b. Identical window levelling parameters are applied in Figure 8a-b after normalization to unity, and in Figure 8c-d, the normalized cumulative red isodose lines in the lateral and depth dimension (extracted from the treatment planning system) serve as reference in the comparison between BubbleNet and the intensity-weighted thresholding method (Figure 8c-d). BubbleNet was able to detect 27% more bubbles ($n=15685$) that were kept unnoticed by the intensity-parameter sensitive thresholding algorithm ($n=12339$). The elevated bubble count gives rise to smoother cumulative dose histograms in both directions, although the biggest advances by BubbleNet are noticeable in the US depth dimension (Figure 8d).

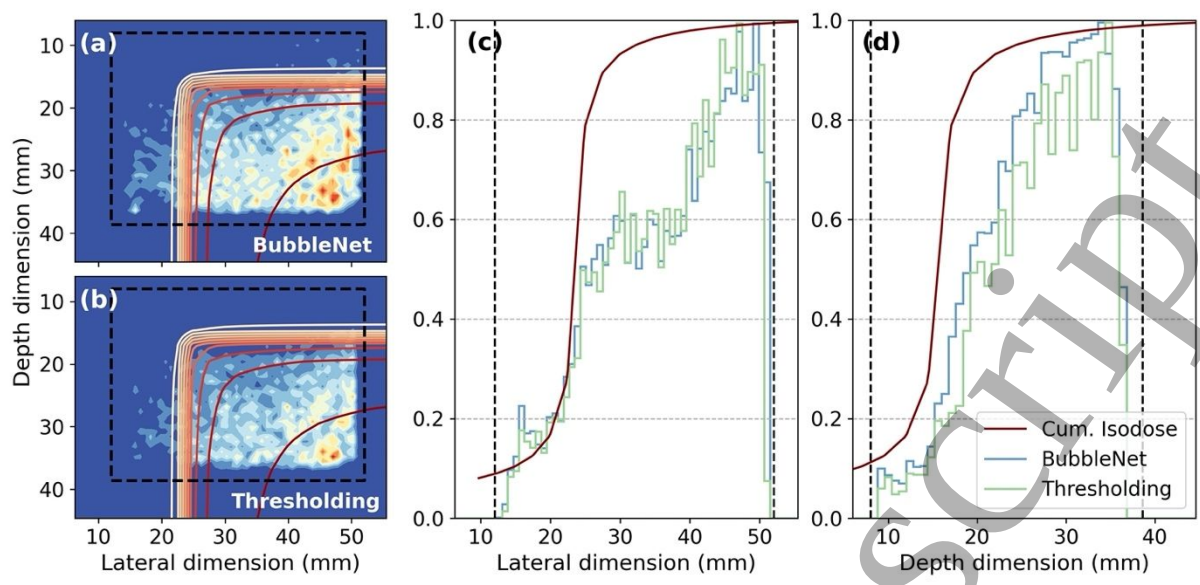


Figure 8. The estimated dose profiles, including the cumulative isodose lines (dark red), after unity normalization by BubbleNet (blue) and by intensity-weighted bubble thresholding (green) in a Carbol phantom that was irradiated with 6MV photons.

4. Discussion

A widely applicable deep convolutional neural network (BubbleNet, Figure 2) was developed to detect vaporized nanodroplets on differential US frames, eliminating the need of time-consuming manual bubble identification methods or subjective dataset-specific intensity-weighted bubble thresholding. A 5-fold cross validation (Figure 6) was completed to determine the model performance in the form of an overlap metric (i.e., DSC). An overall good agreement was found between the segmentation performance of the left-out batches (median DSC = 0.88) which showed a similar performance with a slightly larger degree of deviation, compared to the intra-observer variability measured on 150 differential US frames (median DSC = 0.86). The complete dataset was composed and evaluated on differential US frames with a low- and high number of bubbles per frame. Furthermore, the generalization abilities of BubbleNet were evaluated on an unseen test dataset acquired with a lower frequency ultrasound array and with larger pixel dimensions (283 x 495 μm^2) with respect to the training dataset (71 x 250 μm^2 ; 85 x 250 μm^2 ; 86 x 99 μm^2) (Supplementary Material A).

Next, the segmentation capabilities of BubbleNet were explored to assess the 80% distal dose fall off in a proton treatment beam (Figure 7), and to qualitatively visualize the dose distribution of a 6MV photon beam in our phantom (Figure 8). Like the other evaluated methods, BubbleNet was able to measure the proton range of a 154 MeV beam with a -0.8 mm accuracy. Nevertheless, 29% more bubbles were detected by BubbleNet, compared to the more conventional intensity-weighted thresholding method (Figure 8). BubbleNet's increased detection efficiency was also confirmed for the 7.5 MHz US image dataset acquired of the Carbol phantom (27%), which was irradiated with 6MV photons (Figure 8). An increased bubble count with respect to other available methods is relevant because a raised number of identified vaporizations in the irradiated US imaging volume indirectly leads to a better precision in the localization of the dose distribution. If a lower bubble count was previously sufficient to derive solid and scientific conclusions, BubbleNet could possibly trigger a shift

1 towards the injection of lower nanodroplet concentrations. Moreover, BubbleNet can ignore US
2 image regions subject to high-frequency artifacts (e.g., [Figure 4](#)).

3
4 Additionally, it is relevant to note that the value picked for intensity-weighted thresholding is a very
5 sensitive parameter to be tuned, and moreover alternating with respect to several imaging
6 parameters. A threshold value picked too high fails to detect vaporized nanodroplets (false negative)
7 that show up as a low intensity US signal, and a value picked too low is likely to identify high-frequency
8 image artifacts as a false positive vaporized nanodroplet. To illustrate the sensitivity of the intensity-
9 weighted thresholding method in one dataset (e.g., Phantom 8, [Supplementary Material A](#)); a 5%
10 lower threshold value gave a 55.5% increase in bubble counts, while a 5% higher threshold value gave
11 a 43.6% decrease in bubble counts, which substantially complicates the future standardization of
12 nanodroplet based dose assessment in radiotherapy. Additionally, the US beam is attenuated in the
13 US depth dimension, which directly complicates the manual procedure of optimizing one single
14 thresholding value. It should also be noted that the manual threshold value parameter tuning requires
15 staff time, which would be avoided by BubbleNet.

16
17 Furthermore, it is important to highlight that the conversion from bubble counts to radiation dose is
18 not a simple one-to-one conversion. In proton irradiations, a LET threshold must be exceeded before
19 droplet evaporation could be triggered. At 50°C, the LET threshold was reported to be 60 keV/ μm by
20 ([Carlier et al., 2020](#)). This threshold is thereby typically reached by recoil nuclei, alpha particles, and
21 by the primary protons at the very end of their particle track. To illustrate, in [Figure 7](#), the plateau
22 region in vaporization events before 155 mm depth could typically be originating from rare high-LET
23 nuclear interactions and the generation of high-LET recoil-nuclei, while at the end of the proton range
24 (between 155 mm and 170 mm depth), a vaporization peak is observed because the LET of the primary
25 protons exceeds the vaporization threshold.

26
27 BubbleNet is composed of a U-Net ++ L^2 network architecture to detect microbubbles on differential
28 US-image. Previously, in ([Park et al., 2020](#)), a U-Net based architecture was integrated to detect
29 microbubbles on high-resolution US images to achieve diagnostic imaging of the microvasculature
30 system, and additionally, the vasculature blood flow. ([Liu et al., 2020](#)) employed a multi-layer neural
31 network to localize microbubbles in the vasculature with US microscopy, and ([van Sloun et al., 2021](#))
32 presented a patch-based fully connected convolutional neural network to localize individual
33 microbubbles in vascular architectures without incorporating structural priors. In all referred works,
34 the neural network was trained on synthetic data, and evaluated in variable US imaging conditions
35 and bubble concentrations. Although the training of convolutional neural networks on synthetic data
36 implies an advantageous ground truth of the bubble positioning, it ignores the indirect uncertainties
37 that come with experimental US due to imaging artifacts such as reverberation or speckle. Moreover,
38 recently published research is mainly focused on the super-resolution imaging of the vasculature with
39 US contrast agents, while this work aims to contribute towards the technological development of an
40 *in vivo* dosimeter for radiotherapy with radiosensitive nanodroplets and high frame rate US imaging.

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1 The development of a widely deployable online *in vivo* dosimeter is still a persistent challenge in
2 radiotherapy. Although some promising full-scale prototypes for proton range verification exist such
3 as post-treatment PET imaging or prompt-gamma imaging, these methods regrettably fail to be
4 settled in the conventional hadron therapy workflow due to the extra operational and equipment
5 costs. Alternatively, US imaging of radiation-induced vaporization events of nanodroplets seems a
6 plausible and cheaper dosimetry solution. However, some technological limitations remain to be
7 resolved. One of these limitations was the detection of vaporized nanodroplets on a diversely
8 composed dataset. US imaging combined with super-resolution techniques enable to obtain high-
9 resolution images (e.g., 100 x 100 μm^2), even for deep seated target volumes, and although the active
10 imaging field-of-view will be spatially limited, such resolution is substantially better than the more
11 recent treatment verification solutions such as the reconstructed 3D dose-grid by portal dosimetry
12 (e.g. 3x3 mm³) in photon therapy (van Elmpt *et al.*, 2008), or the post-treatment PET (e.g. 2 mm)
13 (Knopf *et al.*, 2011) or prompt-gamma imaging dosimetry solutions in proton therapy (e.g. 1-3 mm)
14 (Hueso-Gonzalez *et al.*, 2018). This also gives room to speculate that *in vivo* dosimetry with
15 radiosensitive nanodroplets may enter an application field to narrow down the existing measurement
16 uncertainties currently obtained in small-field dosimetry (Palmans *et al.*, 2018; Andreo, 2018). Also,
17 the resolution of dose verification techniques is sensitive to motion, especially over the full duration
18 of a radiotherapy treatment fraction. In motion-sensitive anatomical treatment volumes, 2D
19 deformable image registration could be required to calculate artifact-free differential US images,
20 however, US imaging of the clinical target volume could also indirectly enable the possibility to track
21 the target motion or even underlying soft tissue deformations in real-time. One of the other major
22 advantages of *in vivo* dosimetry with nanodroplets are the ultra-high frame rates that can be achieved
23 in US imaging. For instance, with the growing number of publications indicating the advantage of ultra-
24 high dose rate radiotherapy (FLASH) for sparing healthy tissues (Esplen *et al.*, 2020), the high spatial
25 (<100 μm) and temporal (>1000 fps) resolution of US imaging might be able to monitor the deposited
26 treatment dose, free of detector saturation, with ultra-high dose rates going up to 40 Gy per second.

27 **5. Conclusion**

28 A deep convolutional neural network (BubbleNet) was developed and evaluated in this work to
29 localize vaporized nanodroplets on differential US images for dose assessments in radiotherapy
30 applications. The trained BubbleNet network showed a good segmentation performance (median
31 DSC=0.88) on a collection of differential US images that were acquired with a varying degree of
32 imaging and bubble parameters. Approximately 30% better bubble count statistics were obtained with
33 BubbleNet compared to the conventional intensity-weighted thresholding for nanodroplet
34 localization on differential US images after proton and photon irradiation. Furthermore, BubbleNet
35 would avoid the time-consuming process of adequately tuning the intensity threshold value for each
36 US imaging dataset.

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Conflict of Interest

The authors have no relevant conflict of interest to disclose.

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